# Three non-zero solutions for a nonlinear eigenvalue problem 

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#### Abstract

In the present paper we prove a novel multiplicity result for a model quasilinear Dirichlet problem $\left(P_{\lambda}\right)$ depending on a positive parameter $\lambda$. By a variational method, we prove that for every $\lambda>1$ problem $\left(P_{\lambda}\right)$ has at least two non-zero solutions, while there exists $\hat{\lambda}>1$ such that problem ( $P_{\hat{\lambda}}$ ) has at least three non-zero solutions.


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## 1. Introduction

In the present paper we deal with the problem of multiplicity results for the following quasilinear equation coupled with the Dirichlet boundary condition

$$
\begin{cases}-\Delta_{p} u=\lambda \alpha(x) f(u) & \text { in } \Omega \\ u=0 & \text { on } \partial \Omega\end{cases}
$$

where $\Omega$ is a bounded open connected set in $\mathbb{R}^{n}$ with smooth boundary $\partial \Omega, p>n, \Delta_{p}$ is the $p$-Laplacian operator, $\lambda$ is a positive parameter, $\alpha \in L^{1}(\Omega)$ is a non-zero potential, and $f:[0,+\infty[\rightarrow \mathbb{R}$ is a continuous function with $f(0)=0$.

Problems of the type $\left(P_{\lambda}\right)$ have been the object of intensive investigations in the recent years, see [1-8], and references therein. Many of the aforementioned contributions guarantee the existence of at least two non-trivial weak solutions of $\left(P_{\lambda}\right)$ for $\lambda>0$ large enough where the key geometric assumptions on the nonlinear term $F$, where $F:[0,+\infty[\rightarrow \mathbb{R}$ is the primitive of $f$, that is $F(s)=\int_{0}^{s} f(t) d t$ for every $s \geq 0$, can be summarized as

$$
\left\{\begin{array}{l}
\sup _{[0,+\infty[ } F>0  \tag{1.1}\\
\limsup _{s \rightarrow 0^{+}} \frac{F(s)}{s^{p}} \leq 0 \text { and } \quad \limsup _{s \rightarrow+\infty} \frac{F(s)}{s^{p}} \leq 0
\end{array}\right.
$$

In order to obtain the aforementioned multiplicity results, various variational approaches are exploited; for instance, Morse theory [5,6], the mountain pass theorem and Ricceri-type three critical points results [1-4,7,9].

Notice that under (1.1) one can have even an exact multiplicity result for $\left(P_{\lambda}\right)$. To see this, let $p=2, n=1, \Omega=I \subset \mathbb{R}$ be a large interval, $\alpha=1$, and $f:\left[0,+\infty\left[\rightarrow \mathbb{R}\right.\right.$ defined by $f(s)=s(s-a)(1-s)_{+}$with $0<a<1 / 2$; here, $t_{+}=\max (0, t)$. It is clear that $F$ verifies (1.1). Moreover, via a bifurcation argument, Wei [10] proved that there exists $\lambda_{0}>0$ such that for

[^0]all $0<\lambda<\lambda_{0}$ problem $\left(P_{\lambda}\right)$ has no positive solution, it has exactly one positive solution for $\lambda=\lambda_{0}$, and exactly two positive solutions for $\lambda>\lambda_{0}$; see also [11].

The main purpose of the present paper is to guarantee the existence of at least three non-zero, non-negative weak solutions for $\left(P_{\lambda}\right)$ for certain values of $\lambda>0$ when (1.1) holds. According to the above exact multiplicity result, our aim requires more specific assumptions both on $f$ (or $F$ ) and $\alpha$. In order to state our main result, we introduce the notation

$$
\begin{equation*}
k_{\infty}:=\frac{n^{\frac{-1}{p}}}{\sqrt{\pi}}\left[\Gamma\left(1+\frac{n}{2}\right)\right]^{\frac{1}{n}}\left(\frac{p-1}{p-n}\right)^{1-\frac{1}{p}} m(\Omega)^{\frac{1}{n}-\frac{1}{p}} \tag{1.2}
\end{equation*}
$$

where $\Gamma$ denotes the Euler Gamma-function.
Our main result reads as follows:
Theorem 1.1. Let $p>n, \alpha \in L^{1}(\Omega)$ be a non-negative, non-zero function with compact support $K$. Assume that
(i) $S_{F}:=\sup _{[0,+\infty[ } F<+\infty$;
(ii) $\lim \sup _{s \rightarrow 0^{+}} \frac{F(s)}{s^{\eta}} \leq 0$.

Moreover, there exists $c>0$ such that
(iii) $F(c)=\max _{\left[0, k_{\infty}\left(p S_{F}\|\alpha\|_{L^{1}}\right)^{\frac{1}{p}}\right]} F<S_{F}$;
(iv) $\frac{F(c)}{c^{p}}>\frac{m(\Omega \backslash K)}{p \operatorname{dist}(K, \partial \Omega)^{p}\left\|_{\alpha}\right\|_{L^{1}}}$.

Then, the following statements hold:
(a) For every $\lambda>1$, problem $\left(P_{\lambda}\right)$ has at least two non-zero, non-negative weak solutions.
(b) There exists $\hat{\lambda}>1$ such that problem $\left(P_{\hat{\lambda}}\right)$ has at least three non-zero, non-negative weak solutions.

Before proving Theorem 1.1 some remarks are in order.
Remark 1.1. (a) Under the assumptions of Theorem 1.1, one can prove the existence of two non-zero weak solutions for $\left(P_{\lambda}\right)$ for enough large values of $\lambda>0$; the first one is the global minimum of the energy functional associated with $\left(P_{\lambda}\right)$ with negative energy-level, while the second one is a mountain-pass type solution with positive energy-level. A much precise conclusion can be deduced as follows. Since (i),(ii) and (iv) imply (1.1), a suitable choice in [9] guarantees the existence of at least two non-zero weak solutions for $\left(P_{\lambda}\right)$ for every $\lambda>\lambda_{0}$, where

$$
\begin{equation*}
\lambda_{0}=\inf \left\{\frac{\int_{\Omega}|\nabla u|^{p}}{p \int_{K} \alpha(x) F(u(x)) d x}: u \in W_{0}^{1, p}(\Omega), \int_{K} \alpha(x) F(u(x)) d x>0\right\} \tag{1.3}
\end{equation*}
$$

A simple estimate by means of a suitable truncation function and assumption (iv) show that

$$
\lambda_{0}<\frac{c^{p} m(\Omega \backslash K)}{p F(c) \operatorname{dist}(K, \partial \Omega)^{p}\|\alpha\|_{L^{1}}}<1
$$

which concludes the proof of (a) in Theorem 1.1; for details see (3.6). Even more, under these assumptions, Ricceri's result (see [9]) provides a stability of problem $\left(P_{\lambda}\right)$ with respect to any small nonlinear perturbation whenever $\lambda>\lambda_{0}$. However, for $\lambda>0$ small enough, problem $\left(P_{\lambda}\right)$ has usually only the trivial solution. Example 3.1 supports this fact as well.
(b) Assumption (iii) requires that the function $F$ has a local maximum $c>0$ on a quite large set whose size depends on the function $F$ itself, namely, on the interval $I_{F}:=\left[0, k_{\infty}\left(p S_{F}\|\alpha\|_{L^{1}}\right)^{\frac{1}{p}}\right]$. Note that a simple estimate together with hypothesis (iv) shows that $c$ belongs to the interval $I_{F}$. In view of the above discussion, the technical assumption (iii) is behind on the existence of a third non-zero weak solution for $\left(P_{\lambda}\right)$.
Remark 1.2. Note that in Theorem 1.1 we are able to prove the existence of a single value of $\hat{\lambda}>1$ such that problem ( $P_{\hat{\lambda}}$ ) has at least three non-zero, non-negative weak solutions. A challenging problem is to know if this phenomenon is stable/unstable with respect to the parameter $\lambda$; namely, to confirm/infirm the existence of certain functions $f$ satisfying all the assumptions of Theorem 1.1 such that problem $\left(P_{\lambda}\right)$ has exactly two non-zero weak solutions for $\left.\lambda \in\right] 1,+\infty[\backslash\{\hat{\lambda}\}$ and at least three solutions for $\lambda=\hat{\lambda}$.
Remark 1.3. Taking into account the special character of the function $\alpha$ (i.e., $\alpha$ has a compact support $K$ in $\Omega$ ), we could expect to construct in a trivial way some weak solutions for $\left(P_{\lambda}\right)$ via $p$-harmonic functions. The reason is the following; for simplicity, let us consider the case when $\Omega=B(0, R)$ and $K=\bar{B}(0, r)$ for some $0<r<R$. Due to (iii), the nonlinearity $f$ attains the zero value at least in two points ( $c$ being one of them since it is a local maximum for $F$ ). Let us denote such an element by $c>0$. A simple calculation shows that the function $\tilde{u}_{c} \in W_{0}^{1, p}(B(0, R))$ defined by

$$
\tilde{u}_{c}(x)= \begin{cases}c & \text { if } x \in K=\bar{B}(0, r) \\ c \frac{|x|^{\frac{p-n}{p-1}}-R^{\frac{p-n}{p-1}}}{r^{\frac{p-n}{p-1}}-R^{\frac{p-n}{p-1}}} & \text { if } x \in B(0, R) \backslash K\end{cases}
$$

verifies almost everywhere problem $\left(P_{\lambda}\right)$ for every $\lambda \in \mathbb{R}$. Thus, one can construct in a direct way two almost pointwise solutions of $\left(P_{\lambda}\right)$ for every $\lambda \in \mathbb{R}$. However, it is worth noticing that $\tilde{u}_{c}$ is not a weak solution for $\left(P_{\lambda}\right)$. Indeed, according to a standard regularity result (see for instance Lieberman [12, Theorem 1]), a bounded weak solution of $\left(P_{\lambda}\right)$ is a function of class $C^{1, \beta}$ for some $\beta>0$ which is not our case. Note that without $\alpha$ having compact support $K$ in $\Omega$ we are not able to state a similar multiplicity result as Theorem 1.1; we postpone this discussion after giving the whole proof (see Remark 3.1).

Remark 1.4. We are able to state a similar result also in the case when $S_{F}:=\sup _{[0,+\infty[ } F=+\infty$. Note that in this case the assumptions/proof are more involved, see Theorem 3.1.

We conclude this section with a simple consequence of Theorem 1.1 when we are dealing with a highly quasilinear problem, i.e., the value of $p$ in the $p$-Laplacian is large enough. Namely, we have

Corollary 1.1. Let $\alpha \in L^{1}(\Omega)$ be a non-negative, non-zero function with compact support $K$, and besides of (i) from Theorem 1.1, we assume that 0 is a local maximum of $F$, and that there exist constants $c, \delta$, with $0<c<k_{\infty}<\delta$ and $c \leq \operatorname{dist}(K, \partial \Omega)$ such that $0<F(c)=\max _{[0, \delta]} F<S_{F}$. Then, there exists $p_{0}>n$ such that for each $p \geq p_{0}$, both conclusions of Theorem 1.1 hold.

The proof of Corollary 1.1 is based on the observations that $\lim _{p \rightarrow \infty}\left(p S_{F}\|\alpha\|_{L^{1}}\right)^{\frac{1}{p}}=1$ and $\lim _{p \rightarrow \infty}(c / \operatorname{dist}(K, \partial \Omega))^{p} / p=0$; these limits are used to prove items (iii) and (iv) from Theorem 1.1, respectively.

## 2. Preliminaries

Our main tool is the following theorem by Ricceri which is a consequence of a more general result [13, Theorem 1]:
Theorem 2.1. Let $(X,\|\cdot\|)$ be a reflexive real Banach space, $p>1, J: X \rightarrow \mathbb{R}$ a $C^{1}$ functional, with compact derivative such that $J(0)=0$ and

$$
\max \left\{\limsup _{u \rightarrow 0} \frac{J(u)}{\|u\|^{p}}, \limsup _{\|u\| \rightarrow \infty} \frac{J(u)}{\|u\|^{p}}\right\} \leq 0
$$

Moreover, assume that there exist $\gamma>0, \rho \in \mathbb{R}, v \in\left[0, \frac{1}{p}\left[, u_{1} \in X \backslash\{0\}, u_{2} \in X\right.\right.$ such that
(j) $J(u) \leq \gamma+v\|u\|^{p}$ for all $u \in X$;
(jj) $\left\|u_{1}\right\|^{p} \leq p J\left(u_{1}\right)$ and $\left\|u_{2}\right\|^{p}<p\left(J\left(u_{2}\right)+\rho\right)$;
(jjj) $J\left(u_{2}\right)=\sup _{\|u\|^{p} \leq \frac{p(\rho+\gamma)}{1-p v}} J(u)<\sup _{X} J$.
Then, there exists $\hat{\lambda}>1$ such that the functional $\Phi: X \rightarrow \mathbb{R}$ defined by

$$
\Phi(u)=\frac{1}{p}\|u\|^{p}-\hat{\lambda} J(u)
$$

has at least three non-zero critical points.
Remark 2.1. Notice that, from the assumptions of Theorem 2.1 one has also that 0 , being a strict local minimum, belongs to the set of the critical points of $\Phi$. Also, one has that $u_{2}$ is a local maximum of $J$, hence a critical point of $J$.

In the sequel we will denote by $X$ the space $W_{0}^{1, p}(\Omega)$ endowed with the usual norm

$$
\|u\|=\left(\int_{\Omega}|\nabla u(x)|^{p} d x\right)^{\frac{1}{p}}
$$

Since $p>n$, the embedding of $X$ into $C^{0}(\bar{\Omega})$ is continuous and compact. Let $c_{\infty}$ be the embedding constant, that is

$$
c_{\infty}=\sup _{u \in X \backslash\{0\}} \frac{\max _{\bar{\Omega}}|u|}{\|u\|}
$$

We have the following estimate for $c_{\infty}$, see [14]:

$$
c_{\infty} \leq \frac{n^{\frac{-1}{p}}}{\sqrt{\pi}}\left[\Gamma\left(1+\frac{n}{2}\right)\right]^{\frac{1}{n}}\left(\frac{p-1}{p-n}\right)^{1-\frac{1}{p}} m(\Omega)^{\frac{1}{n}-\frac{1}{p}},
$$

where $\Gamma$ denotes the Euler Gamma-function, and equality occurs when $\Omega$ is a ball. From (1.2), we clearly have that $c_{\infty} \leq k_{\infty}$.
Recall that by a weak solution of ( $P_{\hat{\lambda}}$ ) we mean a function $u \in X$ such that

$$
\int_{\Omega}|\nabla u|^{p-2} \nabla u \nabla v-\hat{\lambda} \int_{\Omega} \alpha(x) f(u) v=0
$$

for every $v \in X$. It is well known that critical points of $\Phi$ are weak solutions of $\left(P_{\hat{\lambda}}\right)$.

## 3. Proof of Theorem 1.1

Without loss of generality we can assume that $f$ is defined on the whole real axis, putting $f(s)=0$ for all $s \leq 0$. If we still denote by $F$ the primitive of $f$, then $F(s)=0$ for all $s \leq 0$. Define $J: X \rightarrow \mathbb{R}$ by

$$
J(u)=\int_{\Omega} \alpha(x) F(u) \text { for all } u \in X
$$

The functional $J$ is of class $C^{1}$, has compact derivative and $J(0)=0$. Assumption (i) implies that $J$ is bounded and

$$
\begin{equation*}
\sup _{X} J \leq \sup _{[0,+\infty[ } F\|\alpha\|_{L^{1}}=S_{F}\|\alpha\|_{L^{1}} \tag{3.1}
\end{equation*}
$$

In particular,

$$
\begin{equation*}
\limsup _{\|u\| \rightarrow \infty} \frac{J(u)}{\|u\|^{p}} \leq 0 \tag{3.2}
\end{equation*}
$$

Moreover, from (ii) it follows that for fixed $\varepsilon>0$, there exists $s_{0}>0$ such that $F(s) \leq \varepsilon s^{p}$ for all $s \in\left[0, s_{0}\right]$ and so, $F(s) \leq \varepsilon|s|^{p}$ for all $s \in\left[-s_{0}, s_{0}\right]$. Then, if $u \in X$ and $\|u\| \leq \frac{s_{0}}{c_{\infty}}$, one has

$$
F(u(x)) \leq \varepsilon|u(x)|^{p} \quad \text { for every } x \in \Omega
$$

So,

$$
J(u) \leq \varepsilon\|\alpha\|_{L^{1}}\|u\|_{\infty}^{p} \leq \varepsilon\|\alpha\|_{L^{1}} c_{\infty}^{p}\|u\|^{p},
$$

which implies at once

$$
\begin{equation*}
\limsup _{u \rightarrow 0} \frac{J(u)}{\|u\|^{p}} \leq 0 \tag{3.3}
\end{equation*}
$$

We claim to apply Theorem 2.1 to the functional $J$ defined above which, in view of (3.2) and (3.3), verifies

$$
\max \left\{\limsup _{u \rightarrow 0} \frac{J(u)}{\|u\|^{p}}, \limsup _{\|u\| \rightarrow \infty} \frac{J(u)}{\|u\|^{p}}\right\} \leq 0
$$

Denote by $\delta=\operatorname{dist}(K, \partial \Omega)$ and define $u_{c}: \Omega \rightarrow \mathbb{R}$ as it follows:

$$
u_{c}(x)= \begin{cases}c & \text { if } \operatorname{dist}(x, K)=0  \tag{3.4}\\ c\left(1-\frac{\operatorname{dist}(x, K)}{\delta}\right) & \text { if } 0<\operatorname{dist}(x, K) \leq \delta \\ 0 & \text { if } \operatorname{dist}(x, K)>\delta\end{cases}
$$

where $c$ is from assumption (iii). Notice that the function $u_{c} \in X$ is Lipschitzian and $\left|\nabla u_{c}(x)\right| \leq \frac{c}{\delta}$ for almost every $x \in \Omega$. One has that

$$
\left\|u_{c}\right\|^{p}=\int_{\Omega \backslash K}\left|\nabla u_{c}\right|^{p} \leq \frac{c^{p}}{\delta^{p}} m(\Omega \backslash K) .
$$

Also, since $K$ is the support of the function $\alpha$, one has

$$
\begin{equation*}
J\left(u_{c}\right)=\int_{\Omega} \alpha(x) F\left(u_{c}\right)=F(c)\|\alpha\|_{L^{1}} \tag{3.5}
\end{equation*}
$$

and assumption (iv) implies at once that

$$
\begin{equation*}
\left\|u_{c}\right\|^{p}<p J\left(u_{c}\right) \tag{3.6}
\end{equation*}
$$

From assumption (iii) we have also that $u_{c}$ is not a global maximum of $J$. Indeed, if $d$ is a positive number such that $F(d)>F(c)$, then defining $u_{d}$ as in (3.4), we have that

$$
\begin{equation*}
J\left(u_{d}\right)=F(d)\|\alpha\|_{L^{1}}>F(c)\|\alpha\|_{L^{1}}=J\left(u_{c}\right) . \tag{3.7}
\end{equation*}
$$

It is easily seen that

$$
\left\{u \in X:\|u\| \leq\left(p S_{F}\|\alpha\|_{L^{1}}\right)^{\frac{1}{p}}\right\} \subseteq\left\{u \in X:\|u\|_{\infty} \leq k_{\infty}\left(p S_{F}\|\alpha\|_{L^{1}}\right)^{\frac{1}{p}}\right\}
$$

So, if $u \in X$ and $\|u\| \leq\left(p S_{F}\|\alpha\|_{L^{1}}\right)^{\frac{1}{p}}$, then, due to assumption (iii),

$$
J(u) \leq J\left(u_{c}\right)
$$

that is, together with the fact that $\left\|u_{c}\right\| \leq\left(p S_{F}\|\alpha\|_{L^{1}}\right)^{\frac{1}{p}}$ (cf. (iv)),

$$
\begin{equation*}
J\left(u_{c}\right)=\max _{\bar{B}\left(0,\left(p S_{F}\|\alpha\|_{L^{1}}\right)^{\frac{1}{p}}\right)} J, \tag{3.8}
\end{equation*}
$$

where $\bar{B}(0, \sigma)$ denotes the closed ball in $X$ centered at zero of radius $\sigma$.
Assumptions ( j )-( jjj ) of Theorem 2.1 are immediately verified with the choices $\gamma=S_{F}\|\alpha\|_{L^{1}}, \rho=v=0$ and $u_{1}=u_{2}=$ $u_{c}$. Indeed, condition ( j ) follows from (3.1) while ( jj ) is a consequence of (3.6). Finally, (3.7) and (3.8) imply at once ( jjj ). All the assumptions of Theorem 2.1 are satisfied. Then, there exists $\hat{\lambda}>1$ such that the functional

$$
u \rightarrow \frac{1}{p}\|u\|^{p}-\hat{\lambda} J(u)
$$

has at least three non-zero critical points. As critical points of this functional are non-negative weak solutions of problem ( $P_{\hat{\lambda}}$ ), our conclusion is achieved.

Remark 3.1. As we already pointed out in the Introduction, without $\alpha$ having compact support $K$ in $\Omega$ we meet several obstacles to apply Theorem 2.1. Indeed, in order to ensure the existence of a non-zero, local (but not global) maximum point $u_{2}=u_{c}$ for $J$, careful estimates are needed with specific truncation functions in $X$, see relations (3.5), (3.7) and (3.8); otherwise, the aforementioned expressions will become much involved. Notice that if in $\left(P_{\lambda}\right)$ we have a zero Neumann boundary condition instead of the zero Dirichlet boundary condition, the arguments become much simpler and no restriction is needed on $\alpha$.

We propose now an example of nonlinearity satisfying the assumptions of Theorem 1.1.
Example 3.1. Let $q>p>n, \alpha \in L^{1}(\Omega)$ be a non-negative function with compact support $K$ satisfying

$$
\|\alpha\|_{L^{1}}>\frac{m(\Omega \backslash K)}{p \operatorname{dist}(K, \partial \Omega)^{p}} \frac{\pi^{p-1}}{(\sqrt{2})^{q+1}}
$$

Assume also that $m$ is an integer, verifying

$$
m>\frac{k_{\infty}}{(2 \pi)^{1-\frac{1}{p}}}\left(p\|\alpha\|_{L^{1}}\right)^{\frac{1}{p}}
$$

Define $f:[0,+\infty[\rightarrow \mathbb{R}$ by

$$
f(s)= \begin{cases}\operatorname{sign}(\pi-s)|\sin s|^{q-1} & \text { if } s \in[0,2 \pi[ \\ 2|\sin s|^{q-1} \chi_{[2 m \pi,(2 m+1) \pi]}(s) & \text { if } s \in[2 \pi,+\infty[ \end{cases}
$$

where $\chi_{[2 m \pi,(2 m+1) \pi]}$ is the characteristic function of the interval $[2 m \pi,(2 m+1) \pi]$.
First, for $\lambda \in] 0, c_{\infty}^{-p}\|\alpha\|_{L^{1}}^{-1}\left[\right.$, problem $\left(P_{\lambda}\right)$ has only the zero solution. On the other hand, according to Theorem 1.1, for every $\lambda>1$ problem $\left(P_{\lambda}\right)$ has at least two non-zero weak solutions, and there exists $\hat{\lambda}>1$ such that problem $\left(P_{\hat{\lambda}}\right)$ has at least three non-zero, non-negative solutions.

In the previous result and example we treated the case of bounded primitive $F$. It is also possible to handle the case when $F$ is unbounded under more technical assumptions. We conclude the present paper by stating such a result without giving its explicit proof.

Theorem 3.1. Let $p>n, \alpha \in L^{\infty}(\Omega)$ be a non-negative, non-zero function with compact support $K$. Assume that
(i) $\sup _{[0,+\infty[ } F=+\infty$;
(ii) $\lim \sup _{s \rightarrow 0^{+}} \frac{F(s)}{s^{p}} \leq 0$; $\lim \sup _{s \rightarrow+\infty} \frac{F(s)}{s^{p}} \leq 0$.

Moreover, assume that there exist $\gamma>0, v \in\left[0, \frac{1}{p}[\right.$ and $c>0$ such that
(iii) $F(c)=\max _{\left[0, k_{\infty}\left(\frac{p \gamma}{1-p \nu}\right)^{\frac{1}{p}}\right]} F$;
(iv) $\frac{F(c)}{c^{p}}>\frac{m(\Omega \backslash K)}{p \operatorname{dist}(K, \partial \Omega)^{p}\|\alpha\|_{L^{1}}}$;
(v) $\|\alpha\|_{L^{\infty}} F(s)-v\left(k_{\infty} m(\Omega)\right)^{-1} s^{p} \leq \frac{\gamma}{m(\Omega)}$ for all $s \geq 0$.

Then, there exists $\hat{\lambda}>1$ such that problem $\left(P_{\hat{\lambda}}\right)$ has at least three non-zero, non-negative solutions.

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