Filomat 36:6 (2022), 1967–1970 https://doi.org/10.2298/FIL2206967A



Published by Faculty of Sciences and Mathematics, University of Niš, Serbia Available at: http://www.pmf.ni.ac.rs/filomat

Global Regularity for the 3D Micropolar Fluid Flows

Ahmad M. Alghamdi^a, Sadek Gala^{b,c}, Maria Alessandra Ragusa^{c,d}

^aDepartment of Mathematical Science, Faculty of Applied Science, Umm Al-Qura University, P. O. Box 14035, Makkah 21955, Saudi Arabia ^bDepartment of Mathematics, ENS of Mostaganem, Box 227, Mostaganem 27000, Algeria ^cDipartimento di Matematica e Informatica, Università di Catania, Viale Andrea Doria, 6 95125 Catania - Italy ^dRUDN University, 6 Miklukho - Maklay St, Moscow, 117198, Russia

Abstract. The aim of this note is to establish the global regularity of classical solutions of the 3D micropolar fluid equations for a family of large initial data with finite energy.

1. Introduction

In this paper, we consider the following Cauchy problem for the incompressible micropolar fluid equations :

$$\begin{cases} \partial_t u + (u \cdot \nabla) u - \Delta u + \nabla \pi - \nabla \times \omega = 0, \\ \partial_t \omega - \Delta \omega - \nabla div\omega + 2\omega + u \cdot \nabla \omega - \nabla \times u = 0, \\ \nabla \cdot u = 0, \\ u(x, 0) = u_0(x), \ \omega(x, 0) = \omega_0(x), \end{cases}$$
(1.1)

where $u = u(x, t) \in \mathbb{R}^3$, $\omega = \omega(x, t) \in \mathbb{R}^3$ and p = p(x, t) denote the unknown velocity vector field, the microrotational velocity and the unknown scalar pressure of the fluid at the point $(x, t) \in \mathbb{R}^3 \times (0, T)$, respectively, while u_0, ω_0 are given initial data with $\nabla \cdot u = 0$ in the sense of distributions.

Micropolar fluid system was first proposed by Eringen [2] in 1966. Later on, Galdi and Rionero [3] considered the weak solution in the year 1977. Using linearization and an almost fixed point theorem, in 1988, Lukaszewicz [4] established the global existence of weak solutions with sufficiently regular initial data. In 1989, using the same technique, Lukaszewicz [5] proved the local and global existence and the uniqueness of the strong solutions under asymmetric condition. In 2005, Yamaguchi [8] proved the existence theorem of global in time solution for small initial data.

Inspired by the work of [6], for the 3D Navier-Stokes equations, the main purpose of this note is to study the global existence of smooth solutions to (1.1) for a family of large initial data with finite energy.

Our result is the following.

²⁰²⁰ Mathematics Subject Classification. Primary 35Q35; Secondary 35B65, 76D05

Keywords. Micropolar fluid equations; global solutions; finite energy

Received: 27 July 2016; Accepted: 23 March 2020

Communicated by Dragan S. Djordjević

Corresponding author: Maria Alessandra Ragusa

This paper has been supported by the RUDN University Strategic Academic Leadership Program and PRIN 2017 n.2017AYM8XW004.

Email addresses: amghamdi@uqu.edu.sa (Ahmad M. Alghamdi), sgala793@gmail.com (Sadek Gala), mariaalessandra.ragusa@unict.it (Maria Alessandra Ragusa)

Theorem 1.1. Assume that $u_0, w_0 \in \mathcal{M}$ for some constant $\delta > 0$. Then there exists a positive constant δ_0 such that (1.1) with the initial data (u_0, w_0) has a unique global classical solution (u, ω) if $\delta \leq \delta_0$. Here

$$\mathcal{M} = \left\{ \begin{array}{l} u_{0}, w_{0} \in H^{1}(\mathbb{R}^{3}) \quad with \quad \nabla \cdot u_{0} = 0, \\ \sum_{i=1}^{2} \|u_{0}\|_{L^{2}} \left\|\partial_{x_{i}}u_{0}\right\|_{L^{2}} \leq \delta, \quad \sum_{i=1}^{2} \|\omega_{0}\|_{L^{2}} \left\|\partial_{x_{i}}\omega_{0}\right\|_{L^{2}} \leq \delta, \\ \sum_{i=1}^{2} \|u_{0}\|_{L^{2}} \left\|\partial_{x_{i}}\omega_{0}\right\|_{L^{2}} \leq \delta, \quad \sum_{i=1}^{2} \|\omega_{0}\|_{L^{2}} \left\|\partial_{x_{i}}u_{0}\right\|_{L^{2}} \leq \delta \end{array} \right\}.$$

We recall the following Serrin's type non-blow up criterion [3].

Lemma 1.2. Assume that the initial data $u_0, \omega_0 \in H^1(\mathbb{R}^3)$ with $\nabla \cdot u_0 = 0$. If

$$u \in L^q\left((0,T); L^p(\mathbb{R}^3)\right) \ with \ \frac{2}{q} + \frac{3}{p} \leq 1 \ and \ 3$$

then the solution (u, ω) remains smooth on [0, T].

In the following calculations, we use the following interpolation inequality due to [6]:

$$\|f\|_{L^4} \le C \|f\|_{L^2}^{\frac{1}{2}} \|\partial_1 f\|_{L^2}^{\frac{1}{8}} \|\partial_1 \partial_3 f\|_{L^2}^{\frac{1}{8}} \|\partial_2 f\|_{L^2}^{\frac{1}{8}} \|\partial_2 \partial_3 f\|_{L^2}^{\frac{1}{8}}.$$
(1.2)

2. Proof of Theorem 1.1

Proof: Assume that u_0 , ω_0 belongs to \mathcal{M} . The local existence theory is classical, see for instance [3, 8]. Hence there exists a unique smooth solution (u, ω) of (1.1) on some time interval [0, T) with T > 0.

Taking the inner products of $(1.1)_1$ with u and $(1.1)_2$ with ω , adding the results and integrating by parts, we obtain

$$\begin{aligned} \|u(\cdot,t)\|_{L^{2}}^{2} + \|\omega(\cdot,t)\|_{L^{2}}^{2} + 2\int_{0}^{t} \|\nabla u(\cdot,s)\|_{L^{2}}^{2} \, ds + 2\int_{0}^{t} \|\nabla \omega(\cdot,s)\|_{L^{2}}^{2} \, ds \\ + 2\int_{0}^{t} \|\nabla \cdot \omega(\cdot,s)\|_{L^{2}}^{2} \, ds + 2\int_{0}^{t} \|\omega(\cdot,s)\|_{L^{2}}^{2} \, ds \leq \|u_{0}\|_{L^{2}}^{2} + \|\omega_{0}\|_{L^{2}}^{2} \, ds \end{aligned}$$

for all $t \ge 0$.

Applying the derivatives $\partial_i = \frac{\partial}{x_i}$ (*i* = 1, 2) on either sides of the equations (1.1) yields to

$$\begin{cases} \partial_i \partial_i u + (u \cdot \nabla) \partial_i u - \Delta \partial_i u + \nabla \partial_i \pi - \nabla \times \partial_i \omega = 0, \\ \partial_i \partial_i \omega - \Delta \partial_i \omega - \nabla \operatorname{div} \partial_i \omega + 2 \partial_i \omega + (u \cdot \nabla) \partial_i \omega - \nabla \times \partial_i u = 0. \end{cases}$$
(2.1)

Considering the scalar products with $\partial_i u$, $\partial_i \omega$, respectively, and adding them, we have

$$\begin{aligned} &\frac{1}{2}\frac{d}{dt}\left(\left\|\partial_{i}u\right\|_{L^{2}}^{2}+\left\|\partial_{i}\omega\right\|_{L^{2}}^{2}\right)+\left\|\nabla\partial_{i}u\right\|_{L^{2}}^{2}+\left\|\nabla\partial_{i}\omega\right\|_{L^{2}}^{2}+\left\|\nabla\cdot\partial_{i}\omega\right\|_{L^{2}}^{2}+2\left\|\partial_{i}\omega\right\|_{L^{2}}^{2}\\ &=-\int_{\mathbb{R}^{3}}\partial_{i}u\cdot\nabla u\cdot\partial_{i}udx+\int_{\mathbb{R}^{3}}(\nabla\times\partial_{i}\omega)\cdot\partial_{i}udx+\int_{\mathbb{R}^{3}}(\nabla\times\partial_{i}u)\cdot\partial_{i}\omega dx-\int_{\mathbb{R}^{3}}\partial_{i}u\cdot\nabla\omega\cdot\partial_{i}\omega dx\\ &=A_{1}+A_{2}+A_{3}+A_{4}.\end{aligned}$$

To bound A_1 , we integrate by parts and apply Hölder's inequality to obtain by (1.2)

$$\begin{split} A_{1} &= -\int_{\mathbb{R}^{3}} \partial_{i} u \cdot \nabla u \cdot \partial_{i} u dx = \int_{\mathbb{R}^{3}} \partial_{i} u \cdot u \cdot \nabla \partial_{i} u dx \\ &\leq \|u\|_{L^{4}} \|\partial_{i} u\|_{L^{4}} \|\nabla \partial_{i} u\|_{L^{2}} \\ &\leq C \|u\|_{L^{2}}^{\frac{1}{2}} \|\partial_{1} u\|_{L^{2}}^{\frac{1}{8}} \|\partial_{1} \partial_{3} u\|_{L^{2}}^{\frac{1}{8}} \|\partial_{2} u\|_{L^{2}}^{\frac{1}{8}} \|\partial_{2} \partial_{3} u\|_{L^{2}}^{\frac{1}{8}} \|\partial_{i} u\|_{L^{2}}^{\frac{1}{4}} \|\nabla \partial_{i} u\|_{L^{2}}^{\frac{7}{4}} \\ &\leq C \|u\|_{L^{2}}^{\frac{1}{2}} \|\partial_{i} u\|_{L^{2}}^{\frac{1}{2}} \|\nabla \partial_{i} u\|_{L^{2}}^{2} \,. \end{split}$$

Using the integration by parts and the Cauchy-Schwarz inequality, we estimate

 $A_2 + A_3 \le 2 \|\partial_i \omega\|_{L^2} \|\nabla \partial_i u\|_{L^2} \le \|\partial_i \omega\|_{L^2}^2 + \|\nabla \partial_i u\|_{L^2}^2.$

To bound A_4 , we integrate by parts and apply Hölder's inequality to get by (1.2)

$$\begin{split} A_{4} &= -\int_{\mathbb{R}^{3}} \partial_{i} u \cdot \nabla \omega \cdot \partial_{i} \omega dx = -\sum_{j,k=1}^{3} \int_{\mathbb{R}^{3}} \partial_{i} u_{j} \omega_{k} \partial_{j} \partial_{i} \omega_{k} dx \\ &\leq \| \omega \|_{L^{4}} \| \partial_{i} u \|_{L^{4}} \| \nabla \partial_{i} \omega \|_{L^{2}} \\ &\leq C \| \omega \|_{L^{2}}^{\frac{1}{2}} \| \partial_{1} \omega \|_{L^{2}}^{\frac{1}{8}} \| \partial_{1} \partial_{3} \omega \|_{L^{2}}^{\frac{1}{8}} \| \partial_{2} \omega \|_{L^{2}}^{\frac{1}{8}} \| \partial_{2} \partial_{3} \omega \|_{L^{2}}^{\frac{1}{8}} \| \partial_{i} u \|_{L^{2}}^{\frac{1}{4}} \| \nabla \partial_{i} u \|_{L^{2}}^{\frac{3}{4}} \| \nabla \partial_{i} \omega \|_{L^{2}}^{\frac{3}{4}} \| \nabla \partial_{i} \omega \|_{L^{2}}^{\frac{3}{4}} \| \partial_{1} \omega \|_{L^{2}}^{\frac{1}{4}} \| \nabla \partial_{i} \omega \|_{L^{2}}^{\frac{3}{4}} \\ &\leq C \| \omega \|_{L^{2}}^{\frac{1}{2}} \| \partial_{i} \omega \|_{L^{2}}^{\frac{1}{4}} \| \partial_{i} u \|_{L^{2}}^{\frac{1}{4}} (\| \nabla \partial_{i} \omega \|_{L^{2}}^{2} + \| \nabla \partial_{i} u \|_{L^{2}}^{2}) \\ &\leq C \| \omega \|_{L^{2}}^{\frac{1}{2}} \| \partial_{i} \omega \|_{L^{2}}^{\frac{1}{4}} + \| \omega \|_{L^{2}}^{\frac{1}{4}} (\| \nabla \partial_{i} \omega \|_{L^{2}}^{2} + \| \nabla \partial_{i} u \|_{L^{2}}^{2}) \\ &= C \left(\| \omega \|_{L^{2}}^{\frac{1}{2}} \| \partial_{i} \omega \|_{L^{2}}^{\frac{1}{2}} + \| \omega \|_{L^{2}}^{\frac{1}{2}} \| \partial_{i} u \|_{L^{2}}^{\frac{1}{2}} \right) (\| \nabla \partial_{i} \omega \|_{L^{2}}^{2} + \| \nabla \partial_{i} u \|_{L^{2}}^{2}). \end{split}$$

Combining the estimates for A_1 , A_2 , A_3 and A_4 , we find

$$\frac{1}{2}\frac{d}{dt}\sum_{i=1}^{2}\left(\left\|\partial_{i}u\right\|_{L^{2}}^{2}+\left\|\partial_{i}\omega\right\|_{L^{2}}^{2}\right)+\sum_{i=1}^{2}\left(\left\|\nabla\partial_{i}u\right\|_{L^{2}}^{2}+\left\|\nabla\partial_{i}\omega\right\|_{L^{2}}^{2}+\left\|\nabla\cdot\partial_{i}\omega\right\|_{L^{2}}^{2}+2\left\|\partial_{i}\omega\right\|_{L^{2}}^{2}\right)$$

$$\leq C\sum_{i=1}^{2}\left(\left\|\nabla\partial_{i}\omega\right\|_{L^{2}}^{2}+\left\|\nabla\partial_{i}u\right\|_{L^{2}}^{2}\right)\left(\left\|u\right\|_{L^{2}}^{\frac{1}{2}}\left\|\partial_{i}u\right\|_{L^{2}}^{\frac{1}{2}}+\left\|\omega\right\|_{L^{2}}^{\frac{1}{2}}\left\|\partial_{i}\omega\right\|_{L^{2}}^{\frac{1}{2}}+\left\|\omega\right\|_{L^{2}}^{\frac{1}{2}}\left\|\partial_{i}\omega\right\|_{L^{2}}^{\frac{1}{2}}+\left\|\omega\right\|_{L^{2}}^{\frac{1}{2}}\left\|\partial_{i}\omega\right\|_{L^{2}}^{\frac{1}{2}}\right).$$

Hence, if the initial data belongs to \mathcal{M} and taking $\delta_0 = \frac{1}{2C}$, we have

$$\frac{1}{2}\frac{d}{dt}\sum_{i=1}^{2}\left(\|\partial_{i}u\|_{L^{2}}^{2}+\|\partial_{i}\omega\|_{L^{2}}^{2}\right)+\sum_{i=1}^{2}\left(\|\nabla\partial_{i}u\|_{L^{2}}^{2}+\|\nabla\partial_{i}\omega\|_{L^{2}}^{2}+\|\nabla\cdot\partial_{i}\omega\|_{L^{2}}^{2}+2\|\partial_{i}\omega\|_{L^{2}}^{2}\right)\leq0,$$

for all $t \ge 0$. In particular, there holds

$$\sum_{i=1}^{2} \|\partial_{i}u\|_{L^{2}}^{2} \leq \sum_{i=1}^{2} \left(\|\partial_{i}u_{0}\|_{L^{2}}^{2} + \|\partial_{i}\omega_{0}\|_{L^{2}}^{2} \right).$$
(2.2)

By using (2.2), it yields

$$\begin{split} \int_{0}^{t} \|u(\cdot,s)\|_{L^{4}}^{6} ds &\leq C \int_{0}^{t} \|\partial_{1}u(\cdot,s)\|_{L^{2}}^{\frac{4}{3}} \|\partial_{2}u(\cdot,s)\|_{L^{2}}^{\frac{4}{3}} \|\partial_{3}u(\cdot,s)\|_{L^{2}}^{\frac{4}{3}} ds \\ &\leq C \left(\sup_{0 \leq s \leq t} \|\partial_{1}u(\cdot,s)\|_{L^{2}}^{\frac{4}{3}} \|\partial_{2}u(\cdot,s)\|_{L^{2}}^{\frac{2}{3}} \right) \int_{0}^{t} \|\partial_{2}u(\cdot,s)\|_{L^{2}}^{\frac{2}{3}} \|\partial_{3}u(\cdot,s)\|_{L^{2}}^{\frac{4}{3}} ds \\ &\leq C \left(\sum_{i=1}^{2} \|\partial_{i}u\|_{L^{2}}^{2} \right) \int_{0}^{t} \|\nabla u(\cdot,s)\|_{L^{2}}^{2} ds \\ &\leq C \sum_{i=1}^{2} \left(\|\partial_{i}u_{0}\|_{L^{2}}^{2} + \|\partial_{i}\omega_{0}\|_{L^{2}}^{2} \right) \left(\|u_{0}\|_{L^{2}}^{2} + \|\omega_{0}\|_{L^{2}}^{2} \right) < \infty, \end{split}$$

where we have used the following interpolation inequality [1]:

 $\|f\|_{L^4} \le C \|\partial_1 f\|_{L^2}^{\frac{1}{3}} \|\partial_2 f\|_{L^2}^{\frac{1}{3}} \|\partial_3 f\|_{L^2}^{\frac{1}{3}}.$

Hence, by Lemma 1.2, we have proved that u, ω is a smooth solution. This completes the proof of Theorem 1.1.

Remark 2.1. It should be added that at the time the paper was accepted, the authors learnt that Y. Wang and L. Gu [7] have also obtained a similar result for the three dimensional magneto-micropolar fluid equations for a family of large initial data with finite energy.

3. Acknowledgments

Part of the work was carried out while S. Gala was a long-term visitor at the University of Catania. The hospitality of Catania University is graciously acknowledged. The paper is partially supported by PRIN 2017 n.2017AYM8XW004. Research of M.A. Ragusa is partially supported by the RUDN University Strategic Academic Leadership Program.

References

- [1] R.A. Adams and J.J. Fournier, Sobolev spaces, 2nd Ed. Academic Press, New York, 2003.
- [2] A. C. Eringen, Theory of micropolar fluids. J. Math. Mech. 16 (1966), 1-18.
- [3] G. Galdi and S. Rionero, A note on the existence and uniqueness of solutions of micropolar fluid equations, Int. J. Engrg. Sci. 14 (1977) 105-108.
- [4] G. Lukaszewicz, Micropolar fluids. Theory and applications. Modeling and Simulation in Science, Engineering and Technology. Birkhauser Boston, Inc., Boston, MA, 1999.
- [5] G. Lukaszewicz, On the existence, uniqueness and asymptotic properties for solutions of flows of asymmetric fluids. Rendiconti della Accademia Nazionale delle Scienze detta dei XL. Memorie di Matematica Serie V 1989; 13(1) :105-120, MR 91d:35174.Zbl 692.76020.
- [6] K.Y. Wang, On global regularity of incompressible Navier-Stokes equations in R³, Commun. Pure Appl. anal. 8 (2009), 1067-1072.
- [7] Y. Wang and L. Gu, Global regularity of 3D magneto-micropolar fluid equations, Appl. math. Lett. 99 (2020), DOI: 10.1016/j.aml.2019.07.011.
- [8] N. Yamaguchi, Existence of global strong solution to the micropolar fluid system in a bounded domain, Math. Meth. Appl. Sci. 28 (2005), 1507-1526.