# A note on gradient estimates for $p$-Laplacian equations 

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#### Abstract

The aim of this short paper is to show that some assumptions in Guarnotta et al. (Adv Nonlinear Anal 11:741-756, 2022) can be relaxed and even dropped when looking for weak solutions instead of strong ones. This improvement is a consequence of two results concerning gradient terms: an $L^{\infty}$ estimate, which exploits nonlinear potential theory, and a compactness result, based on the classical Riesz-Fréchet-Kolmogorov theorem.


Keywords A priori estimates • Compactness • Convection terms • Strong solutions
Mathematics Subject Classification 35J15 • 35J47 • 35D30 • 35D35

## 1 Introduction

In this brief note, whose starting point is [10], we consider the problem

$$
\left\{\begin{array}{rlr}
-\Delta_{p} u=f(x, u, v, \nabla u, \nabla v) & & \text { in } \mathbb{R}^{N}  \tag{P}\\
-\Delta_{q} v & =g(x, u, v, \nabla u, \nabla v) & \\
\text { in } \mathbb{R}^{N} \\
u, v & >0 & \\
\text { in } \mathbb{R}^{N}
\end{array}\right.
$$

where $N \geq 2,1<p, q<N, \Delta_{r} z:=\operatorname{div}\left(|\nabla z|^{r-2} \nabla z\right)$ denotes the $r$-Laplacian of $z$ for $1<r<+\infty$, while $f, g: \mathbb{R}^{N} \times(0,+\infty)^{2} \times \mathbb{R}^{2 N} \rightarrow(0,+\infty)$ are Carathéodory functions satisfying the following hypotheses.
$\mathrm{H}_{1}(\mathrm{f})$ There exist $\alpha_{1} \in(-1,0], \beta_{1}, \delta_{1} \in[0, q-1), \gamma_{1} \in[0, p-1), m_{1}, \hat{m}_{1}>0$, and a measurable $a_{1}: \mathbb{R}^{N} \rightarrow(0,+\infty)$ such that

$$
m_{1} a_{1}(x) s_{1}^{\alpha_{1}} s_{2}^{\beta_{1}} \leq f\left(x, s_{1}, s_{2}, \mathbf{t}_{1}, \mathbf{t}_{2}\right) \leq \hat{m}_{1} a_{1}(x)\left(s_{1}^{\alpha_{1}} s_{2}^{\beta_{1}}+\left|\mathbf{t}_{1}\right|^{\gamma_{1}}+\left|\mathbf{t}_{2}\right|^{\delta_{1}}\right)
$$

in $\mathbb{R}^{N} \times(0,+\infty)^{2} \times \mathbb{R}^{2 N}$. Moreover, ess $\underset{B_{\rho}}{\inf } a_{1}>0$ for all $\rho>0$.

[^0]$\mathrm{H}_{1}(\mathrm{~g})$ There exist $\beta_{2} \in(-1,0], \alpha_{2}, \gamma_{2} \in[0, p-1), \delta_{2} \in[0, q-1), m_{2}, \hat{m}_{2}>0$, and a measurable $a_{2}: \mathbb{R}^{N} \rightarrow(0,+\infty)$ such that
$$
m_{2} a_{2}(x) s_{1}^{\alpha_{2}} s_{2}^{\beta_{2}} \leq g\left(x, s_{1}, s_{2}, \mathbf{t}_{1}, \mathbf{t}_{2}\right) \leq \hat{m}_{2} a_{2}(x)\left(s_{1}^{\alpha_{2}} s_{2}^{\beta_{2}}+\left|\mathbf{t}_{1}\right|^{\gamma_{2}}+\left|\mathbf{t}_{2}\right|^{\delta_{2}}\right)
$$
in $\mathbb{R}^{N} \times(0,+\infty)^{2} \times \mathbb{R}^{2 N}$. Moreover, $\underset{B_{\rho}}{\text { ess } \inf } a_{2}>0$ for all $\rho>0$.
$\underline{\mathrm{H}_{1}(\mathrm{a})}$ There exist $\zeta_{1}, \zeta_{2} \in(N,+\infty]$ such that $a_{i} \in L^{1}\left(\mathbb{R}^{N}\right) \cap L^{\zeta_{i}}\left(\mathbb{R}^{N}\right), i=1,2$, where
$$
\frac{1}{\zeta_{1}}<1-\frac{p}{p^{*}}-\theta_{1}, \quad \frac{1}{\zeta_{2}}<1-\frac{q}{q^{*}}-\theta_{2}
$$
with
$$
\theta_{1}:=\max \left\{\frac{\beta_{1}}{q^{*}}, \frac{\gamma_{1}}{p}, \frac{\delta_{1}}{q}\right\}<1-\frac{p}{p^{*}}, \quad \theta_{2}:=\max \left\{\frac{\alpha_{2}}{p^{*}}, \frac{\gamma_{2}}{p}, \frac{\delta_{2}}{q}\right\}<1-\frac{q}{q^{*}} .
$$
$\underline{\mathrm{H}_{2}}$ If $\eta_{1}:=\max \left\{\beta_{1}, \delta_{1}\right\}$ and $\eta_{2}:=\max \left\{\alpha_{2}, \gamma_{2}\right\}$ then
$$
\eta_{1} \eta_{2}<\left(p-1-\gamma_{1}\right)\left(q-1-\delta_{2}\right) .
$$

In the sequel, by $\mathrm{H}_{1}$ we mean the set of hypotheses $\mathrm{H}_{1}(\mathrm{f}), \mathrm{H}_{1}(\mathrm{~g})$, and $\mathrm{H}_{1}(\mathrm{a})$.
Unlike [10], we restrict our attention to weak solutions instead of strong ones, which allows us to weaken several conditions. In particular,

- $p, q>2-\frac{1}{N}$ is relaxed to $p, q>1$,
- assumption $\mathrm{H}_{3}$ (cf. [10, p. 743]), ensuring a high local summability of reactions, is dropped, and
- no high local summability for $a_{1}, a_{2}$ is required (cf. $\mathrm{H}_{1}(\mathrm{f})-\mathrm{H}_{1}(\mathrm{~g})$ ).

Let us briefly comment these improvements, focusing our attention on the first equation of (P), since arguments do not exploit any system structure. The lower bound concerning $p$ was used to prove [10, Lemma 2.1] and, jointly with $\mathrm{H}_{3}$, to guarantee the strong convergence of $\left\{\left|\nabla u_{n}\right|^{p-2} \nabla u_{n}\right\}$ in $L_{\text {loc }}^{p^{\prime}}\left(\mathbb{R}^{N}\right.$ ), being $\left\{u_{n}\right\}$ a sequence of solutions (precisely, their first components) to problems that approximate ( P ); see [10, formula (4.5)]. On the other hand, in hypothesis $a_{1} \in L_{\mathrm{loc}}^{s_{p}}\left(\mathbb{R}^{N}\right)$ the number $s_{p}$ was supposed to be greater than $p^{\prime} N$. Thanks to [5, p. 830], this ensures the local $C^{1, \alpha}$-regularity of each $u_{n}$; cf. [10, Lemma 3.1]. However, by [12], the same holds true once $s_{p}>N$, so that we can take $s_{p}:=\zeta_{1}$ with no additional conditions, where $\zeta_{1}$ stems from $\mathrm{H}_{1}(\mathrm{a})$. Moreover, exploiting [12] instead of [5] yields that $\mathrm{H}_{3}^{\prime}$ in [10, Remark 4.4] can be relaxed to

$$
\frac{1}{s_{p}}+\max \left\{\frac{\gamma_{1}}{p}, \frac{\delta_{1}}{q}\right\}<\frac{1}{N}, \quad \frac{1}{s_{q}}+\max \left\{\frac{\gamma_{2}}{p}, \frac{\delta_{2}}{q}\right\}<\frac{1}{N} .
$$

The following example aims to catch the essence of these improvements.
Example 1.1 Let $0<\varepsilon<\frac{1}{N}$ and let $\sigma>N$. Then the functions

$$
\begin{aligned}
& f\left(x, s_{1}, s_{2}, \mathbf{t}_{1}, \mathbf{t}_{2}\right):=|x|^{-\frac{N}{N+2 \sigma}}(1+|x|)^{-N}\left[\left(\frac{s_{2}^{\varepsilon}}{s_{1}}\right)^{\frac{1}{2}}+\left|\mathbf{t}_{1}\right|^{\frac{\varepsilon}{2}}+\left|\mathbf{t}_{2}\right|^{\frac{\varepsilon}{2}}\right], \\
& g\left(x, s_{1}, s_{2}, \mathbf{t}_{1}, \mathbf{t}_{2}\right):=|x|^{-\frac{N}{N+2 \sigma}}(1+|x|)^{-N}\left[\left(\frac{s_{1}^{\varepsilon}}{s_{2}}\right)^{\frac{1}{2}}+\left|\mathbf{t}_{1}\right|^{\frac{\varepsilon}{2}}+\left|\mathbf{t}_{2}\right|^{\frac{\varepsilon}{2}}\right]
\end{aligned}
$$

satisfy hypotheses $\mathrm{H}_{1}-\mathrm{H}_{2}$ with $p=q:=1+2 \varepsilon$. In fact, pick $\beta_{1}=\alpha_{2}=\gamma_{1}=\gamma_{2}=\delta_{1}=$ $\delta_{2}:=\frac{\varepsilon}{2}, m_{1}=\hat{m}_{1}=m_{2}=\hat{m}_{2}:=1$, and $\zeta_{1}=\zeta_{2}:=N+\sigma$. To verify $\mathrm{H}_{1}(\mathrm{a})$, observe at first that

$$
\frac{1+2 \varepsilon}{N}-\frac{\varepsilon / 2}{1+2 \varepsilon}>\frac{1}{N}-\frac{\varepsilon}{2}>\frac{1}{2 N}, \quad\left(\frac{1+2 \varepsilon}{N}-\frac{\varepsilon / 2}{1+2 \varepsilon}\right)^{-1}-N<2 N-N=N
$$

by the choice of $\varepsilon$. So,

$$
\begin{aligned}
& \frac{1}{\zeta_{1}}<1-\frac{p}{p^{*}}-\theta_{1} \Leftrightarrow \frac{1}{N+\sigma}<\frac{1+2 \varepsilon}{N}-\frac{\varepsilon / 2}{1+2 \varepsilon} \\
& \quad \Leftrightarrow \quad \sigma>\left(\frac{1+2 \varepsilon}{N}-\frac{\varepsilon / 2}{1+2 \varepsilon}\right)^{-1}-N
\end{aligned}
$$

which is true because $\sigma>N$. It is worth noticing that $p, q \leq 2-\frac{1}{N}$, namely $1+2 \varepsilon \leq 2-\frac{1}{N}$, whenever $\varepsilon \leq \frac{1}{2 N^{\prime}}$, as well as $\zeta_{1}, \zeta_{2} \leq p^{\prime} N$, i.e. $N+\sigma \leq \frac{1+2 \varepsilon}{2 \varepsilon} N$, when $\varepsilon \leq \frac{N}{2 \sigma}$. A concrete case can be obtained taking $N:=3, \sigma:=4$, and $\varepsilon:=\frac{1}{4}$.

Convergence of gradient terms comes into play whenever a second-order differential problem needs to be approximated: this can occur due to the lack of ellipticity (or uniform ellipticity) of the principal part and/or the presence of non-smooth nonlinearities; see, e.g., [11, Theorem 3.3]. An approximation procedure is necessary also in the context of singular problems, that is, problems whose reaction term blows up when the solution approaches to zero, as $(\mathrm{P})$. The very recent papers $[8,9]$ provide an account on this topic.

Here, we proceed as follows. Lemma 2.1 of [10] is restated in a new, general fashion and its proof is made adapting the one of [10]; vide Lemma 2.4. Next, we establish a compactness result (Lemma 2.5) for gradient terms, which is self-contained (unlike the alternative arguments mentioned in Remark 2.6) and relies on the classical Riesz-Fréchet-Kolmogorov $L^{p}$-compactness criterion. Finally, the proof of [10, Lemma 4.1] is modified to get a weak solution of $(\mathrm{P})$ under assumptions $\mathrm{H}_{1}-\mathrm{H}_{2}$ and the unavailability of [10, Lemma 4.3], pertaining strong solutions, in this context is commented (see Remark 2.7).

## Notations

Hereafter, $\Omega$ denotes a bounded domain in $\mathbb{R}^{N}, N \geq 2$, while $p \in(1,+\infty)$. We set $p^{\prime}:=\frac{p}{p-1}$ and, provided $p<N, p^{*}:=\frac{N p}{N-p}$. If $p \geq N$ then $p^{*}:=\infty$ and $\left(p^{*}\right)^{\prime}:=1$. Write $\operatorname{dist}(A, B)$ for the distance between the nonempty sets $A, B \subseteq \mathbb{R}^{N}$. The symbol $B_{R}(x)$ indicates the (open) ball having center $x \in \mathbb{R}^{N}$ and radius $R>0$, while $\bar{B}_{R}(x)$ stands for the closure of $B_{R}(x)$. Moreover, $B_{R}(x) \Subset \Omega$ means that $\bar{B}_{R}(x) \subseteq \Omega$. Centers of balls will be omitted when they are irrelevant. We denote by $|E|$ the $N$-dimensional Lebesgue measure of the set $E \subseteq \mathbb{R}^{N}$.

Let $C_{c}^{\infty}\left(\mathbb{R}^{N}\right)$ be the space of compactly supported test functions and let $\|\cdot\|_{p}$ be the usual norm in $L^{p}\left(\mathbb{R}^{N}\right)$. The Beppo Levi space $\mathcal{D}_{0}^{1, p}\left(\mathbb{R}^{N}\right)$ is defined as the closure of $C_{c}^{\infty}\left(\mathbb{R}^{N}\right)$ with respect to the norm

$$
\|u\|_{1, p}:=\|\nabla u\|_{p} .
$$

We know that $\mathcal{D}_{0}^{1, p}\left(\mathbb{R}^{N}\right)$ is a reflexive Banach space. Moreover, the Sobolev-type embedding $\mathcal{D}_{0}^{1, p}\left(\mathbb{R}^{N}\right) \hookrightarrow L^{p^{*}}\left(\mathbb{R}^{N}\right)$ entails

$$
\mathcal{D}_{0}^{1, p}\left(\mathbb{R}^{N}\right)=\left\{u \in L^{p^{*}}\left(\mathbb{R}^{N}\right):|\nabla u| \in L^{p}\left(\mathbb{R}^{N}\right)\right\}
$$

Given $f \in L_{\mathrm{loc}}^{1}\left(\mathbb{R}^{N}\right)$, a distributional solution to the equation

$$
\begin{equation*}
-\Delta_{p} u=f(x) \text { in } \mathbb{R}^{N} \tag{1.1}
\end{equation*}
$$

is a function $u \in W_{\text {loc }}^{1, p}\left(\mathbb{R}^{N}\right)$ such that

$$
\begin{equation*}
\int_{\Omega}|\nabla u|^{p-2} \nabla u \cdot \nabla \phi \mathrm{~d} x=\int_{\Omega} f \phi \mathrm{~d} x \quad \forall \phi \in C_{c}^{\infty}\left(\mathbb{R}^{N}\right) . \tag{1.2}
\end{equation*}
$$

If $f \in L^{\left(p^{*}\right)^{\prime}}\left(\mathbb{R}^{N}\right)$ then by weak solution of (1.1) we mean a function $u \in \mathcal{D}_{0}^{1, p}\left(\mathbb{R}^{N}\right)$ satisfying (1.2) for all $\phi \in \mathcal{D}_{0}^{1, p}\left(\mathbb{R}^{N}\right)$. Analogous definitions hold when $\Omega$ replaces $\mathbb{R}^{N}$ or $f$ depends also on $u, \nabla u$. Further details can be found in [10, Section 2].

Finally, $C$ and $C(\cdot)$ represent generic positive constants, which may change value at each passage. Possible arguments emphasize their dependence on written variables.

## 2 Main results

The main result of the paper is the following.
Theorem 2.1 Let $\mathrm{H}_{1}-\mathrm{H}_{2}$ be satisfied. Then problem $(\mathrm{P})$ possesses a weak solution $(u, v) \in$ $\mathcal{D}_{0}^{1, p}\left(\mathbb{R}^{N}\right) \times \mathcal{D}_{0}^{1, q}\left(\mathbb{R}^{N}\right)$.

For every $f \in L_{\mathrm{loc}}^{2}(\Omega)$, we define the nonlinear potential

$$
P_{f}(x, R):=\int_{0}^{R}\left(\frac{|f|^{2}\left(B_{\rho}(x)\right)}{\rho^{N-2}}\right)^{\frac{1}{2}} \frac{\mathrm{~d} \rho}{\rho}, \quad \text { where }|f|^{2}\left(B_{\rho}(x)\right):=\|f\|_{L^{2}\left(B_{\rho}(x)\right)}^{2}
$$

The following basic result was established in [6].
Proposition 2.2 Let $u \in W_{\text {loc }}^{1, p}(\Omega)$ be a distributional solution to

$$
\begin{equation*}
-\Delta_{p} u=f(x) \text { in } \Omega \tag{2.1}
\end{equation*}
$$

with $f \in L_{\mathrm{loc}}^{r}(\Omega), r:=\max \left\{2,\left(p^{*}\right)^{\prime}\right\}$. Then there exists $C=C(N, p)>0$ such that

$$
\|\nabla u\|_{L^{\infty}\left(B_{R}\right)} \leq C\left[\left(\frac{1}{\left|B_{2 R}\right|} \int_{B_{2 R}}|\nabla u|^{p} \mathrm{~d} x\right)^{\frac{1}{p}}+\left\|P_{f}(\cdot, 2 R)\right\|_{L^{\infty}\left(B_{2 R}\right)}^{\frac{1}{p-1}}\right]
$$

for any $B_{2 R} \Subset \Omega$.
Remark 2.3 As observed in [6, p. 1363], the condition $r \geq\left(p^{*}\right)^{\prime}$ is not used to prove the result, but it guarantees that $u$ is a weak solution, and not merely a very weak solution. In the latter case, an approximation procedure yields the existence of a very weak solution $u \in W^{1, p-1}(\Omega)$ of (2.1). For a thorough treatment on approximable solutions, see [3].

Lemma 2.4 Let $u \in \mathcal{D}_{0}^{1, p}\left(\mathbb{R}^{N}\right)$ be a distributional solution to

$$
-\Delta_{p} u=f(x) \text { in } \mathbb{R}^{N},
$$

with $f \in L^{r}\left(\mathbb{R}^{N}\right), r>N$. Then $\nabla u \in L^{\infty}\left(\mathbb{R}^{N}\right)$. More precisely, there exists $C=C(N, p)>$ 0 such that

$$
\|\nabla u\|_{L^{\infty}\left(\mathbb{R}^{N}\right)}^{p-1} \leq C\left(\|\nabla u\|_{L^{p}\left(\mathbb{R}^{N}\right)}^{p-1}+\|f\|_{L^{r}\left(\mathbb{R}^{N}\right)}\right) .
$$

Proof Pick any $x \in \mathbb{R}^{N}$. By Proposition 2.2 and Hölder's inequality (with exponents $\frac{r}{2}$ and $\frac{r}{r-2}$ ), after observing that $r>N \geq \max \left\{2,\left(p^{*}\right)^{\prime}\right\}$, we get

$$
\begin{aligned}
|\nabla u(x)|^{p-1} & \leq\|\nabla u\|_{L^{\infty}\left(B_{1}(x)\right)}^{p-1} \\
& \leq C\left[\left(\frac{1}{\left|B_{2}(x)\right|} \int_{B_{2}(x)}|\nabla u|^{p} \mathrm{~d} x\right)^{\frac{1}{p^{\prime}}}+\left\|P_{f}(\cdot, 2)\right\|_{L^{\infty}\left(B_{2}(x)\right)}\right] \\
& \leq C\left[\|\nabla u\|_{L^{p}\left(\mathbb{R}^{N}\right)}^{p-1}+\sup _{y \in B_{2}(x)} \int_{0}^{2} \rho^{-\frac{N}{2}}\|f\|_{L^{2}\left(B_{\rho}(y)\right)} \mathrm{d} \rho\right] \\
& \leq C\left[\|\nabla u\|_{L^{p}\left(\mathbb{R}^{N}\right)}^{p-1}+\|f\|_{L^{r}\left(\mathbb{R}^{N}\right)} \int_{0}^{2} \rho^{-\frac{N}{r}} \mathrm{~d} \rho\right] \\
& \leq C\left(\|\nabla u\|_{L^{p}\left(\mathbb{R}^{N}\right)}^{p-1}+\|f\|_{L^{r}\left(\mathbb{R}^{N}\right)}\right) .
\end{aligned}
$$

Taking the supremum in $x \in \mathbb{R}^{N}$ on the left yields the conclusion.
For every $u \in W_{\text {loc }}^{1, p}(\Omega), x \in B_{R} \Subset \Omega$, and $h \in \mathbb{R}^{N}$ such that $|h|<\operatorname{dist}\left(B_{R}, \partial \Omega\right)$, we set

$$
u_{h}(x):=u(x+h), \quad \delta_{h} u:=u_{h}-u .
$$

Analogous definitions hold for vector-valued functions.
Lemma 2.5 Let $\left\{u_{n}\right\} \subseteq W_{\mathrm{loc}}^{1, p}(\Omega)$ and $\left\{f_{n}\right\} \subseteq L_{\mathrm{loc}}^{r^{\prime}}(\Omega), r \in\left(1, p^{*}\right)$, be such that $u_{n}$ is a distributional solution to

$$
-\Delta_{p} u_{n}=f_{n}(x) \text { in } \Omega
$$

for all $n \in \mathbb{N}$. Suppose that:
$\left(\mathrm{K}_{1}\right) \quad\left\{\nabla u_{n}\right\}$ is bounded in $L_{\mathrm{loc}}^{p}(\Omega)$;
$\left(\mathrm{K}_{2}\right) \quad\left\{f_{n}\right\}$ is bounded in $L_{\mathrm{loc}}^{r^{\prime}}(\Omega)$;
$\left(\mathrm{K}_{3}\right) \quad u_{n} \rightarrow u$ in $L_{\mathrm{loc}}^{p}(\Omega) \cap L_{\mathrm{loc}}^{r}(\Omega)$.
Then $\left\{\nabla u_{n}\right\}$ admits a strongly convergent subsequence in $L_{\mathrm{loc}}^{p}(\Omega)$.
Proof Fix $R>0$ fulfilling $B_{R} \Subset \Omega$. A density argument produces

$$
\begin{equation*}
\int_{B_{R}}\left|\nabla u_{n}\right|^{p-2} \nabla u_{n} \cdot \nabla \phi \mathrm{~d} x=\int_{B_{R}} f_{n} \phi \mathrm{~d} x \tag{2.2}
\end{equation*}
$$

for every $n \in \mathbb{N}$ and $\phi \in W_{0}^{1, p}\left(B_{R}\right)$. Now, pick $t, s>0$ such that $B_{t} \Subset B_{s} \Subset B_{R}$ and $\eta \in C_{c}^{\infty}\left(B_{s}\right)$ such that $0 \leq \eta \leq 1, \eta \equiv 1$ on $B_{t}$, and $|\nabla \eta| \leq \frac{C}{s-t}$ for some $C>0$. If $V_{n}:=\left|\nabla u_{n}\right|^{p-2} \nabla u_{n}$ then using (2.2) with $\phi:=\eta^{2} \delta_{h} u_{n}$, where $|h|<R-s$, gives

$$
\begin{equation*}
\int_{B_{R}} \eta^{2} V_{n} \cdot \delta_{h}\left(\nabla u_{n}\right) \mathrm{d} x+2 \int_{B_{R}} \eta \delta_{h} u_{n} V_{n} \cdot \nabla \eta \mathrm{~d} x=\int_{B_{R}} f_{n} \phi \mathrm{~d} x . \tag{2.3}
\end{equation*}
$$

Next, exploit (2.2) with $\phi_{-h}$, perform the change of variable $x \mapsto x+h$ on the left-hand side, and recall that $B_{s+|h|} \subseteq B_{R}$, to achieve

$$
\begin{equation*}
\int_{B_{R}} \eta^{2}\left(V_{n}\right)_{h} \cdot \delta_{h}\left(\nabla u_{n}\right) \mathrm{d} x+2 \int_{B_{R}} \eta \delta_{h} u_{n}\left(V_{n}\right)_{h} \cdot \nabla \eta \mathrm{~d} x=\int_{B_{R}} f_{n} \phi_{-h} \mathrm{~d} x . \tag{2.4}
\end{equation*}
$$

Subtracting (2.3) from (2.4) yields

$$
\int_{B_{R}} \eta^{2} \delta_{h} V_{n} \cdot \delta_{h}\left(\nabla u_{n}\right) \mathrm{d} x+2 \int_{B_{R}} \eta \delta_{h} u_{n} \delta_{h} V_{n} \cdot \nabla \eta \mathrm{~d} x=\int_{B_{R}} f_{n} \delta_{-h} \phi \mathrm{~d} x
$$

Since supp $\eta \subseteq B_{s}$, this entails

$$
\begin{align*}
\int_{B_{t}} \delta_{h} V_{n} \cdot \delta_{h}\left(\nabla u_{n}\right) \mathrm{d} x \leq & \int_{B_{R}} \eta^{2} \delta_{h} V_{n} \cdot \delta_{h}\left(\nabla u_{n}\right) \mathrm{d} x \\
\leq & 2 \int_{B_{R}}\left|\delta_{h} u_{n}\left\|\delta_{h} V_{n}\right\| \nabla \eta\right| \mathrm{d} x+\int_{B_{R}}\left|f_{n} \| \delta_{-h} \phi\right| \mathrm{d} x \\
\leq & \frac{C}{s-t}\left\|\delta_{h} u_{n}\right\|_{L^{p}\left(B_{s}\right)}\left\|\delta_{h} V_{n}\right\|_{L^{p^{\prime}\left(B_{s}\right)}}+\left\|f_{n}\right\|_{L^{r^{\prime}\left(B_{s}\right)}}\left\|\delta_{-h} \phi\right\|_{L^{r}\left(B_{s}\right)} \\
\leq & \frac{C}{s-t}\left\|\delta_{h} u_{n}\right\|_{L^{p}\left(B_{R}\right)}\left(\left\|\left(V_{n}\right)_{h}\right\|_{L^{p^{\prime}\left(B_{s}\right)}}+\left\|V_{n}\right\|_{L^{p^{\prime}\left(B_{s}\right)}}\right) \\
& +\left\|f_{n}\right\|_{L^{r^{\prime}\left(B_{R}\right)}}\left(\left\|\phi_{-h}\right\|_{L^{r}\left(B_{s}\right)}+\|\phi\|_{L^{r}\left(B_{s}\right)}\right) \\
\leq & \frac{2 C}{s-t}\left\|\delta_{h} u_{n}\right\|_{L^{p}\left(B_{R}\right)}\left\|V_{n}\right\|_{L^{p^{\prime}\left(B_{R}\right)}}+2\left\|f_{n}\right\|_{L^{r^{\prime}\left(B_{R}\right)}}\left\|\delta_{h} u_{n}\right\|_{L^{r}\left(B_{R}\right)} \\
\leq & C\left(\left\|\delta_{h} u_{n}\right\|_{L^{p}\left(B_{R}\right)}\left\|\nabla u_{n}\right\|_{L^{p}\left(B_{R}\right)}^{p-1}+\left\|f_{n}\right\|_{L^{r^{\prime}\left(B_{R}\right)}}\left\|\delta_{h} u_{n}\right\|_{L^{r}\left(B_{R}\right)}\right) \tag{2.5}
\end{align*}
$$

where Hölder's inequality has been used twice, while $C=C(N, t, s)>0$. Notice that, thanks to $\left(\mathrm{K}_{1}\right)-\left(\mathrm{K}_{3}\right)$ and [2, Exercise 4.34], the last term of (2.5) vanishes as $h \rightarrow 0^{+}$ uniformly in $n$. Let us now distinguish two cases, namely $p \geq 2$ and $p \in(1,2)$.

Case 1. If $p \geq 2$ then

$$
\begin{align*}
\int_{B_{t}} \delta_{h} V_{n} \cdot \delta_{h}\left(\nabla u_{n}\right) \mathrm{d} x & =\int_{B_{t}}\left(\left|\nabla\left(u_{n}\right)_{h}\right|^{p-2} \nabla\left(u_{n}\right)_{h}-\left|\nabla u_{n}\right|^{p-2} \nabla u_{n}\right) \cdot\left(\nabla\left(u_{n}\right)_{h}-\nabla u_{n}\right) \mathrm{d} x \\
& \geq C\left\|\left(\nabla u_{n}\right)_{h}-\nabla u_{n}\right\|_{L^{p}\left(B_{t}\right)}^{p}=C\left\|\delta_{h}\left(\nabla u_{n}\right)\right\|_{L^{p}\left(B_{t}\right)}^{p}, \tag{2.6}
\end{align*}
$$

with $C>0$ small enough; cf. [13, Chapter 12, inequality (I)]. By (2.5)-(2.6) we thus obtain $\delta_{h}\left(\nabla u_{n}\right) \rightarrow 0$ in $L^{p}\left(B_{t}\right)$ as $h \rightarrow 0^{+}$uniformly in $n$, and the Riesz-Fréchet-Kolmogorov $L^{p}$-compactness criterion yields the conclusion, because $t>0$ was arbitrary.

Case 2. For $p \in(1,2)$ one has (see [13, Chapter 12, inequality (VII)])

$$
\begin{align*}
\int_{B_{t}} \delta_{h} V_{n} \cdot \delta_{h}\left(\nabla u_{n}\right) \mathrm{d} x & =\int_{B_{t}}\left(\left|\nabla\left(u_{n}\right)_{h}\right|^{p-2} \nabla\left(u_{n}\right)_{h}-\left|\nabla u_{n}\right|^{p-2} \nabla u_{n}\right) \cdot\left(\nabla\left(u_{n}\right)_{h}-\nabla u_{n}\right) \mathrm{d} x \\
& \geq C \int_{B_{t}}\left(1+\left|\nabla\left(u_{n}\right)_{h}\right|^{2}+\left|\nabla u_{n}\right|^{2}\right)^{\frac{p-2}{2}}\left|\nabla\left(u_{n}\right)_{h}-\nabla u_{n}\right|^{2} \mathrm{~d} x \\
& =C \int_{B_{t}} W_{n h}\left|\delta_{h}\left(\nabla u_{n}\right)\right|^{2} \mathrm{~d} x, \tag{2.7}
\end{align*}
$$

where $C>0$ is sufficiently small while $W_{n h}:=\left(1+\left|\nabla\left(u_{n}\right)_{h}\right|^{2}+\left|\nabla u_{n}\right|^{2}\right)^{\frac{p-2}{2}}$. Hölder's inequality with exponents $\frac{2}{p}$ and $\frac{2}{2-p}$, besides $\left(\mathrm{K}_{1}\right)$, produce

$$
\begin{align*}
\left\|\delta_{h}\left(\nabla u_{n}\right)\right\|_{L^{p}\left(B_{t}\right)}^{p} & =\int_{B_{t}} W_{n h}^{\frac{p}{2}}\left|\delta_{h}\left(\nabla u_{n}\right)\right|^{p} W_{n h}^{-\frac{p}{2}} \mathrm{~d} x \\
& \leq\left(\int_{B_{t}} W_{n h}\left|\delta_{h}\left(\nabla u_{n}\right)\right|^{2} \mathrm{~d} x\right)^{\frac{p}{2}}\left(\int_{B_{t}} W_{n h}^{\frac{p}{p-2}} \mathrm{~d} x\right)^{\frac{2-p}{2}} \\
& \leq\left(\int_{B_{t}} W_{n h}\left|\delta_{h}\left(\nabla u_{n}\right)\right|^{2} \mathrm{~d} x\right)^{\frac{p}{2}}\left(\left|B_{t}\right|+2\left\|\nabla u_{n}\right\|_{L^{p}\left(B_{R}\right)}^{p}\right)^{\frac{2-p}{2}} \\
& \leq C\left(\int_{B_{t}} W_{n h}\left|\delta_{h}\left(\nabla u_{n}\right)\right|^{2} \mathrm{~d} x\right)^{\frac{p}{2}} . \tag{2.8}
\end{align*}
$$

Reasoning as in the case above, the conclusion directly follows from (2.5), (2.7), and (2.8).

Remark 2.6 Lemma 2.5 can be proved also (in a less direct way) through a result by Boccardo and Murat [1] which, under the hypotheses of Lemma 2.5, ensures that

$$
\begin{equation*}
\nabla u_{n} \rightarrow \nabla u \text { in } L_{\mathrm{loc}}^{q}(\Omega) \quad \forall q \in(1, p) . \tag{2.9}
\end{equation*}
$$

Evidently, (2.9) implies $\nabla u_{n}(x) \rightarrow \nabla u(x)$ for almost every $x \in \Omega$. A development of this approach, allowing $q=p$, is contained in [7, Lemma 2.5 and Remark 3]. Another way $[4,11]$ to get convergence of gradient terms relies on a differentiability result for the stress field, i.e., the field whose divergence represents the elliptic operator (as $|\nabla u|^{p-2} \nabla u$ for the $p$-Laplacian). In fact, by Rellich-Kondrachov's theorem [2, Theorem 9.16], such a differentiability allows to gain compactness.

Proof of Theorem 2.1 The reasoning is patterned after that of [10, Lemma 4.1]. So, here, we only sketch it. Pick $r, s>1$ such that

$$
\begin{equation*}
\frac{1}{\zeta_{1}}+\theta_{1}<\frac{1}{r^{\prime}}<1-\frac{p}{p^{*}}, \quad \frac{1}{\zeta_{2}}+\theta_{2}<\frac{1}{s^{\prime}}<1-\frac{q}{q^{*}}, \tag{2.10}
\end{equation*}
$$

which is possible thanks to $\mathrm{H}_{1}$ (a). Fix $\rho>0$ and define $\varepsilon_{n}:=\frac{1}{n}, n \in \mathbb{N}$. By [10, Lemmas 3.5-3.8], for every $n \in \mathbb{N}$ there exists $\left(u_{n}, v_{n}\right) \in\left(\mathcal{D}_{0}^{1, p}\left(\mathbb{R}^{N}\right) \times \mathcal{D}_{0}^{1, q}\left(\mathbb{R}^{N}\right)\right) \cap C_{\text {loc }}^{1, \alpha}\left(\mathbb{R}^{N}\right)^{2}$ solution to

$$
\left\{\begin{align*}
-\Delta_{p} u & =f\left(x, u+\varepsilon_{n}, v, \nabla u, \nabla v\right) & & \text { in } \mathbb{R}^{N}  \tag{n}\\
-\Delta_{q} v & =g\left(x, u, v+\varepsilon_{n}, \nabla u, \nabla v\right) & & \text { in } \mathbb{R}^{N} \\
u, v & >0 & & \text { in } \mathbb{R}^{N}
\end{align*}\right.
$$

such that the following properties hold true, with appropriate $(u, v) \in \mathcal{D}_{0}^{1, p}\left(\mathbb{R}^{N}\right) \times \mathcal{D}_{0}^{1, q}\left(\mathbb{R}^{N}\right)$ and $M, \sigma_{2 \rho}>0$ :

$$
\begin{align*}
\left(u_{n}, v_{n}\right) & \rightarrow(u, v) & & \text { in } \mathcal{D}_{0}^{1, p}\left(\mathbb{R}^{N}\right. \\
\left(u_{n}, v_{n}\right) & \rightarrow(u, v) & & \text { in } W^{1, p}\left(B_{2}\right. \\
\left(u_{n}, v_{n}\right) & \rightarrow(u, v) & & \text { in } L^{r}\left(B_{2 \rho}\right) \\
\left(\nabla u_{n}, \nabla v_{n}\right) & \rightarrow(\nabla u, \nabla v) & & \text { a.e. in } \mathbb{R}^{N} ; \\
\max \left\{\left\|u_{n}\right\|_{L^{\infty}\left(\mathbb{R}^{N}\right)},\left\|v_{n}\right\|_{L^{\infty}\left(\mathbb{R}^{N}\right)}\right\} & \leq M & & \forall n \in \mathbb{N} ;  \tag{2.11}\\
\min \left\{\inf _{B_{2 \rho}} u_{n}, \inf _{B_{2 \rho}} v_{n}\right\} & \geq \sigma_{2 \rho} & & \forall n \in \mathbb{N} .
\end{align*}
$$

Hence, $\mathrm{H}_{1}(\mathrm{f})$ and (2.11) yield, for almost every $x \in B_{2 \rho}$,

$$
\begin{align*}
& f\left(x, u_{n}(x)+\varepsilon_{n}, v_{n}(x), \nabla u_{n}(x), \nabla v_{n}(x)\right) \\
& \leq \hat{m}_{1} a_{1}(x)\left[\left(u_{n}(x)+\varepsilon_{n}\right)^{\alpha_{1}} v_{n}(x)^{\beta_{1}}+\left|\nabla u_{n}(x)\right|^{\gamma_{1}}+\left|\nabla v_{n}(x)\right|^{\delta_{1}}\right] \\
& \leq \hat{m}_{1} a_{1}(x)\left(\sigma_{2 \rho}^{\alpha_{1}} M^{\beta_{1}}+\left|\nabla u_{n}(x)\right|^{\gamma_{1}}+\left|\nabla v_{n}(x)\right|^{\delta_{1}}\right) . \tag{2.12}
\end{align*}
$$

By (2.11) the sequence $\left\{\left(\nabla u_{n}, \nabla v_{n}\right)\right\}$ is bounded in $L^{p}\left(B_{2 \rho}\right) \times L^{q}\left(B_{2 \rho}\right)$. Exploiting $\mathrm{H}_{1}(\mathrm{a})$, (2.10), and (2.12) we thus see that

$$
\left\{f\left(\cdot, u_{n}+\varepsilon_{n}, v_{n}, \nabla u_{n}, \nabla v_{n}\right)\right\} \quad \text { is bounded in } L^{r^{\prime}}\left(B_{2 \rho}\right) .
$$

Accordingly, Lemma 2.5, with $\Omega:=B_{2 \rho}$, besides (2.11), produces $\nabla u_{n} \rightarrow \nabla u$ in $L^{p}\left(B_{\rho}\right)$. Now the proof goes on exactly as in [10, Lemma 4.1], ensuring that $(u, v)$ is a distributional solution to ( P ). The conclusion is achieved through [10, Lemma 4.2], which shows that any distributional solution to $(\mathrm{P})$ turns out a weak one.

Remark 2.7 An advantage of using differentiability results for the stress field (see Remark 2.6) in this context is the possibility to obtain strong solutions of ( P ), as done in [10, Lemma 4.3]. Indeed, otherwise we do not know how to give a pointwise (a.e.) sense to the $p$-Laplacian operator, seen as the divergence of the stress field $|\nabla u|^{p-2} \nabla u$. This issue is linked to a well-known conjecture for (2.1), which can be stated as

$$
f \in L_{\mathrm{loc}}^{r}(\Omega) \quad \stackrel{?}{\Leftrightarrow} \quad|\nabla u|^{p-2} \nabla u \in W_{\mathrm{loc}}^{1, r}(\Omega) .
$$

For a discussion about this conjecture, see [11, Section 1].
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## Declarations

Conflict of interest On behalf of all authors, the corresponding author states that there is no conflict of interest.

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