

Searching for very-high-energy electromagnetic counterparts to gravitational-wave events with the Cherenkov Telescope Array

Barbara Patricelli,^{a,b,*} Alessandro Carosi,^c Lara Nava,^d Monica Seglar-Arroyo,^e Fabian Schüssler,^f Antonio Stamerra,^b Andrea Adelfio,^g Halim Ashkar,^f Andrea Bulgarelli,^h Tristano Di Girolamo,ⁱ Ambra Di Piano,^h Thomas Gasparetto,^g Jarred Green,^b Francesco Longo,^g Ivan Agudo,^j Alessio Berti,^k Elisabetta Bissaldi,^l Giancarlo Cella,^m Antonio Circiello,ⁱ Stefano Covino,^d Giancarlo Ghirlanda,^d Brian Humensky,ⁿ Susumu Inoue,^o Julien Lefaucheur,^p Miroslav Filipovic,^q Massimiliano Razzano,^{r,m} Deivid Ribeiro,ⁿ Olga Sergijenko,^s Giulia Stratta,^h and Susanna Vergani^p
on behalf of the CTA Consortium

(a complete list of authors can be found at the end of the proceedings)

^aEuropean Gravitational Observatory, Via E Amaldi, I- 56021 Cascina (Pisa), Italy

^bINAF - Osservatorio Astronomico di Roma, Via Frascati 33, I-00078 Monte Porzio Catone (Rome), Italy

^cUniversity of Geneva - Département de physique nucléaire et corpusculaire, 24 rue du Général-Dufour, 1211 Genève 4, Switzerland

^dINAF-Osservatorio Astronomico di Brera, Via E. Bianchi 46, I-23807 Merate (LC), Italy

^eLAPP, Univ. Grenoble Alpes, Univ. Savoie Mont Blanc, CNRS-IN2P3, 9 Chemin de Bellevue - BP 110, 74941 Annecy Cedex, France

^fIRFU, CEA, Université Paris-Saclay, Bât 141, 91191 Gif-sur-Yvette, France

^gINFN Sezione di Trieste and Università degli Studi di Trieste, Via Valerio 2 I-34127 Trieste, Italy

^hINAF - Osservatorio di Astrofisica e Scienza dello spazio di Bologna, Via Piero Gobetti 9 3/3, I-40129 Bologna, Italy

ⁱINFN Sezione di Napoli and Università degli Studi di Napoli "Federico II", Complesso Universitario di Monte S. Angelo, Via Cintia, I-80126 Napoli, Italy

^jInstituto de Astrofísica de Andalucía-CSIC, Glorieta de la Astronomía s/n, 18008, Granada, Spain

^kINFN Sezione di Torino, Via P. Giuria 1, I-10125 Torino, Italy

^lINFN Sezione di Bari and Politecnico di Bari, via Orabona 4, I-70124 Bari, Italy

^mINFN - Sezione di Pisa, Largo B. Pontecorvo 3, I-56127 Pisa, Italy

ⁿDepartment of Physics, Columbia University, 538 West 120th Street, New York, NY 10027, USA

^oRIKEN, Institute of Physical and Chemical Research, 2-1 Hirosawa, Wako, Saitama, 351-0198, Japan

^pLUTH, GEPI and LERMA, Observatoire de Paris, CNRS, PSL University, 5 place Jules Janssen, 92190, Meudon, France

^qWestern Sydney University, Locked Bag 1797, Penrith, NSW 2751, Australia

^rDipartimento di Fisica, Università di Pisa, Largo B. Pontecorvo 3, I-56127 Pisa, Italy

*Presenter

^s*Astronomical Observatory of Taras Shevchenko National University of Kyiv, 3 Observatorna Street, Kyiv, 04053, Ukraine*

E-mail: barbara.patricelli@inaf.it

The detection of electromagnetic (EM) emission following the gravitational wave (GW) event GW170817 opened the era of multi-messenger astronomy with GWs and provided the first direct evidence that at least a fraction of binary neutron star (BNS) mergers are progenitors of short Gamma-Ray Bursts (GRBs). GRBs are also expected to emit very-high energy (VHE, > 100 GeV) photons, as proven by the recent MAGIC and H.E.S.S. observations. One of the challenges for future multi-messenger observations will be the detection of such VHE emission from GRBs in association with GWs. In the next years, the Cherenkov Telescope Array (CTA) will be a key instrument for the EM follow-up of GW events in the VHE range, owing to its unprecedented sensitivity, rapid response, and capability to monitor a large sky area via scan-mode operation. We present the CTA GW follow-up program, with a focus on the searches for short GRBs possibly associated with BNS mergers. We investigate the possible observational strategies and we outline the prospects for the detection of VHE EM counterparts to transient GW events.

1. Introduction

The joint observation of gravitational waves (GWs) from the binary neutron star (BNS) merger GW170817 [1] by Advanced LIGO [2] and Advanced Virgo [3] and of the short Gamma-Ray Burst GRB 170817A by *Fermi*-GBM [4] and INTEGRAL [5] marked the beginning of multi-messenger astronomy with GWs and provided the first direct evidence that at least a fraction of BNS mergers are progenitors of short GRBs [6]. The intense electromagnetic (EM) follow-up campaign performed after this joint detection also allowed to detect an optical/infrared counterpart to the GW event (the kilonova), hosted in the galaxy NGC 4993; X-ray and radio counterparts have also been observed, and later identified as the GRB afterglow emission (see [7] and references therein). GRBs are also known to emit very-high-energy (VHE, $E > 100$ GeV) photons, as shown by the observations of GRB 190114C and GRB 160821B by MAGIC [8, 9] and GRB 180720B and GRB 190829A by H.E.S.S. [10, 11]. A VHE EM follow-up of GW170817 was performed by H.E.S.S., that started the observations 5.3 hr after the GW event, but no EM counterpart was found [12]. A search for a possible VHE EM counterparts has been performed also with HAWC, whose observations started ~ 8 hr after GW170817, but no significant gamma-ray emission was found [13].

In the coming years, the Cherenkov Telescope Array (CTA, [14]) will play a fundamental role in the follow-up of GWs at VHE, thanks to its unprecedented sensitivity, its rapid slewing capabilities, and its large field-of-view (FOV). CTA will be composed of two arrays, one in the northern hemisphere and one in the southern hemisphere, which together will provide full-sky coverage; it will be an order of magnitude more sensitive and will have a greater energy coverage (from a few tens of GeV to above 100 TeV) with respect to current Imaging Atmospheric Cherenkov Telescopes (IACTs). The two arrays will consist of a combination of large (LST), medium (MST) and small (SST) size telescopes, covering different energy ranges: 20 GeV - 150 GeV, 150 GeV - 5 TeV and 5 TeV - 300 TeV, respectively. In the scheme of the CTA Key Science Project on transients, GW transient events are ranked as the highest priority ones to be studied [15]. As a result, the GW follow-up strategies with CTA, also investigated in previous studies (see, e.g. 16–20), are currently being defined.

In this paper, we present the EM follow-up program proposed for CTA and investigate the capability of CTA to detect VHE EM counterparts to GW transient events, based on detailed simulations of BNS mergers accompanied by short GRBs.

2. The population of astrophysical sources

To investigate the capability of CTA to follow-up GW transient events and detect possible VHE EM counterparts, we simulate a catalog of short GRBs associated with GW signals from BNS mergers. This catalog of simulated BNS mergers and their GW detection was produced in expectation of the fourth observing run of current GW detectors (O4). Available in the public database GWCOSMoS [21], the catalog is based on the work by [16, 22]. It has been built starting from a simulated, realistic ensemble of BNS merging systems evenly distributed in space up to a maximum distance of 500 Mpc, and contains only the events expected to be detected by Advanced LIGO and Advanced Virgo in O4; for these events, the 2-dimensional GW skymaps are also available. We associate VHE emission to each simulated BNS merger, adopting the following

empirical approach. According to the few available detections of VHE radiation from long GRBs [8, 10, 11], the VHE lightcurve looks similar to the soft X-ray lightcurve in terms of luminosity and temporal behaviour. Time-resolved spectral analysis of the brightest VHE event, GRB 190114C, showed that the spectra are consistent with a power law (PL) with photon index $\alpha \sim -2.2$ with no strong evidence for temporal evolution [8]. Assuming that short GRBs also produce VHE radiation similarly to long GRBs (see [9]), we simulate its temporal and spectral properties as follows. Each BNS merger is assumed to successfully launch a relativistic jet, whose isotropic equivalent prompt emission energy E_{iso} follows the E_{iso} distribution of short GRBs derived in [25]. The afterglow X-ray luminosity at 11 h is assigned by adopting the $E_{\text{iso}} - L_{X,11\text{h}}$ correlation found for short GRBs in [26]. We then assume $L_{\text{VHE},11\text{h}} \sim L_{X,11\text{h}}$, allowing for a dispersion of 0.3 dex. The full VHE lightcurve is built by assuming that it decays as a PL with an index extracted from the distribution of decay indices of X-ray afterglows of short GRBs; considering a sample of 22 short GRBs, we find that this distribution is well described by a Gaussian function with mean value $\langle \alpha_2 \rangle = -1.45$ and $\sigma_{\alpha_2} = 0.48$. The initial Lorentz factor, assigned from a lognormal distribution centered around ~ 200 , determines the lightcurve peak time. Before the peak time, the light curve rises as $L_{\text{VHE}} \propto t^2$. The off-axis lightcurve at viewing angle θ_{view} is calculated following [28] and [29], and adopting a structured (Gaussian) jet with opening angle of the core taken from the distribution inferred in [27].

3. CTA observations: exposure time versus latency time

The VHE EM emission is expected to start shortly after the BNS merger, but the starting time of the EM follow-up observations typically doesn't coincide with the onset of the GRB emission. This is due to several factors: i) the latency needed to send the GW alert to astronomers (during the third observing run of Advanced LIGO and Advanced Virgo the typical latency was of the order of minutes, see <https://gracedb.ligo.org/superevents/public/03/>, but in the future the latency could be shorter, see https://emfollow.docs.ligo.org/userguide/early_warning.html); ii) the time needed to point the telescopes in the region of the sky of interest (for instance, the slewing time of the LSTs is 30 s); iii) the uncertainty in the sky location of the GW event, that is typically of the order of tens/hundreds of square degrees (see, e.g., [23]). This last point means that several consecutive pointings are needed to cover the GW localization region, and subsequently to pinpoint the sky location of the GRB (see, e.g., [16]). As a consequence, the exposure time needed to eventually detect the source can also vary, depending on the GRB luminosity and on the shape of its light curve.

As a first step for our investigations, we estimate the exposure time needed to detect the GRBs in our simulated catalog with CTA as a function of the latency t_0 from the onset of the GRB emission and the starting of the observation of the sky region containing the source. Specifically, following the approach used in [16], we estimate the exposure time needed to detect the source (T_{exp}) as the time required to make a 5σ detection, i.e. the time such that the following condition is fulfilled:

$$\int_{t_0}^{t_0+T_{\text{exp}}} F(t) dt \geq F_{5\sigma}^S(T_{\text{exp}}), \quad (1)$$

where $F(t)$ is the GRB flux and $F_{5\sigma}^S(T_{\text{exp}})$ is the minimum fluence detectable by CTA for the exposure time T_{exp} at a 5σ significance level. This last term is computed for different exposure

times using the `ctools`¹ function `cssens`, with the Instrument Response Functions (IRFs) computed by the CTA consortium from detailed Monte Carlo simulations, in the so-called “Production 3” [24]. The IRFs for the two arrays² “North_0.5h” and “South_0.5h” have been generated by assuming a 30-minute observation of a point source situated at zenith angle 20° . We assumed an offset between the position of the source and the center of the FOV of 1° .

Figure 1 shows the percentage of GRBs that could be detected by CTA for different exposure times, as a function of t_0 , for GRBs seen at a viewing angle $\theta_{\text{view}} < 10^\circ$ (these are mostly on-axis GRBs) and GRBs seen at $\theta_{\text{view}} < 45^\circ$. When considering only on-axis GRBs and $t_0 \sim 10$ min, $\sim 92\%$ of the sources can be detected with T_{exp} of the order of a few hours, by either CTA North or South alone; when considering a shorter delay of $t_0 \sim 30$ s, $\sim 94\%$ of the sources can be detected with $T_{\text{exp}} \leq 30$ minutes. When including off-axis GRBs for which $\theta_{\text{view}} < 45^\circ$, $\sim 54\%$ of the sources can be detected within a few hours, considering $t_0 \sim 10$ min; with the shorter delay $t_0 \sim 30$ s, $\sim 52\%$ of these sources can be detected with $T_{\text{exp}} \leq 30$ minutes.

4. The CTA observational strategy

The larger uncertainties on the source localization in GW events add an extra layer of complexity to the EM follow-up, i.e. to have a detection, the GW skymap region needs to be covered first. With the goal of studying the prospects for CTA and understanding how to maximise the chances of detecting a source, we study the most optimistic scenario: that is, to know *a priori* the spectral and temporal evolution of the GRB, so the derived observation scheduling is optimal for each source (see, e.g., [16]). Then, by scanning the parameter space, we can derive the strategy which presents the best compromise for the input population described in Section 2.

4.1 EM follow-up observations: the scheduler

Several observation scheduling algorithms have been developed to derive optimal pointing patterns which cover the largest total GW uncertainty region possible, an approach based on [30]. These algorithms are part of realistic observation scheduling simulations, which include the consideration of visibility conditions of both the North and South sites, i.e. darkness and moonlight conditions for each GW alert time. Other optimizations are performed regarding the prioritization of observations in low zenith angle conditions in order to achieve lower energy thresholds during observations.

Whereas in [20] the main characteristics of this scheduler were introduced, we went a step further with these realistic simulations by considering the connection between the zenith angle evolution of the source, the computation of the exposure time from Eq. 1, and the probability coverage maximisation in each iteration of the scheduler. This means that we are maximising our chances to detect the source, since the selected region is defined as being the one which encloses the highest GW source sky-position probability in each iteration of the observation strategy. The exposure is selected following Eq. 1 while considering zenith angle evolution as well, which is key for long exposure times.

¹<http://cta.irap.omp.eu/ctools/>; in this work we used the version 1.6.3.

²In this work we considered the baseline array layouts: <https://www.cta-observatory.org/science/cta-performance/>.

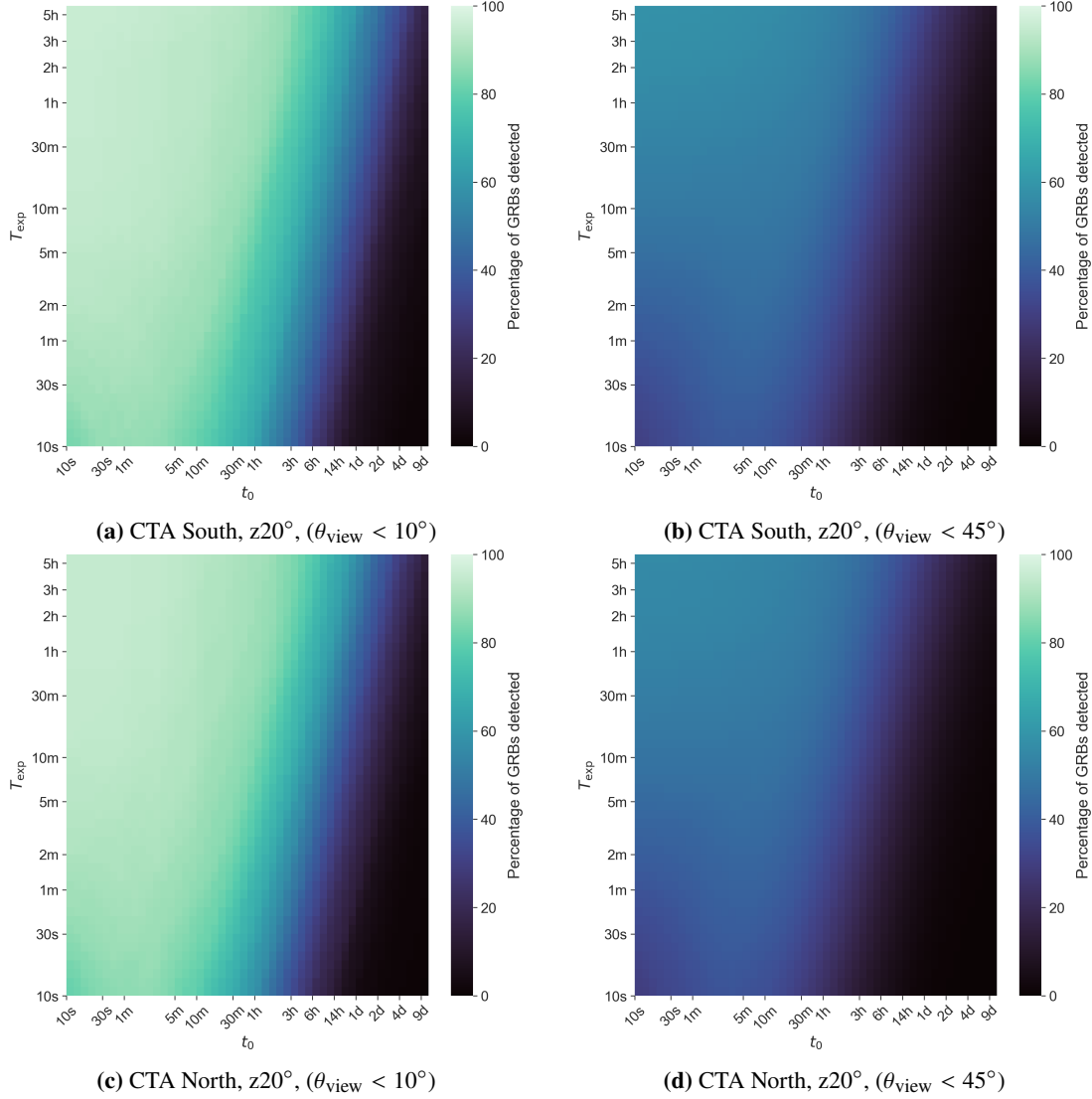


Figure 1: Percentage of short GRBs with $\theta_{\text{view}} < 10^{\circ}$ (left panels) and $\theta_{\text{view}} < 45^{\circ}$ (right panels) detected with CTA South (upper panels) and North (lower panels) with a given exposure time as a function of the delay time from the onset of the GRB emission and the starting of the observation of the sky region containing the source. A zenith angle of 20° has been assumed for all the GRBs.

5. A test case

The complete algorithm described in Subsection 4.1 is currently being used to investigate the GRB catalog associated with the simulated GW events from the GWCOSMoS database. Here we show one example corresponding to a simulated BNS merger located at a distance of ~ 270 Mpc and whose GW sky localization area³ is ~ 40 deg²; the associated GRB is on-axis.

The injection time is 2016-04-15 00:15:30 UTC and has been selected so that the observations can be scheduled by at least one site, in this case CTA North. Four observations are scheduled,

³Here we refer to the 90% credible region, i.e., the area enclosing 90% of the total posterior GW probability.

covering a 92% of the uncertainty region in the localization of the source (see Fig. 2). For this simulation, we consider the latency of the arrival of the GW alert to be 210 seconds, and the slewing time of the telescopes to be 30 seconds. The inter-slewing time to reach each position and the start of data acquisition between observations are estimated to be of 20 seconds. Thanks to this observation strategy, the source is covered and detected twice, in the first and third observation.

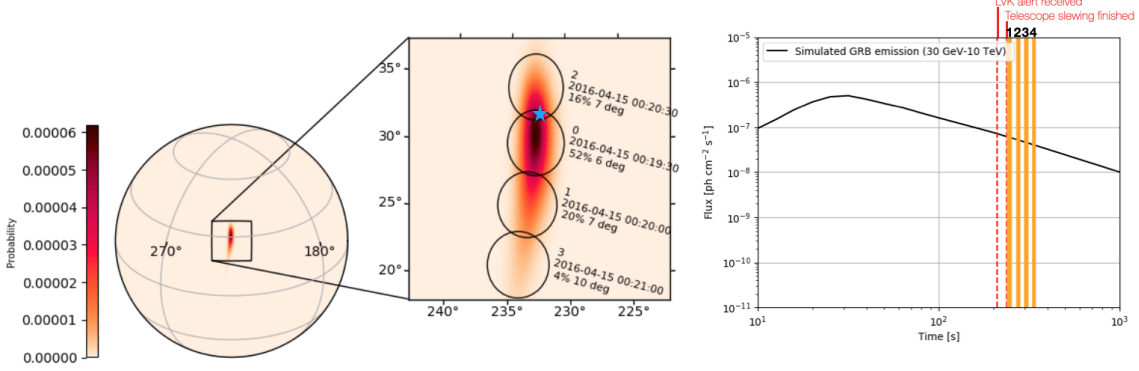


Figure 2: Observational scheduling of the test case from the GWCOSMoS catalog, for which four observations are scheduled and total of 92 % of the uncertainty region is covered. The blue star marks the sky location of the BNS merger. For each observation, we quote the number, the time, the % uncertainty region covered and the zenith angle. The exposure times are selected such that a 5σ detection is achieved, which in this case correspond to $T_{\text{exp}} = 10$ s for all four observations. The injection time is 2016-04-15 00:15:30 UTC and CTA-North is selected due to the 90% C.R. region. A total of 210 seconds are considered as latency for the GW alert to be received, 30 seconds for the first slewing of the telescopes, and 20 seconds for the final slewing before starting data acquisition. The simulated observation schedule is overlaid on the lightcurve of the test case GRB. We assumed a conservative FOV of 2.5° (see [20]).

6. Conclusions

We have presented a study on the capability of CTA to detect VHE EM counterparts to GWs and discussed the possible observational strategies to follow-up GW transient events. We have shown that CTA represents a promising instrument to identify the VHE emission from GRBs associated with BNS mergers. Detailed estimates of the joint GW and VHE EM detection rates will be presented in a future work.

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Full Authors List: CTA Consortium

H. Abdalla¹, H. Abe², S. Abe², A. Abusleme³, F. Acero⁴, A. Acharyya⁵, V. Acín Portella⁶, K. Ackley⁷, R. Adam⁸, C. Adams⁹, S.S. Adhikari¹⁰, I. Aguado-Ruesga¹¹, I. Agudo¹², R. Aguilera¹³, A. Aguirre-Santaella¹⁴, F. Aharonian¹⁵, A. Alberdi¹², R. Alfaro¹⁶, J. Alfaro³, C. Alispach¹⁷, R. Aloisio¹⁸, R. Alves Batista¹⁹, J.-P. Amans²⁰, L. Amati²¹, E. Amato²², L. Ambrogio¹⁸, G. Ambrosi²³, M. Ambrosio²⁴, R. Ammendola²⁵, J. Anderson²⁶, M. Anduze⁸, E.O. Angüner²⁷, L.A. Antonelli²⁸, V. Antonuccio²⁹, P. Antoranz³⁰, R. Anutarawiramkul³¹, J. Aragunde Gutierrez³², C. Aramo²⁴, A. Araudo^{33,34}, M. Araya³⁵, A. Arbet-Engels³⁶, C. Arcaro¹, V. Arendt³⁷, C. Armand³⁸, T. Armstrong²⁷, F. Arqueros¹¹, L. Arrabito³⁹, B. Arsoli⁴⁰, M. Artero⁴¹, K. Asano², Y. Ascasíbar¹⁴, J. Aschersleben⁴², M. Ashley⁴³, P. Attinà⁴⁴, P. Aubert⁴⁵, C. B. Singh¹⁹, D. Baack⁴⁶, A. Babic⁴⁷, M. Backes⁴⁸, V. Baena¹³, S. Bajtlik⁴⁹, A. Baktash⁵⁰, C. Balazs⁷, M. Balbo³⁸, O. Ballester⁴¹, J. Ballet⁴, B. Balmaverde⁴⁴, A. Bamba⁵¹, R. Bandiera²², A. Baquero Larriva¹¹, P. Barai¹⁹, C. Barbier⁴⁵, V. Barbosa Martins⁵², M. Barcelo⁵³, M. Barkov⁵⁴, M. Barnard¹, L. Baroncelli²¹, U. Barres de Almeida⁴⁰, J.A. Barrio¹¹, D. Bastieri⁵⁵, P.I. Batista⁵², I. Batkovic⁵⁵, C. Bauer⁵³, R. Bautista-González⁵⁶, J. Baxter², U. Becciani²⁹, J. Becerra González³², Y. Beckerini⁵⁷, G. Beck⁵⁸, J. Becker Tjus⁵⁹, W. Bednarek⁶⁰, A. Belfiore⁶¹, L. Bellizzi⁶², R. Belmont⁴, W. Benbow⁶³, D. Berge⁵², E. Bernardini⁵², M.I. Bernardos⁵⁵, K. Bernlöhr⁵³, A. Berti⁶⁴, M. Berton⁶⁵, B. Bertucci²³, V. Beshley⁶⁶, N. Bhatt⁶⁷, S. Bhattacharyya⁶⁷, W. Bhattacharyya⁵², S. Bhattacharyya⁶⁸, B. Bi⁶⁹, G. Bicknell⁷⁰, N. Biederbeck⁴⁶, C. Bigongiari²⁸, A. Biland³⁶, R. Bird⁷¹, E. Bissaldi⁷², J. Biteau⁷³, M. Bitossi⁷⁴, O. Blanch⁴¹, M. Blank⁵⁰, J. Blazek³³, J. Bobin⁷⁵, C. Boccato⁷⁶, F. Bocchino⁷⁷, C. Boehm⁷⁸, M. Bohacova³³, C. Boisson²⁰, J. Boix⁴¹, J.-P. Bolle⁵², J. Bolmont⁷⁹, G. Bonanno²⁹, C. Bonavolontà²⁴, L. Bonneau Arbeleche⁸⁰, G. Bonnoli¹², P. Bordes⁸¹, J. Borkowski⁴⁹, S. Bórquez³⁵, R. Bose⁸², D. Bose⁸³, Z. Bosnjak⁴⁷, E. Bottacini⁵⁵, M. Böttcher¹, M.T. Botticella⁸⁴, C. Boutonnet⁸⁵, F. Bouyouf⁷⁵, V. Bozhilov⁸⁶, E. Bozzo³⁸, L. Brahimi³⁹, C. Braiding⁴³, S. Brau-Nogue⁸⁷, S. Breen⁷⁸, J. Bregeon³⁹, M. Breuhaus⁵³, A. Brill⁹, W. Bricken⁸⁸, E. Brocato²⁸, A.M. Brown⁵, K. Brügge⁴⁶, P. Brun⁸⁹, P. Brun⁸⁹, F. Brun⁸⁹, L. Brunetti⁴⁵, G. Brunetti⁹⁰, P. Bruno²⁹, A. Bruno⁹¹, A. Bruzzese⁶, N. Bucciantini²², J. Buckley⁸², R. Bühler⁵², A. Bulgarelli²¹, T. Bulik⁹², M. Bünning⁵², M. Bunse⁴⁶, M. Burton⁹³, A. Burtovoi⁷⁶, M. Buscemi⁹⁴, S. Buschjäger⁴⁶, G. Busetto⁵⁵, J. Buss⁴⁶, K. Byrum²⁶, A. Caccianiga⁹⁵, F. Cadoux¹⁷, A. Calanducci²⁹, C. Calderón³, J. Calvo Tovar³², R. Cameron⁹⁶, P. Campaña³⁵, R. Canestrari⁹¹, F. Cangemi⁷⁹, B. Cantlay³¹, M. Capalbi⁹¹, M. Capasso⁹, M. Cappi²¹, A. Caproni⁹⁷, R. Capuzzo-Dolcetta²⁸, P. Caraveo⁶¹, V. Cárdenas⁹⁸, L. Cardiel⁴¹, M. Cardillo⁹⁹, C. Carlile¹⁰⁰, S. Caroff⁴⁵, R. Carosi⁷⁴, A. Carosi¹⁷, E. Carquín³⁵, M. Carrère³⁹, J.-M. Casandjian⁴, S. Casanova^{101,53}, E. Cascone⁸⁴, F. Cassol²⁷, A.J. Castro-Tirado¹², F. Catalani¹⁰², O. Catalano⁹¹, D. Cauz¹⁰³, A. Ceccanti⁶⁴, C. Celestino Silva⁸⁰, S. Celli¹⁸, K. Cerny¹⁰⁴, M. Cerruti⁸⁵, E. Chabanne⁴⁵, P. Chadwick⁵, Y. Chai¹⁰⁵, P. Chambery¹⁰⁶, C. Champion⁸⁵, S. Chandra¹, S. Chaty⁴, A. Chen⁵⁸, K. Cheng², M. Chernyakova¹⁰⁷, G. Chiaro⁶¹, A. Chiavassa^{64,108}, M. Chikawa², V.R. Chitnis¹⁰⁹, J. Chudoba³³, L. Chytka¹⁰⁴, S. Cikota⁴⁷, A. Circiello^{24,110}, P. Clark⁵, M. Çolak⁴¹, E. Colombo³², J. Colome¹³, S. Colonges⁸⁵, A. Comastri²¹, A. Compagnino⁹¹, V. Conforti²¹, E. Congiu⁹⁵, R. Coniglione⁹⁴, J. Conrad¹¹¹, F. Conte⁵³, J.L. Contreras¹¹, P. Coppi¹¹², R. Cornat⁸, J. Coronado-Blazquez¹⁴, J. Cortina¹¹³, A. Costa²⁹, H. Costantini²⁷, G. Cotter¹¹⁴, B. Courty⁸⁵, S. Covino⁹⁵, S. Crestan⁶¹, P. Cristofari²⁰, R. Crocker⁷⁰, J. Croston¹¹⁵, K. Cubuk⁹³, O. Cuevas⁹⁸, X. Cui², G. Cusumano⁹¹, S. Cutini²³, A. D'Ài⁹¹, G. D'Amico¹¹⁶, F. D'Ammando⁹⁰, P. D'Avanzo⁹⁵, P. Da Vela⁷⁴, M. Dadaña²¹, S. Dai¹¹⁷, M. Dalchenko¹⁷, M. Dall'Orta⁸⁴, M.K. Daniel⁶³, J. Dauguet⁸⁵, I. Davids⁴⁸, J. Davies¹¹⁴, B. Dawson¹¹⁸, A. De Angelis⁵⁵, A.E. de Araújo Carvalho⁴⁰, M. de Bony de Lavergne⁴⁵, V. De Caprio⁸⁴, G. De Cesare²¹, F. De Frondat²⁰, E.M. de Gouveia Dal Pino¹⁹, I. de la Calle¹¹, B. De Lotto¹⁰³, A. De Luca⁶¹, D. De Martino⁸⁴, R.M. de Menezes¹⁹, M. de Naurois⁸, E. de Oña Wilhelmi¹³, F. De Palma⁶⁴, F. De Persio¹¹⁹, N. de Simone⁵², V. de Souza⁸⁰, M. Del Sant⁹¹, M.V. del Valle¹⁹, E. Delagnes⁷⁵, G. Deleglise⁴⁵, M. Delfino Reznicek⁶, C. Delgado¹¹³, A.G. Delgado Giler⁸⁰, J. Delgado Mengual⁶, R. Della Ceca⁹⁵, M. Della Valle⁸⁴, D. della Volpe¹⁷, D. Depaoli^{64,108}, D. Depouez²⁷, J. Devin⁸⁵, T. Di Girolamo^{24,110}, C. Di Giulio²⁵, A. Di Piano²¹, F. Di Piero⁶⁴, L. Di Venere¹²⁰, C. Díaz¹¹³, C. Díaz-Bahamondes³, C. Dib³⁵, S. Diebold⁶⁹, S. Digel⁹⁶, R. Dimas⁵⁵, A. Djannati-Ataï⁸⁵, J. Djuvsland¹¹⁶, A. Dmytriiev²⁰, K. Docher⁹, A. Domínguez¹¹, D. Dominis Prester¹²¹, A. Donath⁵³, A. Donini⁴¹, D. Dorner¹²², M. Doró⁵⁵, R.d.C. dos Anjos¹²³, J.-L. Dournaux²⁰, T. Downes¹⁰⁷, G. Drake²⁶, H. Drass³, D. Dravins¹⁰⁰, C. Duangchan³¹, A. Duara¹²⁴, G. Dubus¹²⁵, L. Ducci⁶⁹, C. Duffy¹²⁴, D. Dumora¹⁰⁶, K. Dundas Morá¹¹¹, A. Durkalec¹²⁶, V.V. Dwarkadas¹²⁷, J. Ebr³³, C. Eckner⁴⁵, J. Eder¹⁰⁵, A. Ederoclite¹⁹, E. Edy⁸, K. Egberts¹²⁸, S. Einecke¹¹⁸, J. Eisch¹²⁹, C. Eleftheriadis¹³⁰, D. Elsässer⁴⁶, G. Emery¹⁷, D. Emmanoulopoulos¹¹⁵, J.-P. Ernenwein²⁷, M. Errando⁸², P. Escarate³⁵, J. Escudero¹², C. Espinoza³, S. Etorri²¹, A. Eungwanichayapant³¹, P. Evans¹²⁴, C. Evoli¹⁸, M. Fairbairn¹³¹, D. Falcata-Goncalves¹³², A. Falcone¹³³, V. Fallah Ramazani⁶⁵, R. Falomo⁷⁶, K. Farakos¹³⁴, G. Fasola²⁰, A. Fattorini⁴⁶, Y. Favre¹⁷, R. Fedora¹³⁵, E. Fedorova¹³⁶, S. Fegan⁸, K. Feijen¹¹⁸, Q. Feng⁹, G. Ferrand⁵⁴, G. Ferrara⁹⁴, O. Ferreira⁸, M. Fesquet⁷⁵, E. Fiandrini²³, A. Fiasson⁴⁵, M. Filipovic¹¹⁷, D. Fink¹⁰⁵, J.P. Finley¹³⁷, V. Fioretti²¹, D.F.G. Fiorillo^{24,110}, M. Fiorini⁶¹, S. Flis⁵², H. Flores²⁰, L. Foffano¹⁷, C. Föhr⁵³, M.V. Fonseca¹¹, L. Font¹³⁸, G. Fontaine⁸, O. Fornieri⁵², P. Fortin⁶³, L. Fortson⁸⁸, N. Fouque⁴⁵, A. Fournier¹⁰⁶, B. Fraga⁴⁰, A. Franceschini⁷⁶, F.J. Franco³⁰, A. Franco Ordovas³², L. Freixas Coromina¹¹³, L. Fresnillo³⁰, C. Fruck¹⁰⁵, D. Fugazza⁹⁵, Y. Fujikawa¹³⁹, Y. Fujita², S. Fukami², Y. Fukazawa¹⁴⁰, Y. Fukui¹⁴¹, D. Fulla⁵², S. Funk¹⁴², A. Furniss¹⁴³, O. Gabella³⁹, S. Gabici⁸⁵, D. Gaggero¹⁴, G. Galanti⁶¹, G. Galaz³, P. Galdemard¹⁴⁴, Y. Gallant³⁹, D. Galloway⁷, S. Gallozzi²⁸, V. Gammaldi¹⁴, R. Garcia⁴¹, E. Garcia⁴⁵, E. García¹³, R. Garcia López³², M. Garczarzyk⁵², F. Gargano¹²⁰, C. Gargano⁹¹, S. Garozzo²⁹, D. Gascon⁸¹, T. Gasparetto¹⁴⁵, D. Gasparrini²⁵, H. Gasparyan⁵², M. Gaug¹³⁸, N. Geffroy⁴⁵, A. Gent¹⁴⁶, S. Germani⁷⁶, L. Gesa¹³, A. Ghalumyan¹⁴⁷, A. Ghedina¹⁴⁸, G. Ghirlanda⁹⁵, F. Gianotti²¹, S. Giarrusso⁹¹, M. Giarrusso⁹⁴, G. Giavitto⁵², B. Giebels⁸, N. Giglietto⁷², V. Gika¹³⁴, F. Gillardo⁴⁵, R. Gimenes¹⁹, F. Giordano¹⁴⁹, G. Giovannini⁹⁰, E. Giro⁷⁶, M. Giroletti⁹⁰, A. Giuliani⁶¹, L. Giunti⁸⁵, M. Gjata⁹, J.-F. Glicenstein⁸⁹, P. Gliwny⁶⁰, N. Godinovic¹⁵⁰, H. Göksu⁵³, P. Goldoni⁸⁵, J.L. Gómez¹², G. Gómez-Vargas³, M.M. González¹⁶, J.M. González¹⁵¹, K.S. Gothe¹⁰⁹, D. Götz⁴, J. Goulart Coelho¹²³, K. Gourgouliaos⁹, T. Grabarczyk¹⁵², R. Gracián⁸¹, P. Grandi²¹, G. Grasseau⁸, D. Grasso⁷⁴, A.J. Green⁷⁸, D. Green¹⁰⁵, J. Green²⁸, T. Greenshaw¹⁵³, I. Grenier⁴, P. Grespan⁵⁵, A. Grillo²⁹, M.-H. Grondin¹⁰⁶, J. Grube¹³¹, V. Guarino²⁰, B. Guest³⁷, O. Gueta⁵², M. Gündüz⁵⁹, S. Gunji¹⁵⁴, A. Gusdorf²⁰, G. Gyuk¹⁵⁵, J. Hackfeld⁵⁹, D. Hadasch², J. Haga¹³⁹, L. Hagge⁵², A. Hahn¹⁰⁵, J.E. Hajlaoui⁸⁵, H. Hakobyan³⁵, A. Halim⁸⁹, P. Hamal³³, W. Hanlon⁶³, S. Hara¹⁵⁶, Y. Harada¹⁵⁷, M.J. Hardcastle¹⁵⁸, M. Harvey⁵,

K. Hashiyama², T. Hassan Collado¹¹³, T. Haubold¹⁰⁵, A. Haupt⁵², U.A. Hautmann¹⁵⁹, M. Havelka³³, K. Hayashi¹⁴¹, K. Hayashi¹⁶⁰, M. Hayashida¹⁶¹, H. He⁵⁴, L. Heckmann¹⁰⁵, M. Heller¹⁷, J.C. Helo³⁵, F. Henault¹²⁵, G. Henri¹²⁵, G. Hermann⁵³, R. Herndl⁴⁵, S. Hernández Cadena¹⁶, J. Herrera Lorente³², A. Herrero³², O. Hervet¹⁴³, J. Hinton⁵³, A. Hiramatsu¹⁵⁷, N. Hiroshima⁵⁴, K. Hirotani², B. Hnatyk¹³⁶, R. Hnatyk¹³⁶, J.K. Hoang¹¹, D. Hoffmann²⁷, W. Hofmann⁵³, C. Hoischen¹²⁸, J. Holder¹⁶², M. Holler¹⁶³, B. Hona¹⁶⁴, D. Horan⁸, J. Hörandel¹⁶⁵, D. Horns⁵⁰, P. Horvath¹⁰⁴, J. Houles²⁷, T. Hovatta⁶⁵, M. Hrabovsky¹⁰⁴, D. Hrupec¹⁶⁶, Y. Huang¹³⁵, J.-M. Huet²⁰, G. Hughes¹⁵⁹, D. Hui², G. Hull⁷³, T.B. Humensky⁹, M. Hütten¹⁰⁵, R. Iaria⁷⁷, M. Iarlori¹⁸, J.M. Illa⁴¹, R. Imazawa¹⁴⁰, D. Impiombato⁹¹, T. Inada², F. Incardona²⁹, A. Ingallinera²⁹, Y. Inoue², S. Inoue⁵⁴, T. Inoue¹⁴¹, Y. Inoue¹⁶⁷, A. Insolia^{120,94}, F. Iocco^{24,110}, K. Ioka¹⁶⁸, M. Ionica²³, M. Iori¹¹⁹, S. Iovenitti⁹⁵, A. Iriarte¹⁶, K. Ishio¹⁰⁵, W. Ishizaki¹⁶⁸, Y. Iwamura², C. Jablonski¹⁰⁵, J. Jacquemier⁴⁵, M. Jacquemont⁴⁵, M. Jamroz¹⁶⁹, P. Jancek³³, F. Jankowsky¹⁷⁰, A. Jardin-Blicq³¹, C. Jarnot⁸⁷, P. Jean⁸⁷, I. Jiménez Martínez¹¹³, W. Jin¹⁷¹, L. Jocu¹²⁵, N. Jordana¹⁷², M. Josselin⁷³, L. Jouvin⁴¹, I. Jung-Richardt¹⁴², F.J.P.A. Junqueira¹⁹, C. Juramy-Gilles⁷⁹, J. Jurysek³⁸, P. Kaaret¹⁷³, L.H.S. Kadowaki¹⁹, M. Kagaya², O. Kalekin¹⁴², R. Kankanyan⁵³, D. Kantzas¹⁷⁴, V. Karas³⁴, A. Karastergiou¹¹⁴, S. Karkar⁷⁹, E. Kasai⁴⁸, J. Kasperek¹⁷⁵, H. Katagiri¹⁷⁶, J. Kataoka¹⁷⁷, K. Katarzyński¹⁷⁸, S. Katsuda¹⁷⁹, U. Katz¹⁴², N. Kawanaka¹⁸⁰, D. Kazanas¹³⁰, D. Kerszberg⁴¹, B. Khélifi⁸⁵, M.C. Kherlakian⁵², T.P. Kian¹⁸¹, D.B. Kieda¹⁶⁴, T. Kihm⁵³, S. Kim³, S. Kimeswenger¹⁶³, S. Kisaka¹⁴⁰, R. Kissmann¹⁶³, R. Kleijwegt¹³⁵, T. Kleiner⁵², G. Kluge¹⁰, W. Kluźniak⁴⁹, J. Knapp⁵², J. Knölseder⁸⁷, A. Kobakhidze⁷⁸, Y. Kobayashi², B. Koch³, J. Kocot¹⁵², K. Kohri¹⁸², K. Kokkotas⁶⁹, N. Komin⁵⁸, A. Kong², K. Kosack⁴, G. Kowal¹³², F. Krack⁵², M. Krause⁵², F. Krennrich¹²⁹, M. Krumholz⁷⁰, H. Kubo¹⁸⁰, V. Kudryavtsev¹⁸³, S. Kunwar⁵³, Y. Kuroda¹³⁹, J. Kushida¹⁵⁷, P. Kushwaha¹⁹, A. La Barbera⁹¹, N. La Palombara⁶¹, V. La Parola⁹¹, G. La Rosa⁹¹, R. Lahmann¹⁴², G. Lamanna⁴⁵, A. Lamastra²⁸, M. Landoni⁹⁵, D. Landriau⁴, R.G. Lang⁸⁰, J. Lapington¹²⁴, P. Laporte²⁰, P. Lason¹⁵², J. Lasui³⁷, J. Lazendic-Galloway⁷, T. Le Flour⁴⁵, P. Le Sidaner²⁰, S. Leach¹²⁴, A. Leckngam³¹, S.-H. Lee¹⁸⁰, W.H. Lee¹⁸⁰, S. Lee¹¹⁸, M.A. Leigui de Oliveira¹⁸⁴, A. Lemière⁸⁵, M. Lemoine-Goumard¹⁰⁶, J.-P. Lenain⁷⁹, F. Leone^{94,185}, V. Leray⁸, G. Leto²⁹, F. Leuschner⁶⁹, C. Levy^{79,20}, R. Lindemann⁵², E. Lindfors⁶⁵, L. Linhof⁴⁶, I. Liodakis⁶⁵, A. Lipniacka¹¹⁶, S. Lloyd⁵, M. Lobo¹¹³, T. Lohse¹⁸⁶, S. Lombardi²⁸, F. Longo¹⁴⁵, A. Lopez³², M. López¹¹, R. López-Coto⁵⁵, S. Loporchio¹⁴⁹, F. Louis⁷⁵, M. Louys²⁰, F. Lucarelli²⁸, D. Lucchesi⁵⁵, H. Ludwig Boudi³⁹, P.L. Luque-Escamilla⁵⁶, E. Lyard³⁸, M.C. Maccarone⁹¹, T. Maccarone¹⁸⁷, E. Mach¹⁰¹, A.J. Maciejewski¹⁸⁸, J. Mackey¹⁵, G.M. Madejski⁹⁶, P. Maeght³⁹, C. Maggio¹³⁸, G. Maieti⁵², A. Majczyna¹²⁶, P. Majumdar^{83,2}, M. Makariev¹⁸⁹, M. Mallamaci⁵⁵, R. Malta Nunes de Almeida¹⁸⁴, S. Maltezos¹³⁴, D. Malyshev¹⁴², D. Malyshev⁶⁹, D. Mandat³³, G. Maneva¹⁸⁹, M. Manganaro¹²¹, G. Manicò⁹⁴, P. Manigot⁸, K. Mannheim¹²², N. Maragos¹³⁴, D. Marano²⁹, M. Marconi⁸⁴, A. Marcowith³⁹, M. Marculewicz¹⁹⁰, B. Marčun⁶⁸, J. Marin⁹⁸, N. Marinello⁵⁵, P. Marinos¹¹⁸, M. Mariotti⁵⁵, S. Markoff¹⁷⁴, P. Marquez⁴¹, G. Marsella⁹⁴, J. Martí⁵⁶, J.-M. Martin²⁰, P. Martin⁸⁷, O. Martínez³⁰, M. Martínez⁴¹, G. Martínez¹¹³, O. Martínez⁴¹, H. Martínez-Huerta⁸⁰, C. Marty⁸⁷, R. Marx⁵³, N. Masetti^{21,151}, P. Massimo²⁹, A. Mastichiadis¹⁹¹, H. Matsumoto¹⁶⁷, N. Matthews¹⁶⁴, G. Maurin⁴⁵, W. Max-Moerbeck¹⁹², N. Maxted⁴³, D. Mazin^{2,105}, M.N. Mazziotta¹²⁰, S.M. Mazzola⁷⁷, J.D. Mbarubucyeye⁵², L. Mc Comb⁵, I. McHardy¹¹⁵, S. McKeague¹⁰⁷, S. McMuldrough⁶³, E. Medina⁶⁴, D. Medina Miranda¹⁷, A. Melandri⁹⁵, C. Melioli¹⁹, D. Melkumyan⁵², S. Menchiari⁶², S. Mender⁴⁶, S. Mereghetti⁶¹, G. Merino Arévalo⁶, E. Mestre¹³, J.-L. Meunier⁷⁹, T. Meures¹³⁵, M. Meyer¹⁴², S. Micanovic¹²¹, M. Miceli⁷⁷, M. Michailidis⁶⁹, J. Michałowski¹⁰¹, T. Miener¹¹, I. Mievre⁴⁵, J. Miller³⁵, I.A. Minaya¹⁵³, T. Mineo⁹¹, M. Mineev¹⁸⁹, J.M. Miranda³⁰, R. Mirzoyan¹⁰⁵, A. Mitchell³⁶, T. Mizuno¹⁹³, B. Mode¹³⁵, R. Moderski⁴⁹, L. Mohrman¹⁴², E. Molina⁸¹, E. Molinari¹⁴⁸, T. Montaruli¹⁷, I. Monteiro⁴⁵, C. Moore¹²⁴, A. Moralejo⁴¹, D. Morcuende-Parrilla¹¹, E. Moretti⁴¹, L. Morganti⁶⁴, K. Mori¹⁹⁴, P. Moriarty¹⁵, K. Morik⁴⁶, G. Morlino²², P. Morris¹¹⁴, A. Morselli²⁵, K. Moshammer⁵², P. Moya¹⁹², R. Mukherjee⁹, J. Muller⁸, C. Mundell¹⁷², J. Mundet⁴¹, T. Murach⁵², A. Muraczewski⁴⁹, H. Muraishi¹⁹⁵, K. Murase², I. Musella⁸⁴, A. Musumarra¹²⁰, A. Nagai¹⁷, N. Nagar¹⁹⁶, S. Nagataki⁵⁴, T. Naito¹⁵⁶, T. Nakamori¹⁵⁴, K. Nakashima¹⁴², K. Nakayama⁵¹, N. Nakhjiri¹³, G. Naletto⁵⁵, D. Naumann⁵², L. Nava⁹⁵, R. Navarro¹⁷⁴, M.A. Nawaz¹³², H. Ndiyavala⁴, D. Neise³⁶, L. Nellen¹⁶, R. Nemmen¹⁹, M. Newbold¹⁶⁴, N. Neyroud⁴⁵, K. Ngernphat³¹, T. Nguyen Trung⁷³, L. Nicastro²¹, L. Nickel⁴⁶, J. Niemiec¹⁰¹, D. Nieto¹¹, M. Nievas³², C. Nigro⁴¹, M. Nikoľajuk¹⁹⁰, D. Ninci⁴¹, K. Nishijima¹⁵⁷, K. Noda², Y. Nogami¹⁷⁶, S. Nolan⁵, R. Nomura², R. Norris¹¹⁷, D. Nosek¹⁹⁷, M. Nöthe⁴⁶, B. Novosyadlyj¹⁹⁸, V. Novotny¹⁹⁷, S. Nozaki¹⁸⁰, F. Nunio¹⁴⁴, P. O'Brien¹²⁴, K. Obara¹⁷⁶, R. Oger⁸⁵, Y. Ohira⁵¹, M. Ohishi², S. Ohm⁵², Y. Ohtani², T. Oka¹⁸⁰, N. Okazaki², A. Okumura^{139,199}, J.-F. Olive⁸⁷, C. Oliver³⁰, G. Olivera⁵², B. Olmi²², R.A. Ong⁷¹, M. Orienti⁹⁰, R. Orito²⁰⁰, M. Orlandini²¹, S. Orlando⁷⁷, E. Orlando¹⁴⁵, J.P. Osborne¹²⁴, M. Ostrowski¹⁶⁹, N. Otte¹⁴⁶, E. Ovcharov⁸⁶, E. Owen², I. Oya¹⁵⁹, A. Ozieblo¹⁵², M. Padovani²², I. Pagano²⁹, A. Pagliaro⁹¹, A. Paizis⁶¹, M. Palatiello¹⁴⁵, M. Palatka³³, E. Palazzi²¹, J.-L. Panazol⁴⁵, D. Paneque¹⁰⁵, B. Panes³, S. Panny¹⁶³, F.R. Pantaleo⁷², M. Panter⁵³, R. Paoletti⁶², M. Paolillo^{24,110}, A. Papitto²⁸, A. Paravac¹²², J.M. Paredes⁸¹, G. Pareschi⁹⁵, N. Park¹²⁷, N. Parmiggiani²¹, R.D. Parsons¹⁸⁶, P. Paško²⁰¹, S. Patel⁵², B. Patricelli²⁸, G. Pauletta¹⁰³, L. Pavletić¹²¹, S. Pavy⁸, A. Pe'er¹⁰⁵, M. Pech³³, M. Pecimotika¹²¹, M.G. Pellegriti¹²⁰, P. Peñil Del Campo¹¹, M. Penno⁵², A. Pepato⁵⁵, S. Perard¹⁰⁶, C. Perennes⁵⁵, G. Peres⁷⁷, M. Peresano⁴, A. Pérez-Aguilera¹¹, J. Pérez-Romero¹⁴, M.A. Pérez-Torres¹², M. Perri²⁸, M. Persic¹⁰³, S. Petrer¹⁸, P.-O. Petrucci¹²⁵, O. Petruk⁶⁶, B. Peyaud⁸⁹, K. Pfrang⁵², E. Pian²¹, G. Piano⁹⁹, P. Piattelli⁹⁴, E. Pietropaolo¹⁸, R. Pillera¹⁴⁹, B. Pilszyk¹⁰¹, D. Pimentel²⁰², F. Pintore⁹¹, C. Pio García⁴¹, G. Pirola⁶⁴, F. Piron³⁹, A. Pisarski¹⁹⁰, S. Pita⁸⁵, M. Pohl¹²⁸, V. Poireau⁴⁵, P. Poledrelli¹⁵⁹, A. Pollo¹²⁶, M. Polo¹¹³, C. Pongkitivanichkul³¹, J. Porthault¹⁴⁴, J. Powell¹⁷¹, D. Pozo⁹⁸, R.R. Prado⁵², E. Prandini⁵⁵, P. Prasil³¹, J. Prast⁴⁵, K. Pressard⁷³, G. Principe⁹⁰, C. Priyadarshi⁴¹, N. Produit³⁸, D. Prokhorov¹⁷⁴, H. Prokoph⁵², M. Prouza³³, H. Przybilski¹⁰¹, E. Pueschel⁵², G. Pühlhofer⁶⁹, I. Puljak¹⁵⁰, M.L. Pumo⁹⁴, M. Punch^{85,57}, F. Queiroz²⁰³, J. Quinn²⁰⁴, A. Quirrenbach¹⁷⁰, S. Rainò¹⁴⁹, P.J. Rajda¹⁷⁵, R. Rando⁵⁵, S. Razaque²⁰⁵, E. Rebert²⁰, S. Recchia⁸⁵, P. Reichherzer⁵⁹, O. Reimer¹⁶³, A. Reimer¹⁶³, A. Reisenegger^{3,206}, Q. Remy⁵³, M. Renaud³⁹, T. Reposeur¹⁰⁶, B. Reville⁵³, J.-M. Reymond⁷⁵, J. Reynolds¹⁵, W. Rhode⁴⁶, D. Ribeiro⁹, M. Ribó⁸¹, G. Richards¹⁶², T. Richtler¹⁹⁶, J. Rico⁴¹, F. Rieger⁵³, L. Riitano¹³⁵, V. Rippepi⁸⁴, M. Riquelme¹⁹², D. Riquelme³⁵, S. Rivoire³⁹, V. Rizi¹⁸, E. Roache⁶³, B. Røben¹⁵⁹, M. Roche¹⁰⁶, J. Rodriguez⁴, G. Rodriguez Fernandez²⁵, J.C. Rodriguez Ramirez¹⁹, J.J. Rodríguez Vázquez¹¹³, F. Roepke¹⁷⁰, G. Rojas²⁰⁷, L. Romanato⁵⁵, P. Romano⁹⁵, G. Romeo²⁹, F. Romero Lobato¹¹, C. Romoli⁵³, M. Roncadelli¹⁰³, S. Ronda³⁰, J. Rosado¹¹, A. Rosales de Leon⁵, G. Rowell¹¹⁸, B. Rudak⁴⁹, A. Rugliancich⁷⁴, J.E. Ruíz del Mazo¹², W. Rujopakarn³¹, C. Rulten⁵, C. Russell³³,

F. Russo²¹, I. Sadeh⁵², E. Sæther Hatlen¹⁰, S. Safi-Harb³⁷, L. Saha¹¹, P. Saha²⁰⁸, V. Sahakian¹⁴⁷, S. Sailer⁵³, T. Saito², N. Sakaki⁵⁴, S. Sakurai², F. Salesa Greus¹⁰¹, G. Salina²⁵, H. Salzmann⁶⁹, D. Sanchez⁴⁵, M. Sánchez-Conde¹⁴, H. Sandaker¹⁰, A. Sandoval¹⁶, P. Sangiorgi⁹¹, M. Sanguillon³⁹, H. Sano², M. Santander¹⁷¹, A. Santangelo⁶⁹, E.M. Santos²⁰², R. Santos-Lima¹⁹, A. Sanuy⁸¹, L. Sapozhnikov⁹⁶, T. Saric¹⁵⁰, S. Sarkar¹¹⁴, H. Sasaki¹⁵⁷, N. Sasaki¹⁷⁹, K. Satalecka⁵², Y. Sato²⁰⁹, F.G. Saturni²⁸, M. Sawada⁵⁴, U. Sawangwit³¹, J. Schaefer¹⁴², A. Scherer³, J. Scherpenberg¹⁰⁵, P. Schipani⁸⁴, B. Schleicher¹²², J. Schmoll⁵, M. Schneider¹⁴³, H. Schoorlemmer⁵³, P. Schovaneck³³, F. Schussler⁸⁹, B. Schwab¹⁴², U. Schwanke¹⁸⁶, J. Schwarz⁹⁵, T. Schweizer¹⁰⁵, E. Sciacca²⁹, S. Scuderi⁶¹, M. Seglar Arroyo⁴⁵, A. Segreto⁹¹, I. Seitenzahl⁴³, D. Semikoz⁸⁵, O. Sergijenko¹³⁶, J.E. Serna Franco¹⁶, M. Servillat²⁰, K. Seweryn²⁰¹, V. Sguera²¹, A. Shalchi³⁷, R.Y. Shang⁷¹, P. Sharma⁷³, R.C. Shellard⁴⁰, L. Sidoli⁶¹, J. Sieiro⁸¹, H. Siejkowski¹⁵², J. Silk¹¹⁴, A. Sillanpää⁶⁵, B.B. Singh¹⁰⁹, K.K. Singh²¹⁰, A. Sinha³⁹, C. Siqueira⁸⁰, G. Sironi⁹⁵, J. Sitarek⁶⁰, P. Sizun⁷⁵, V. Sliusar³⁸, A. Slowikowska¹⁷⁸, D. Sobczyńska⁶⁰, R.W. Sobrinho¹⁸⁴, H. Sol²⁰, G. Sottile⁹¹, H. Spackman¹¹⁴, A. Specovius¹⁴², S. Spencer¹¹⁴, G. Spengler¹⁸⁶, D. Spiga⁹⁵, A. Spolon⁵⁵, W. Springer¹⁶⁴, A. Stamerra²⁸, S. Stanić⁶⁸, R. Starling¹²⁴, L. Stawarz¹⁶⁹, R. Steenkamp⁴⁸, S. Stefanik¹⁹⁷, C. Stegmann¹²⁸, A. Steiner⁵², S. Steinmassl⁵³, C. Stella¹⁰³, C. Steppa¹²⁸, R. Sternberger⁵², M. Sterzel¹⁵², C. Stevens¹³⁵, B. Stevenson⁷¹, T. Stolarczyk⁴, G. Stratta²¹, U. Straumann²⁰⁸, J. Strišković¹⁶⁶, M. Strzys², R. Stuijk¹⁷⁴, M. Suchenek²¹¹, Y. Suda¹⁴⁰, Y. Sunada¹⁷⁹, T. Suomijarvi⁷³, T. Suric²¹², P. Sutcliffe¹⁵³, H. Suzuki²¹³, P. Świerk¹⁰¹, T. Szeplieniec¹⁵², A. Tacchini²¹, K. Tachihara¹⁴¹, G. Tagliaferri⁹⁵, H. Tajima¹³⁹, N. Tajima², D. Tak⁵², K. Takahashi²¹⁴, H. Takahashi¹⁴⁰, M. Takahashi², M. Takahashi², J. Takata², R. Takeishi², T. Tam², M. Tanaka¹⁸², T. Tanaka²¹³, S. Tanaka²⁰⁹, D. Tateishi¹⁷⁹, M. Tavani⁹⁹, F. Tavecchio⁹⁵, T. Tavernier⁸⁹, L. Taylor¹³⁵, A. Taylor⁵², L.A. Tejedor¹¹, P. Temnikov¹⁸⁹, Y. Terada¹⁷⁹, K. Terauchi¹⁸⁰, J.C. Terrazas¹⁹², R. Terrier⁸⁵, T. Terzic¹²¹, M. Teshima^{105,2}, V. Testa²⁸, D. Thibaut⁸⁵, F. Thocquenue⁷⁵, W. Tian², L. Tibaldo⁸⁷, A. Tiengo²¹⁵, D. Tiziani¹⁴², M. Tluczykont⁵⁰, C.J. Todero Peixoto¹⁰², F. Tokanai¹⁵⁴, K. Toma¹⁶⁰, L. Tomankova¹⁴², J. Tomastik¹⁰⁴, D. Tonev¹⁸⁹, M. Tornikoski²¹⁶, D.F. Torres¹³, E. Torresi²¹, G. Tosti⁹⁵, L. Tosti²³, T. Totani⁵¹, N. Tothill¹¹⁷, F. Tousseneil⁷⁹, G. Tovmassian¹⁶, P. Travnicek³³, C. Trichard⁸, M. Trifoglio²¹, A. Trois⁹⁵, S. Truzzi⁶², A. Tsiahina⁸⁷, T. Tsuru¹⁸⁰, B. Turk⁴⁵, A. Tutone⁹¹, Y. Uchiyama¹⁶¹, G. Umama²⁹, P. Utayarat³¹, L. Vaclavik¹⁰⁴, M. Vacula¹⁰⁴, V. Vagelli^{23,217}, F. Vagnetti²⁵, F. Vakili²¹⁸, J.A. Valdivia¹⁹², M. Valentino²⁴, A. Valio¹⁹, B. Vallage⁸⁹, P. Vallania^{44,64}, J.V. Valverde Quispe⁸, A.M. Van den Berg⁴², W. van Driel²⁰, C. van Eldik¹⁴², C. van Rensburg¹, B. van Soelen²¹⁰, J. Vandenbroucke¹³⁵, J. Vanderwalt¹, G. Vasileiadis³⁹, V. Vassiliev⁷¹, M. Vázquez Acosta³², M. Vecchi⁴², A. Vegh⁹⁸, J. Veh¹⁴², P. Veitch¹¹⁸, P. Venault⁷⁵, C. Venter¹, S. Ventura⁶², S. Vercellone⁹⁵, S. Vergani²⁰, V. Verguillov¹⁸⁹, G. Verna²⁷, S. Vernetto^{44,64}, V. Verzi²⁵, G.P. Vettolani⁹⁰, C. Veyssiere¹⁴⁴, I. Viale⁵⁵, A. Viana⁸⁰, N. Viaux³⁵, J. Vicha³³, J. Vignatti³⁵, C.F. Vigorito^{64,108}, J. Villanueva⁹⁸, J. Vink¹⁷⁴, V. Vitale²³, V. Vittorini⁹⁹, V. Vodeb⁶⁸, H. Voelk⁵³, N. Vogel¹⁴², V. Voisin⁷⁹, S. Vorobiov⁶⁸, I. Vovk², M. Vrstil³³, T. Vuillaume⁴⁵, S.J. Wagner¹⁷⁰, R. Wagner¹⁰⁵, P. Wagner⁵², K. Wakazono¹³⁹, S.P. Wakely¹²⁷, R. Walter³⁸, M. Ward⁵, D. Warren⁵⁴, J. Watson⁵², N. Webb⁸⁷, M. Wechakama³¹, P. Wegner⁵², A. Weinstein¹²⁹, C. Weniger¹⁷⁴, F. Werner⁵³, H. Wettskind¹⁰⁵, M. White¹¹⁸, R. White⁵³, A. Wierzcholska¹⁰¹, S. Wiesand⁵², R. Wijers¹⁷⁴, M. Wilkinson¹²⁴, M. Will¹⁰⁵, D.A. Williams¹⁴³, J. Williams¹²⁴, T. Williamson¹⁶², A. Wolte⁹⁵, Y.W. Wong¹⁴², M. Wood⁹⁶, C. Wunderlich⁶², T. Yamamoto²¹³, H. Yamamoto¹⁴¹, Y. Yamane¹⁴¹, R. Yamazaki²⁰⁹, S. Yanagita¹⁷⁶, L. Yang²⁰⁵, S. Yoo¹⁸⁰, T. Yoshida¹⁷⁶, T. Yoshikoshi², P. Yu⁷¹, P. Yu⁸⁵, A. Yusufzai⁵⁹, M. Zacharias²⁰, G. Zaharijas⁶⁸, B. Zaldivar¹⁴, L. Zampieri⁷⁶, R. Zanmar Sanchez²⁹, D. Zaric¹⁵⁰, M. Zavrtnik⁶⁸, D. Zavrtnik⁶⁸, A.A. Zdziarski⁴⁹, A. Zech²⁰, H. Zechlin⁶⁴, A. Zenin¹³⁹, A. Zerwekh³⁵, V.I. Zhdanov¹³⁶, K. Zięta¹⁶⁹, A. Zink¹⁴², J. Ziółkowski⁴⁹, V. Zitelli²¹, M. Živec⁶⁸, A. Zmija¹⁴²

1 : Centre for Space Research, North-West University, Potchefstroom, 2520, South Africa

2 : Institute for Cosmic Ray Research, University of Tokyo, 5-1-5, Kashiwa-no-ha, Kashiwa, Chiba 277-8582, Japan

3 : Pontificia Universidad Católica de Chile, Av. Libertador Bernardo O'Higgins 340, Santiago, Chile

4 : AIM, CEA, CNRS, Université Paris-Saclay, Université Paris Diderot, Sorbonne Paris Cité, CEA Paris-Saclay, IRFU/DAP, Bat 709, Orme des Merisiers, 91191 Gif-sur-Yvette, France

5 : Centre for Advanced Instrumentation, Dept. of Physics, Durham University, South Road, Durham DH1 3LE, United Kingdom

6 : Port d'Informació Científica, Edifici D, Carrer de l'Albareda, 08193 Bellaterra (Cerdanyola del Vallès), Spain

7 : School of Physics and Astronomy, Monash University, Melbourne, Victoria 3800, Australia

8 : Laboratoire Leprince-Ringuet, École Polytechnique (UMR 7638, CNRS/IN2P3, Institut Polytechnique de Paris), 91128 Palaiseau, France

9 : Department of Physics, Columbia University, 538 West 120th Street, New York, NY 10027, USA

10 : University of Oslo, Department of Physics, Sem Saelandsvei 24 - PO Box 1048 Blindern, N-0316 Oslo, Norway

11 : EMFTEL department and IPARCOS, Universidad Complutense de Madrid, 28040 Madrid, Spain

12 : Instituto de Astrofísica de Andalucía-CSIC, Glorieta de la Astronomía s/n, 18008, Granada, Spain

13 : Institute of Space Sciences (ICE-CSIC), and Institut d'Estudis Espacials de Catalunya (IEEC), and Institució Catalana de Recerca i Estudis Avançats (ICREA), Campus UAB, Carrer de Can Magrans, s/n 08193 Cerdanyola del Vallès, Spain

14 : Instituto de Física Teórica UAM/CSIC and Departamento de Física Teórica, Universidad Autónoma de Madrid, c/ Nicolás Cabrera 13-15, Campus de Cantoblanco UAM, 28049 Madrid, Spain

15 : Dublin Institute for Advanced Studies, 31 Fitzwilliam Place, Dublin 2, Ireland

16 : Universidad Nacional Autónoma de México, Delegación Coyoacán, 04510 Ciudad de México, Mexico

17 : University of Geneva - Département de physique nucléaire et corpusculaire, 24 rue du Général-Dufour, 1211 Genève 4, Switzerland

18 : INFN Dipartimento di Scienze Fisiche e Chimiche - Università degli Studi dell'Aquila and Gran Sasso Science Institute, Via Vetoio 1, Viale Crispi 7, 67100 L'Aquila, Italy

19 : Instituto de Astronomia, Geofísico, e Ciências Atmosféricas - Universidade de São Paulo, Cidade Universitária, R. do Matão, 1226, CEP 05508-090, São Paulo, SP, Brazil

- 20 : LUTH, GEPI and LERMA, Observatoire de Paris, CNRS, PSL University, 5 place Jules Janssen, 92190, Meudon, France
 21 : INAF - Osservatorio di Astrofisica e Scienza dello spazio di Bologna, Via Piero Gobetti 93/3, 40129 Bologna, Italy
 22 : INAF - Osservatorio Astrofisico di Arcetri, Largo E. Fermi, 5 - 50125 Firenze, Italy
 23 : INFN Sezione di Perugia and Università degli Studi di Perugia, Via A. Pascoli, 06123 Perugia, Italy
 24 : INFN Sezione di Napoli, Via Cintia, ed. G, 80126 Napoli, Italy
 25 : INFN Sezione di Roma Tor Vergata, Via della Ricerca Scientifica 1, 00133 Rome, Italy
 26 : Argonne National Laboratory, 9700 S. Cass Avenue, Argonne, IL 60439, USA
 27 : Aix-Marseille Université, CNRS/IN2P3, CPPM, 163 Avenue de Luminy, 13288 Marseille cedex 09, France
 28 : INAF - Osservatorio Astronomico di Roma, Via di Frascati 33, 00040, Monteporzio Catone, Italy
 29 : INAF - Osservatorio Astrofisico di Catania, Via S. Sofia, 78, 95123 Catania, Italy
 30 : Grupo de Electronica, Universidad Complutense de Madrid, Av. Complutense s/n, 28040 Madrid, Spain
 31 : National Astronomical Research Institute of Thailand, 191 Huay Kaew Rd., Suthep, Muang, Chiang Mai, 50200, Thailand
 32 : Instituto de Astrofísica de Canarias and Departamento de Astrofísica, Universidad de La Laguna, La Laguna, Tenerife, Spain
 33 : FZU - Institute of Physics of the Czech Academy of Sciences, Na Slovance 1999/2, 182 21 Praha 8, Czech Republic
 34 : Astronomical Institute of the Czech Academy of Sciences, Bočni II 1401 - 14100 Prague, Czech Republic
 35 : CCTVal, Universidad Técnica Federico Santa María, Avenida España 1680, Valparaíso, Chile
 36 : ETH Zurich, Institute for Particle Physics, Schafmattstr. 20, CH-8093 Zurich, Switzerland
 37 : The University of Manitoba, Dept of Physics and Astronomy, Winnipeg, Manitoba R3T 2N2, Canada
 38 : Department of Astronomy, University of Geneva, Chemin d'Ecogia 16, CH-1290 Versoix, Switzerland
 39 : Laboratoire Univers et Particules de Montpellier, Université de Montpellier, CNRS/IN2P3, CC 72, Place Eugène Bataillon, F-34095 Montpellier Cedex 5, France
 40 : Centro Brasileiro de Pesquisas Físicas, Rua Xavier Sigaud 150, RJ 22290-180, Rio de Janeiro, Brazil
 41 : Institut de Física d'Altes Energies (IFAE), The Barcelona Institute of Science and Technology, Campus UAB, 08193 Bellaterra (Barcelona), Spain
 42 : University of Groningen, KVI - Center for Advanced Radiation Technology, Zernikelaan 25, 9747 AA Groningen, The Netherlands
 43 : School of Physics, University of New South Wales, Sydney NSW 2052, Australia
 44 : INAF - Osservatorio Astrofisico di Torino, Strada Osservatorio 20, 10025 Pino Torinese (TO), Italy
 45 : Univ. Savoie Mont Blanc, CNRS, Laboratoire d'Annecy de Physique des Particules - IN2P3, 74000 Annecy, France
 46 : Department of Physics, TU Dortmund University, Otto-Hahn-Str. 4, 44221 Dortmund, Germany
 47 : University of Zagreb, Faculty of electrical engineering and computing, Unska 3, 10000 Zagreb, Croatia
 48 : University of Namibia, Department of Physics, 340 Mandume Ndemufayo Ave., Pioneerspark, Windhoek, Namibia
 49 : Nicolaus Copernicus Astronomical Center, Polish Academy of Sciences, ul. Bartycka 18, 00-716 Warsaw, Poland
 50 : Universität Hamburg, Institut für Experimentalphysik, Luruper Chaussee 149, 22761 Hamburg, Germany
 51 : Graduate School of Science, University of Tokyo, 7-3-1 Hongo, Bunkyo-ku, Tokyo 113-0033, Japan
 52 : Deutsches Elektronen-Synchrotron, Platanenallee 6, 15738 Zeuthen, Germany
 53 : Max-Planck-Institut für Kernphysik, Saupfercheckweg 1, 69117 Heidelberg, Germany
 54 : RIKEN, Institute of Physical and Chemical Research, 2-1 Hirosawa, Wako, Saitama, 351-0198, Japan
 55 : INFN Sezione di Padova and Università degli Studi di Padova, Via Marzolo 8, 35131 Padova, Italy
 56 : Escuela Politécnica Superior de Jaén, Universidad de Jaén, Campus Las Lagunillas s/n, Edif. A3, 23071 Jaén, Spain
 57 : Department of Physics and Electrical Engineering, Linnaeus University, 351 95 Växjö, Sweden
 58 : University of the Witwatersrand, 1 Jan Smuts Avenue, Braamfontein, 2000 Johannesburg, South Africa
 59 : Institut für Theoretische Physik, Lehrstuhl IV: Plasma-Astroteilchenphysik, Ruhr-Universität Bochum, Universitätsstraße 150, 44801 Bochum, Germany
 60 : Faculty of Physics and Applied Computer Science, University of Łódź, ul. Pomorska 149-153, 90-236 Łódź, Poland
 61 : INAF - Istituto di Astrofisica Spaziale e Fisica Cosmica di Milano, Via A. Corti 12, 20133 Milano, Italy
 62 : INFN and Università degli Studi di Siena, Dipartimento di Scienze Fisiche, della Terra e dell'Ambiente (DSFTA), Sezione di Fisica, Via Roma 56, 53100 Siena, Italy
 63 : Center for Astrophysics | Harvard & Smithsonian, 60 Garden St, Cambridge, MA 02180, USA
 64 : INFN Sezione di Torino, Via P. Giuria 1, 10125 Torino, Italy
 65 : Finnish Centre for Astronomy with ESO, University of Turku, Finland, FI-20014 University of Turku, Finland
 66 : Pidstryhach Institute for Applied Problems in Mechanics and Mathematics NASU, 3B Naukova Street, Lviv, 79060, Ukraine
 67 : Bhabha Atomic Research Centre, Trombay, Mumbai 400085, India
 68 : Center for Astrophysics and Cosmology, University of Nova Gorica, Vipavska 11c, 5270 Ajdovščina, Slovenia
 69 : Institut für Astronomie und Astrophysik, Universität Tübingen, Sand 1, 72076 Tübingen, Germany
 70 : Research School of Astronomy and Astrophysics, Australian National University, Canberra ACT 0200, Australia
 71 : Department of Physics and Astronomy, University of California, Los Angeles, CA 90095, USA
 72 : INFN Sezione di Bari and Politecnico di Bari, via Orabona 4, 70124 Bari, Italy
 73 : Laboratoire de Physique des 2 infinis, Irene Joliot-Curie, IN2P3/CNRS, Université Paris-Saclay, Université de Paris, 15 rue Georges Clemenceau, 91406 Orsay, Cedex, France
 74 : INFN Sezione di Pisa, Largo Pontecorvo 3, 56217 Pisa, Italy
 75 : IRFU/DEDIP, CEA, Université Paris-Saclay, Bat 141, 91191 Gif-sur-Yvette, France

- 76 : INAF - Osservatorio Astronomico di Padova, Vicolo dell'Osservatorio 5, 35122 Padova, Italy
- 77 : INAF - Osservatorio Astronomico di Palermo "G.S. Vaiana", Piazza del Parlamento 1, 90134 Palermo, Italy
- 78 : School of Physics, University of Sydney, Sydney NSW 2006, Australia
- 79 : Sorbonne Université, Université Paris Diderot, Sorbonne Paris Cité, CNRS/IN2P3, Laboratoire de Physique Nucléaire et de Hautes Energies, LPNHE, 4 Place Jussieu, F-75005 Paris, France
- 80 : Instituto de Física de São Carlos, Universidade de São Paulo, Av. Trabalhador São-carlense, 400 - CEP 13566-590, São Carlos, SP, Brazil
- 81 : Departament de Física Quàntica i Astrofísica, Institut de Ciències del Cosmos, Universitat de Barcelona, IEEC-UB, Martí i Franquès, 1, 08028, Barcelona, Spain
- 82 : Department of Physics, Washington University, St. Louis, MO 63130, USA
- 83 : Saha Institute of Nuclear Physics, Bidhannagar, Kolkata-700 064, India
- 84 : INAF - Osservatorio Astronomico di Capodimonte, Via Salita Moiarriello 16, 80131 Napoli, Italy
- 85 : Université de Paris, CNRS, Astroparticule et Cosmologie, 10, rue Alice Domon et Léonie Duquet, 75013 Paris Cedex 13, France
- 86 : Astronomy Department of Faculty of Physics, Sofia University, 5 James Bourchier Str., 1164 Sofia, Bulgaria
- 87 : Institut de Recherche en Astrophysique et Planétologie, CNRS-INSU, Université Paul Sabatier, 9 avenue Colonel Roche, BP 44346, 31028 Toulouse Cedex 4, France
- 88 : School of Physics and Astronomy, University of Minnesota, 116 Church Street S.E. Minneapolis, Minnesota 55455-0112, USA
- 89 : IRFU, CEA, Université Paris-Saclay, Bât 141, 91191 Gif-sur-Yvette, France
- 90 : INAF - Istituto di Radioastronomia, Via Gobetti 101, 40129 Bologna, Italy
- 91 : INAF - Istituto di Astrofisica Spaziale e Fisica Cosmica di Palermo, Via U. La Malfa 153, 90146 Palermo, Italy
- 92 : Astronomical Observatory, Department of Physics, University of Warsaw, Aleje Ujazdowskie 4, 00478 Warsaw, Poland
- 93 : Armagh Observatory and Planetarium, College Hill, Armagh BT61 9DG, United Kingdom
- 94 : INFN Sezione di Catania, Via S. Sofia 64, 95123 Catania, Italy
- 95 : INAF - Osservatorio Astronomico di Brera, Via Brera 28, 20121 Milano, Italy
- 96 : Kavli Institute for Particle Astrophysics and Cosmology, Department of Physics and SLAC National Accelerator Laboratory, Stanford University, 2575 Sand Hill Road, Menlo Park, CA 94025, USA
- 97 : Universidade Cruzeiro do Sul, Núcleo de Astrofísica Teórica (NAT/UCS), Rua Galvão Bueno 8687, Bloco B, sala 16, Libertade 01506-000 - São Paulo, Brazil
- 98 : Universidad de Valparaíso, Blanco 951, Valparaíso, Chile
- 99 : INAF - Istituto di Astrofisica e Planetologia Spaziali (IAPS), Via del Fosso del Cavaliere 100, 00133 Roma, Italy
- 100 : Lund Observatory, Lund University, Box 43, SE-22100 Lund, Sweden
- 101 : The Henryk Niewodniczański Institute of Nuclear Physics, Polish Academy of Sciences, ul. Radzikowskiego 152, 31-342 Cracow, Poland
- 102 : Escola de Engenharia de Lorena, Universidade de São Paulo, Área I - Estrada Municipal do Campinho, s/nº, CEP 12602-810, Pte. Nova, Lorena, Brazil
- 103 : INFN Sezione di Trieste and Università degli Studi di Udine, Via delle Scienze 208, 33100 Udine, Italy
- 104 : Palacky University Olomouc, Faculty of Science, RCPTM, 17. listopadu 1192/12, 771 46 Olomouc, Czech Republic
- 105 : Max-Planck-Institut für Physik, Föhringer Ring 6, 80805 München, Germany
- 106 : CENBG, Univ. Bordeaux, CNRS-IN2P3, UMR 5797, 19 Chemin du Solarium, CS 10120, F-33175 Gradignan Cedex, France
- 107 : Dublin City University, Glasnevin, Dublin 9, Ireland
- 108 : Dipartimento di Fisica - Università degli Studi di Torino, Via Pietro Giuria 1 - 10125 Torino, Italy
- 109 : Tata Institute of Fundamental Research, Homi Bhabha Road, Colaba, Mumbai 400005, India
- 110 : Università degli Studi di Napoli "Federico II" - Dipartimento di Fisica "E. Pancini", Complesso universitario di Monte Sant'Angelo, Via Cintia - 80126 Napoli, Italy
- 111 : Oskar Klein Centre, Department of Physics, University of Stockholm, Albanova, SE-10691, Sweden
- 112 : Yale University, Department of Physics and Astronomy, 260 Whitney Avenue, New Haven, CT 06520-8101, USA
- 113 : CIEMAT, Avda. Complutense 40, 28040 Madrid, Spain
- 114 : University of Oxford, Department of Physics, Denys Wilkinson Building, Keble Road, Oxford OX1 3RH, United Kingdom
- 115 : School of Physics & Astronomy, University of Southampton, University Road, Southampton SO17 1BJ, United Kingdom
- 116 : Department of Physics and Technology, University of Bergen, Musepllass 1, 5007 Bergen, Norway
- 117 : Western Sydney University, Locked Bag 1797, Penrith, NSW 2751, Australia
- 118 : School of Physical Sciences, University of Adelaide, Adelaide SA 5005, Australia
- 119 : INFN Sezione di Roma La Sapienza, P.le Aldo Moro, 2 - 00185 Roma, Italy
- 120 : INFN Sezione di Bari, via Orabona 4, 70126 Bari, Italy
- 121 : University of Rijeka, Department of Physics, Radmile Matejčić 2, 51000 Rijeka, Croatia
- 122 : Institute for Theoretical Physics and Astrophysics, Universität Würzburg, Campus Hubland Nord, Emil-Fischer-Str. 31, 97074 Würzburg, Germany
- 123 : Universidade Federal Do Paraná - Setor Palotina, Departamento de Engenharias e Exatas, Rua Pioneiro, 2153, Jardim Dallas, CEP: 85950-000 Palotina, Paraná, Brazil
- 124 : Dept. of Physics and Astronomy, University of Leicester, Leicester, LE1 7RH, United Kingdom
- 125 : Univ. Grenoble Alpes, CNRS, IPAG, 414 rue de la Piscine, Domaine Universitaire, 38041 Grenoble Cedex 9, France

- 126 : National Centre for nuclear research (Narodowe Centrum Badań Jądrowych), Ul. Andrzeja Sołtana7, 05-400 Otwock, Świerk, Poland
- 127 : Enrico Fermi Institute, University of Chicago, 5640 South Ellis Avenue, Chicago, IL 60637, USA
- 128 : Institut für Physik & Astronomie, Universität Potsdam, Karl-Liebknecht-Strasse 24/25, 14476 Potsdam, Germany
- 129 : Department of Physics and Astronomy, Iowa State University, Zaffarano Hall, Ames, IA 50011-3160, USA
- 130 : School of Physics, Aristotle University, Thessaloniki, 54124 Thessaloniki, Greece
- 131 : King's College London, Strand, London, WC2R 2LS, United Kingdom
- 132 : Escola de Artes, Ciências e Humanidades, Universidade de São Paulo, Rua Arlindo Bettio, CEP 03828-000, 1000 São Paulo, Brazil
- 133 : Dept. of Astronomy & Astrophysics, Pennsylvania State University, University Park, PA 16802, USA
- 134 : National Technical University of Athens, Department of Physics, Zografos 9, 15780 Athens, Greece
- 135 : University of Wisconsin, Madison, 500 Lincoln Drive, Madison, WI, 53706, USA
- 136 : Astronomical Observatory of Taras Shevchenko National University of Kyiv, 3 Observatorna Street, Kyiv, 04053, Ukraine
- 137 : Department of Physics, Purdue University, West Lafayette, IN 47907, USA
- 138 : Unitat de Física de les Radiacions, Departament de Física, and CERES-IEEC, Universitat Autònoma de Barcelona, Edifici C3, Campus UAB, 08193 Bellaterra, Spain
- 139 : Institute for Space-Earth Environmental Research, Nagoya University, Chikusa-ku, Nagoya 464-8601, Japan
- 140 : Department of Physical Science, Hiroshima University, Higashi-Hiroshima, Hiroshima 739-8526, Japan
- 141 : Department of Physics, Nagoya University, Chikusa-ku, Nagoya, 464-8602, Japan
- 142 : Friedrich-Alexander-Universität Erlangen-Nürnberg, Erlangen Centre for Astroparticle Physics (ECAP), Erwin-Rommel-Str. 1, 91058 Erlangen, Germany
- 143 : Santa Cruz Institute for Particle Physics and Department of Physics, University of California, Santa Cruz, 1156 High Street, Santa Cruz, CA 95064, USA
- 144 : IRFU / DIS, CEA, Université de Paris-Saclay, Bat 123, 91191 Gif-sur-Yvette, France
- 145 : INFN Sezione di Trieste and Università degli Studi di Trieste, Via Valerio 2 I, 34127 Trieste, Italy
- 146 : School of Physics & Center for Relativistic Astrophysics, Georgia Institute of Technology, 837 State Street, Atlanta, Georgia, 30332-0430, USA
- 147 : Alikhanyan National Science Laboratory, Yerevan Physics Institute, 2 Alikhanyan Brothers St., 0036, Yerevan, Armenia
- 148 : INAF - Telescopio Nazionale Galileo, Roche de los Muchachos Astronomical Observatory, 38787 Garafia, TF, Italy
- 149 : INFN Sezione di Bari and Università degli Studi di Bari, via Orabona 4, 70124 Bari, Italy
- 150 : University of Split - FESB, R. Boskovicica 32, 21 000 Split, Croatia
- 151 : Universidad Andres Bello, República 252, Santiago, Chile
- 152 : Academic Computer Centre CYFRONET AGH, ul. Nawojki 11, 30-950 Cracow, Poland
- 153 : University of Liverpool, Oliver Lodge Laboratory, Liverpool L69 7ZE, United Kingdom
- 154 : Department of Physics, Yamagata University, Yamagata, Yamagata 990-8560, Japan
- 155 : Astronomy Department, Adler Planetarium and Astronomy Museum, Chicago, IL 60605, USA
- 156 : Faculty of Management Information, Yamanashi-Gakuin University, Kofu, Yamanashi 400-8575, Japan
- 157 : Department of Physics, Tokai University, 4-1-1, Kita-Kaname, Hiratsuka, Kanagawa 259-1292, Japan
- 158 : Centre for Astrophysics Research, Science & Technology Research Institute, University of Hertfordshire, College Lane, Hertfordshire AL10 9AB, United Kingdom
- 159 : Cherenkov Telescope Array Observatory, Saupfercheckweg 1, 69117 Heidelberg, Germany
- 160 : Tohoku University, Astronomical Institute, Aobaku, Sendai 980-8578, Japan
- 161 : Department of Physics, Rikkyo University, 3-34-1 Nishi-Ikebukuro, Toshima-ku, Tokyo, Japan
- 162 : Department of Physics and Astronomy and the Bartol Research Institute, University of Delaware, Newark, DE 19716, USA
- 163 : Institut für Astro- und Teilchenphysik, Leopold-Franzens-Universität, Technikerstr. 25/8, 6020 Innsbruck, Austria
- 164 : Department of Physics and Astronomy, University of Utah, Salt Lake City, UT 84112-0830, USA
- 165 : IMAPP, Radboud University Nijmegen, P.O. Box 9010, 6500 GL Nijmegen, The Netherlands
- 166 : Josip Juraj Strossmayer University of Osijek, Trg Ljudevita Gaja 6, 31000 Osijek, Croatia
- 167 : Department of Earth and Space Science, Graduate School of Science, Osaka University, Toyonaka 560-0043, Japan
- 168 : Yukawa Institute for Theoretical Physics, Kyoto University, Kyoto 606-8502, Japan
- 169 : Astronomical Observatory, Jagiellonian University, ul. Orla 171, 30-244 Cracow, Poland
- 170 : Landessternwarte, Zentrum für Astronomie der Universität Heidelberg, Königstuhl 12, 69117 Heidelberg, Germany
- 171 : University of Alabama, Tuscaloosa, Department of Physics and Astronomy, Gallalee Hall, Box 870324 Tuscaloosa, AL 35487-0324, USA
- 172 : Department of Physics, University of Bath, Claverton Down, Bath BA2 7AY, United Kingdom
- 173 : University of Iowa, Department of Physics and Astronomy, Van Allen Hall, Iowa City, IA 52242, USA
- 174 : Anton Pannekoek Institute/GRAPPA, University of Amsterdam, Science Park 904 1098 XH Amsterdam, The Netherlands
- 175 : Faculty of Computer Science, Electronics and Telecommunications, AGH University of Science and Technology, Kraków, al. Mickiewicza 30, 30-059 Cracow, Poland
- 176 : Faculty of Science, Ibaraki University, Mito, Ibaraki, 310-8512, Japan
- 177 : Faculty of Science and Engineering, Waseda University, Shinjuku, Tokyo 169-8555, Japan

- 178 : Institute of Astronomy, Faculty of Physics, Astronomy and Informatics, Nicolaus Copernicus University in Toruń, ul. Grudziądzka 5, 87-100 Toruń, Poland
- 179 : Graduate School of Science and Engineering, Saitama University, 255 Simo-Ohkubo, Sakura-ku, Saitama city, Saitama 338-8570, Japan
- 180 : Division of Physics and Astronomy, Graduate School of Science, Kyoto University, Sakyo-ku, Kyoto, 606-8502, Japan
- 181 : Centre for Quantum Technologies, National University Singapore, Block S15, 3 Science Drive 2, Singapore 117543, Singapore
- 182 : Institute of Particle and Nuclear Studies, KEK (High Energy Accelerator Research Organization), 1-1 Oho, Tsukuba, 305-0801, Japan
- 183 : Department of Physics and Astronomy, University of Sheffield, Hounsfield Road, Sheffield S3 7RH, United Kingdom
- 184 : Centro de Ciências Naturais e Humanas, Universidade Federal do ABC, Av. dos Estados, 5001, CEP: 09.210-580, Santo André - SP, Brazil
- 185 : Dipartimento di Fisica e Astronomia, Sezione Astrofisica, Università di Catania, Via S. Sofia 78, I-95123 Catania, Italy
- 186 : Department of Physics, Humboldt University Berlin, Newtonstr. 15, 12489 Berlin, Germany
- 187 : Texas Tech University, 2500 Broadway, Lubbock, Texas 79409-1035, USA
- 188 : University of Zielona Góra, ul. Licealna 9, 65-417 Zielona Góra, Poland
- 189 : Institute for Nuclear Research and Nuclear Energy, Bulgarian Academy of Sciences, 72 boul. Tsarigradsko chaussee, 1784 Sofia, Bulgaria
- 190 : University of Białystok, Faculty of Physics, ul. K. Ciołkowskiego 1L, 15-254 Białystok, Poland
- 191 : Faculty of Physics, National and Kapodestrian University of Athens, Panepistimiopolis, 15771 Ilissia, Athens, Greece
- 192 : Universidad de Chile, Av. Libertador Bernardo O'Higgins 1058, Santiago, Chile
- 193 : Hiroshima Astrophysical Science Center, Hiroshima University, Higashi-Hiroshima, Hiroshima 739-8526, Japan
- 194 : Department of Applied Physics, University of Miyazaki, 1-1 Gakuen Kibana-dai Nishi, Miyazaki, 889-2192, Japan
- 195 : School of Allied Health Sciences, Kitasato University, Sagami-hara, Kanagawa 228-8555, Japan
- 196 : Departamento de Astronomía, Universidad de Concepción, Barrio Universitario S/N, Concepción, Chile
- 197 : Charles University, Institute of Particle & Nuclear Physics, V Holešovičkách 2, 180 00 Prague 8, Czech Republic
- 198 : Astronomical Observatory of Ivan Franko National University of Lviv, 8 Kyrila i Mephodia Street, Lviv, 79005, Ukraine
- 199 : Kobayashi-Maskawa Institute (KMI) for the Origin of Particles and the Universe, Nagoya University, Chikusa-ku, Nagoya 464-8602, Japan
- 200 : Graduate School of Technology, Industrial and Social Sciences, Tokushima University, Tokushima 770-8506, Japan
- 201 : Space Research Centre, Polish Academy of Sciences, ul. Bartycka 18A, 00-716 Warsaw, Poland
- 202 : Instituto de Física - Universidade de São Paulo, Rua do Matão Travessa R Nr.187 CEP 05508-090 Cidade Universitária, São Paulo, Brazil
- 203 : International Institute of Physics at the Federal University of Rio Grande do Norte, Campus Universitário, Lagoa Nova CEP 59078-970 Rio Grande do Norte, Brazil
- 204 : University College Dublin, Belfield, Dublin 4, Ireland
- 205 : Centre for Astro-Particle Physics (CAPP) and Department of Physics, University of Johannesburg, PO Box 524, Auckland Park 2006, South Africa
- 206 : Departamento de Física, Facultad de Ciencias Básicas, Universidad Metropolitana de Ciencias de la Educación, Santiago, Chile
- 207 : Núcleo de Formação de Professores - Universidade Federal de São Carlos, Rodovia Washington Luís, km 235 CEP 13565-905 - SP-310 São Carlos - São Paulo, Brazil
- 208 : Physik-Institut, Universität Zürich, Winterthurerstrasse 190, 8057 Zürich, Switzerland
- 209 : Department of Physical Sciences, Aoyama Gakuin University, Fuchinobe, Sagami-hara, Kanagawa, 252-5258, Japan
- 210 : University of the Free State, Nelson Mandela Avenue, Bloemfontein, 9300, South Africa
- 211 : Faculty of Electronics and Information, Warsaw University of Technology, ul. Nowowiejska 15/19, 00-665 Warsaw, Poland
- 212 : Rudjer Boskovic Institute, Bijenicka 54, 10 000 Zagreb, Croatia
- 213 : Department of Physics, Konan University, Kobe, Hyogo, 658-8501, Japan
- 214 : Kumamoto University, 2-39-1 Kurokami, Kumamoto, 860-8555, Japan
- 215 : University School for Advanced Studies IUSS Pavia, Palazzo del Broletto, Piazza della Vittoria 15, 27100 Pavia, Italy
- 216 : Aalto University, Otakaari 1, 00076 Aalto, Finland
- 217 : Agenzia Spaziale Italiana (ASI), 00133 Roma, Italy
- 218 : Observatoire de la Côte d'Azur, Boulevard de l'Observatoire CS34229, 06304 Nice Cedex 4, France