

A MORE COMPLETE VERSION OF A MINIMAX THEOREM

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ABSTRACT. In this paper, we present a more complete version of the minimax theorem established in [7]. As a consequence, we get, for instance, the following result: Let X be a compact, not singleton subset of a normed space $(E, \|\cdot\|)$ and let Y be a convex subset of E such that $X \subseteq \overline{Y}$. Then, for every convex set $S \subseteq Y$ dense in Y , for every upper semicontinuous bounded function $\gamma : X \rightarrow \mathbf{R}$ and for every $\lambda > \frac{4 \sup_X |\gamma|}{\text{diam}(X)}$, there exists $y^* \in S$ such that the function $x \rightarrow \gamma(x) + \lambda \|x - y^*\|$ has at least two global maxima in X .

1. INTRODUCTION

Here and in what follows, X is a topological space and Y is a convex set in a real Hausdorff topological vector space. A function $h : X \rightarrow \mathbf{R}$ is said to be inf-compact if $h^{-1}(] - \infty, r])$ is compact for all $r \in \mathbf{R}$.

A function $k : Y \rightarrow \mathbf{R}$ is said to be quasi-concave (resp. quasi-convex) if $k^{-1}(]r, +\infty[)$ (resp. if $k^{-1}(] - \infty, r])$ is convex for all $r \in \mathbf{R}$.

If S is a convex subset of Y , we denote by \mathcal{A}_S the class of all functions $f : X \times Y \rightarrow \mathbf{R}$ such that, for each $y \in S$, the function $f(\cdot, y)$ is lower semicontinuous and inf-compact.

Moreover, we denote by \mathcal{B} the class of all functions $f : X \times Y \rightarrow \mathbf{R}$ such that either, for each $x \in X$, the function $f(x, \cdot)$ is quasi-concave and continuous, or, for each $x \in X$, the function $f(x, \cdot)$ is concave.

For any $f : X \times Y \rightarrow \mathbf{R}$, we set

$$\alpha_f = \sup_Y \inf_X f$$

and

$$\beta_f = \inf_X \sup_Y f .$$

Also, we denote by \mathcal{C}_f the family of all sets $S \subseteq Y$ such that

$$\inf_X \sup_S f = \inf_X \sup_Y f$$

and by $\tilde{\mathcal{C}}_f$ the family of all sets $S \subseteq Y$ such that

$$\sup_{y \in S} f(x, y) = \sup_{y \in Y} f(x, y)$$

for all $x \in X$.

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In particular, notice that $S \in \tilde{\mathcal{C}}_f$ provided, for each $x \in X$, there is a topology on Y for which S is dense and $f(x, \cdot)$ is lower semicontinuous.

Furthermore, we denote by τ_f the topology on Y generated by the family

$$\{\{y \in Y : f(x, y) < r\}\}_{x \in X, r \in \mathbf{R}} .$$

So, τ_f is the weakest topology on Y for which $f(x, \cdot)$ is upper semicontinuous for all $x \in X$. In [7], we established the following minimax result:

Theorem 1.1. *For every $g \in \mathcal{A}_Y \cap \mathcal{B}$, at least one of the following assertions holds:*

- (j) $\sup_Y \inf_X g = \inf_X \sup_Y g$;
- (jj) *there exists $y^* \in Y$ such that the function $g(\cdot, y^*)$ has at least two global minima.*

The relevance of Theorem 1.1 resides essentially in the fact that it is a flexible tool which can fruitfully be used to obtain meaningful results of various nature. This is clearly shown by a series of recent papers ([8]- [14]).

So, we believe that it is of interest to present a more complete form of Theorem 1.1: this is just the aim of this paper.

2. MAIN RESULTS

Here is the main abstract result (with the usual rules in $\overline{\mathbf{R}}$):

Theorem 2.1. *Let $f : X \times Y \rightarrow \mathbf{R}$. Assume that there is a function $\psi : Y \rightarrow \mathbf{R}$ such that $f + \psi \in \mathcal{B}$ and*

$$\alpha_{f+\psi} < \beta_{f+\psi} .$$

Then, for every convex set $S \in \mathcal{C}_{f+\psi}$, for every bounded function $\varphi : X \rightarrow \mathbf{R}$ and for every $\lambda > 0$ such that $\lambda f + \varphi \in \mathcal{A}_S$ and

$$(2.1) \quad \lambda > \frac{2 \sup_X |\varphi|}{\beta_{f+\psi} - \alpha_{f+\psi}} ,$$

there exists $y^ \in S$ such that the function $\lambda f(\cdot, y^*) + \varphi(\cdot)$ has at least two global minima.*

Proof. Consider the function $g : X \times Y \rightarrow \mathbf{R}$ defined by

$$g(x, y) = \lambda(f(x, y) + \psi(y)) + \varphi(x)$$

for all $(x, y) \in X \times Y$. Since $S \in \mathcal{C}_{f+\psi}$, we have

$$(2.2) \quad \inf_X \sup_S (f + \psi) = \inf_X \sup_Y (f + \psi) .$$

So, taking (2.1) and (2.2) into account, we have

$$(2.3) \quad \begin{aligned} \sup_S \inf_X g &\leq \sup_Y \inf_X g \leq \lambda \alpha_{f+\psi} + \sup_X |\varphi| \\ &< \lambda \beta_{f+\psi} - \sup_X |\varphi| = \lambda \inf_X \sup_S (f + \psi) - \sup_X |\varphi| \leq \inf_X \sup_S g . \end{aligned}$$

Now, observe that $g \in \mathcal{A}_S$ since $\lambda f + \varphi \in \mathcal{A}_S$ and, at the same time, $g \in \mathcal{B}$ since $f + \psi \in \mathcal{B}$. As a consequence, we can apply Theorem 1.1 to the restriction of the

function g to $X \times S$. Therefore, in view of (2.3), there exists $y^* \in S$ such that the function $g(\cdot, y^*)$ (and hence $\lambda f(\cdot, y^*) + \varphi(\cdot)$) has at least two global minima, as claimed. \square

Remark 2.2. As the above proof shows, Theorem 2.1 is a direct consequence of Theorem 1.1. However, Theorem 2.1 has at least four advantages with respect to Theorem 1.1. Namely, suppose that, for a given function $g \in \mathcal{A}_Y$, we are interested in ensuring the validity of assertion (jj) . Then, if we apply Theorem 1.1 in this regard, we have to show that $g \in \mathcal{B}$ and that assertion (j) does not hold. On the contrary, if we apply Theorem 2.1, we can ensure the validity of (jj) also in cases where either $g \notin \mathcal{B}$ or (j) holds true too. In addition, Theorem 2.1 is able to ensure the validity of (jj) even in a remarkably stronger way: not only extending it to suitable perturbations of g , but also offering an information on the location of y^* .

First, we wish to show how to obtain the very classical minimax theorems in [3] and [6] by means of Theorem 2.1.

Let V be a real vector space, $A \subseteq V$, $\varphi : A \rightarrow \mathbf{R}$. We say that φ is finitely lower semicontinuous if, for every finite-dimensional linear subspace $F \subseteq V$, the function $f|_{A \cap F}$ is lower semicontinuous in the Euclidean topology of F .

In the next result, the topology of X has no role.

Theorem 2.3. *Let X be a convex set in a real vector space and let $f \in \mathcal{B}$. Assume that there is a convex set $S \in \tilde{\mathcal{C}}_f$ such that $f(\cdot, y)$ is finitely lower semicontinuous and convex for all $y \in S$. Finally, assume that, for some $x_0 \in X$, the function that $f(x_0, \cdot)$ is τ_f -sup-compact.*

Then, one has

$$\sup_Y \inf_X f = \inf_X \sup_Y f .$$

Proof. Arguing by contradiction, assume that

$$\sup_Y \inf_X f < \inf_X \sup_Y f .$$

Denote by \mathcal{D} the family of all convex polytopes in X . Since \mathcal{D} is a filtering cover of X and $f(x_0, \cdot)$ is τ_f -sup-compact, by Proposition 2.1 of [7], there exists $P \in \mathcal{D}$ such that

$$\sup_Y \inf_P f < \inf_P \sup_Y f .$$

Let $\|\cdot\|$ be the Euclidean norm on $\text{span}(P)$. So, $\|\cdot\|^2$ is strictly convex. Now, fix λ so that

$$\lambda > \frac{2 \sup_{x \in P} \|x\|^2}{\inf_P \sup_Y f - \sup_Y \inf_P f} .$$

Notice that, for each $y \in S$, the function $x \rightarrow \|x\|^2 + \lambda f(x, y)$ is inf-compact in P with respect to the Euclidean topology. This is due to the assumption that $f(\cdot, y)$ is finitely lower semicontinuous and to the compactness of P in the Euclidean topology. As a consequence, if we consider P equipped with the Euclidean topology, we can apply Theorem 2.1 to the restriction of f to $P \times Y$ (recall that $S \in \tilde{\mathcal{C}}_f$), taking $\varphi = \|\cdot\|^2$. Accordingly, there would exist $y^* \in S$ such that the function

$x \rightarrow \|x\|^2 + \lambda f(x, y^*)$ has at least two global minima in P . But, this is absurd since this function is strictly convex. \square

Reasoning exactly as in the proof of Theorem 2.3 (even in a simplified way, since there is no need to consider the family \mathcal{D}), we also get

Theorem 2.4. *Let X be a compact convex set in a topological vector space such that there exists a lower semicontinuous, strictly convex, bounded function $\varphi : X \rightarrow \mathbf{R}$. Let $f \in \mathcal{B}$. Assume that there is a convex set $S \in \mathcal{C}_f$ such that $f(\cdot, y)$ is lower semicontinuous and convex for all $y \in S$.*

Then, one has

$$\sup_Y \inf_X f = \inf_X \sup_Y f .$$

We now revisit two applications of Theorem 1.1 in the light of Theorem 2.1.

The first one concerns the so called farthest points ([1]- [4]).

Theorem 2.5. *Let X be a non-singleton compact subset of a metric space (E, d) . Moreover, let $h : Y \rightarrow E$ be such that $X \subseteq \overline{h(Y)}$ and let the function $(x, y) \rightarrow f(x, y) := -d(x, h(y))$ belong to \mathcal{B} .*

Then, for every convex set $S \in \mathcal{C}_f$, for every upper semicontinuous bounded function $\gamma : X \rightarrow \mathbf{R}$ and for every λ satisfying

$$\lambda > \frac{4 \sup_X |\gamma|}{\text{diam}(X)} ,$$

there exists $y^ \in S$ such that the function $x \rightarrow \gamma(x) + \lambda d(x, h(y^*))$ has at least two global maxima in X .*

Proof. Since $X \subseteq \overline{h(Y)}$, we have

$$(2.4) \quad \sup_{x \in X} \inf_{y \in Y} d(x, h(y)) = 0 .$$

Also, for each $x_1, x_2 \in X$, $y \in Y$, we have

$$\frac{d(x_1, x_2)}{2} \leq \max\{d(x_1, h(y)), d(x_2, h(y))\}$$

and so

$$(2.5) \quad \frac{\text{diam}(X)}{2} \leq \inf_{y \in Y} \sup_{x \in X} d(x, h(y)) .$$

Hence, in view of (2.4) and (2.5), we have

$$\sup_Y \inf_X f \leq -\frac{\text{diam}(X)}{2} < 0 = \inf_X \sup_Y f .$$

Now, the conclusion follows directly from Theorem 2.1 taking $\varphi = -\gamma$. \square

Of course, the most natural corollary of Theorem 2.5 is as follows:

Corollary 2.6. *Let X be a non-singleton compact subset of a normed space $(E, \|\cdot\|)$ and let Y be a convex subset of E such that $X \subseteq \bar{Y}$.*

Then, for every convex set $S \subseteq Y$ dense in Y , for every upper semicontinuous bounded function $\gamma : X \rightarrow \mathbf{R}$ and for every $\lambda > \frac{4 \sup_X |\gamma|}{\text{diam}(X)}$, there exists $y^ \in S$ such that the function $x \rightarrow \gamma(x) + \lambda \|x - y^*\|$ has at least two global maxima in X .*

In turn, from Corollary 2.6, we clearly get

Corollary 2.7. *Let X be a compact subset of a normed space $(E, \|\cdot\|)$ and let Y be a convex subset of E such that $X \subseteq \bar{Y}$. Assume that there exist a sequence $\{S_n\}$ of convex subsets of Y dense in Y and a sequence $\{\gamma_n\}$ of upper semicontinuous bounded real-valued functions on X , with $\lim_{n \rightarrow \infty} \sup_X |\gamma_n| = 0$, such that, for each $n \in \mathbf{N}$ and for each $y \in S_n$, the function $x \rightarrow \gamma_n(x) + \|x - y\|$ has a unique global maximum in X .*

Then, X is a singleton.

Remark 2.8. Notice that Corollary 2.7 improves Theorem 1.1 of [14] which, in turn, extended a classical result by Klee ([5]) to normed spaces. More precisely, Theorem 1.1 of [14] agrees with the particular case of Corollary 2.7 in which each S_n is equal to $\text{conv}(X)$ and each γ_n is equal to 0. The second application concerns the calculus of variations. We will use the same symbol $|\cdot|$ to denote the norm of \mathbf{R} and the norm of \mathbf{R}^n . Let $\Omega \subset \mathbf{R}^n$ be a bounded domain with smooth boundary and let $p > 1$. On the Sobolev space $W^{1,p}(\Omega)$, we consider the norm

$$\|u\| = \left(\int_{\Omega} |\nabla u(x)|^p dx + \int_{\Omega} |u(x)|^p dx \right)^{\frac{1}{p}}.$$

If $n \geq p$, we denote by \mathcal{E} the class of all continuous functions $\sigma : \mathbf{R} \rightarrow \mathbf{R}$ such that

$$\sup_{\xi \in \mathbf{R}} \frac{|\sigma(\xi)|}{1 + |\xi|^q} < +\infty,$$

where $0 < q < \frac{pn}{n-p}$ if $p < n$ and $0 < q < +\infty$ if $p = n$. While, when $n < p$, \mathcal{E} stands for the class of all continuous functions $\sigma : \mathbf{R} \rightarrow \mathbf{R}$.

Recall that a function $h : \Omega \times \mathbf{R}^m \rightarrow \mathbf{R}$ is said to be a normal integrand ([15]) if it is $\mathcal{L}(\Omega) \otimes \mathcal{B}(\mathbf{R}^m)$ -measurable and $h(x, \cdot)$ is lower semicontinuous for a.e. $x \in \Omega$. Here $\mathcal{L}(\Omega)$ and $\mathcal{B}(\mathbf{R}^m)$ denote the Lebesgue and the Borel σ -algebras of subsets of Ω and \mathbf{R}^m , respectively.

Recall that if h is a normal integrand then, for each measurable function $u : \Omega \rightarrow \mathbf{R}^m$, the composite function $x \rightarrow h(x, u(x))$ is measurable ([15]).

We denote by \mathcal{F} the class of all normal integrands $h : \Omega \times \mathbf{R} \times \mathbf{R}^n \rightarrow \mathbf{R}$ such that $h(x, \xi, \cdot)$ is convex for all $(x, \xi) \in \Omega \times \mathbf{R}$ and there are $M \in L^1(\Omega)$, $b > 0$ such that

$$M(x) - b(|\xi| + |\eta|^p) \leq h(x, \xi, \eta)$$

for all $(x, \xi, \eta) \in \Omega \times \mathbf{R} \times \mathbf{R}^n$.

Let us also recall two results proved in [9].

Proposition 2.9. *Let $\Omega \subset \mathbf{R}^n$ be a bounded domain with smooth boundary, let $p > 1$ and let $h : \Omega \times \mathbf{R} \times \mathbf{R}^n \rightarrow \mathbf{R}$ be a normal integrand such that, for some $c, d > 0$, one has*

$$c|\eta|^p - d \leq h(x, \xi, \eta)$$

for all $(x, \xi, \eta) \in \Omega \times \mathbf{R} \times \mathbf{R}^n$ and

$$\lim_{|\xi| \rightarrow +\infty} \inf_{(x, \eta) \in \Omega \times \mathbf{R}^n} h(x, \xi, \eta) = +\infty .$$

Then, in $W^{1,p}(\Omega)$, one has

$$\lim_{\|u\| \rightarrow +\infty} \int_{\Omega} h(x, u(x), \nabla u(x)) dx = +\infty .$$

Proposition 2.10. *Let X, Y be two non-empty sets and $I : X \rightarrow \mathbf{R}$, $J : X \times Y \rightarrow \mathbf{R}$ two given functions. Assume that there are two sets $A, B \subset X$ such that:*

- (a) $\sup_A I < \inf_B I$;
- (b) $\sup_Y \inf_A J(x, y) \leq 0$;
- (c) $\inf_B \sup_Y J(x, y) \geq 0$;
- (d) $\inf_{X \setminus B} \sup_Y J(x, y) = +\infty$.

Then, one has

$$\sup_Y \inf_X (I + J) \leq \sup_A I < \inf_B I \leq \inf_X \sup_Y (I + J) .$$

Furthermore, let us also recall the following classical fact:

Proposition 2.11. *Let $A \subseteq \mathbf{R}^n$ be any open set and let $v \in L^1(A) \setminus \{0\}$.*

Then, one has

$$\sup_{\alpha \in C_0^\infty(A)} \int_A \alpha(x)v(x)dx = +\infty .$$

After these preliminaries, we can prove the following result:

Theorem 2.12. *Let $h, k \in \mathcal{F}$ and let $\sigma \in \mathcal{E}$ be a strictly monotone function. Assume that:*

- (i) there are $c, d > 0$ such that

$$c|\eta|^p - d \leq h(x, \xi, \eta)$$

for all $(x, \xi, \eta) \in \Omega \times \mathbf{R} \times \mathbf{R}^n$ and

$$\lim_{|\xi| \rightarrow +\infty} \frac{\inf_{(x, \eta) \in \Omega \times \mathbf{R}^n} h(x, \xi, \eta)}{|\sigma(\xi)| + 1} = +\infty ;$$

- (ii) for each $\xi \in \mathbf{R}$, the function $h(\cdot, \xi, 0)$ lies in $L^1(\Omega)$;
- (iii) there are $\xi_1, \xi_2, \xi_3 \in \mathbf{R}$, with $\xi_1 < \xi_2 < \xi_3$, such that

$$\max \left\{ \int_{\Omega} h(x, \xi_1, 0) dx, \int_{\Omega} h(x, \xi_3, 0) dx \right\} < \int_{\Omega} h(x, \xi_2, 0) dx .$$

Then, for every sequentially weakly closed set $V \subseteq W^{1,p}(\Omega)$, containing the constants, for every convex set $T \subseteq L^\infty(\Omega)$ dense in $L^\infty(\Omega)$, for every non-decreasing,

continuous, bounded function $\omega : U \rightarrow \mathbf{R}$, where $U := \{ \int_{\Omega} k(x, u(x), \nabla u(x)) dx : u \in W^{1,p}(\Omega) \}$, and for every λ satisfying

$$(2.6) \quad \lambda > \frac{2 \sup_U |\omega|}{\int_{\Omega} h(x, \xi_2, 0) dx - \max \{ \int_{\Omega} h(x, \xi_1, 0) dx, \int_{\Omega} h(x, \xi_3, 0) dx \}} ,$$

there exists $\gamma \in T$ such that the restriction to V of the functional

$$u \rightarrow \lambda \int_{\Omega} h(x, u(x), \nabla u(x)) dx + \int_{\Omega} \gamma(x) \sigma(u(x)) dx + \omega \left(\int_{\Omega} k(x, u(x), \nabla u(x)) dx \right)$$

has at least two global minima. The same conclusion holds also with $T = C_0^\infty(\Omega)$.

Proof. Fix V, T, ω, λ as in the conclusion. Since $\sigma \in \mathcal{E}$, in view of the Rellich-Kondrachov theorem, for each $u \in W^{1,p}(\Omega)$, we have $\sigma \circ u \in L^1(\Omega)$ and, for each $\gamma \in L^\infty(\Omega)$, the functional $u \rightarrow \int_{\Omega} \gamma(x) \sigma(u(x)) dx$ is sequentially weakly continuous. Moreover, since $h, k \in \mathcal{F}$ the functionals $u \rightarrow \int_{\Omega} h(x, u(x), \nabla u(x)) dx$ and $u \rightarrow \int_{\Omega} k(x, u(x), \nabla u(x)) dx$ (possibly taking the value $+\infty$) are sequentially weakly lower semicontinuous ([2], Theorem 4.6.8). Hence, since ω is non-decreasing and continuous, the functional $u \rightarrow \omega \left(\int_{\Omega} k(x, u(x), \nabla u(x)) dx \right)$ is sequentially weakly lower semicontinuous too. Set

$$X = \left\{ u \in V : \int_{\Omega} h(x, u(x), \nabla u(x)) dx < +\infty \right\} .$$

By (ii), the constants belong to X . Fix $\gamma \in L^\infty(\Omega)$. By (i), there is $\delta > 0$ such that

$$h(x, \xi, \eta) - 2 \|\gamma\|_{L^\infty(\Omega)} |\sigma(\xi)| \geq 0$$

for all $(x, \xi, \eta) \in \Omega \times \mathbf{R} \times \mathbf{R}^n$ with $|\xi| > \delta$. So, we have

$$\frac{c}{2} |\eta|^p - d - \|\gamma\|_{L^\infty(\Omega)} \sup_{|\xi| \leq \delta} |\sigma(\xi)| \leq h(x, \xi, \eta) + \gamma(x) \sigma(\xi)$$

for all $(x, \xi, \eta) \in \Omega \times \mathbf{R} \times \mathbf{R}^n$ and, of course,

$$\lim_{|\xi| \rightarrow +\infty} \inf_{(x, \eta) \in \Omega \times \mathbf{R}^n} (h(x, \xi, \eta) + \gamma(x) \sigma(\xi)) = +\infty .$$

Consequently, in view of Proposition 2.9, we have, in $W^{1,p}(\Omega)$,

$$\lim_{\|u\| \rightarrow +\infty} \left(\int_{\Omega} h(x, u(x), \nabla u(x)) dx + \int_{\Omega} \gamma(x) \sigma(u(x)) dx \right) = +\infty .$$

This implies that, for each $r \in \mathbf{R}$, the set

$$\left\{ u \in V : \int_{\Omega} h(x, u(x), \nabla u(x)) dx + \int_{\Omega} \gamma(x) \sigma(u(x)) dx \leq r \right\}$$

is weakly compact by reflexivity and by Eberlein-Smulyan's theorem. Of course, we also have

$$\begin{aligned} & \left\{ u \in V : \int_{\Omega} h(x, u(x), \nabla u(x)) dx + \int_{\Omega} \gamma(x) \sigma(u(x)) dx \leq r \right\} \\ &= \left\{ u \in X : \int_{\Omega} h(x, u(x), \nabla u(x)) dx + \int_{\Omega} \gamma(x) \sigma(u(x)) dx \leq r \right\} . \end{aligned}$$

Now, observe that, if we put

$$A = \{ \xi_1, \xi_3 \}$$

and

$$B = \{\xi_2\} ,$$

and define $I : X \rightarrow \mathbf{R}$, $J : X \times L^\infty(\Omega) \rightarrow \mathbf{R}$ by

$$I(u) = \int_{\Omega} h(x, u(x), \nabla u(x)) dx ,$$

$$J(u, \gamma) = \int_{\Omega} \gamma(x)(\sigma(u(x)) - \sigma(\xi_2)) dx$$

for all $u \in X$, $\gamma \in L^\infty(\Omega)$, we clearly have

$$\inf_{u \in B} \sup_{\gamma \in L^\infty(\Omega)} J(u, \gamma) = 0$$

and, by (iii),

$$\sup_A I < \inf_B I .$$

Since σ is strictly monotone, the numbers $\sigma(\xi_1) - \sigma(\xi_2)$ and $\sigma(\xi_3) - \sigma(\xi_2)$ have opposite signs. This clearly implies that

$$\sup_{\gamma \in L^\infty(\Omega)} \inf_{u \in A} J(u, \gamma) \leq 0 .$$

Furthermore, if $u \in X \setminus \{\xi_2\}$, again by strict monotonicity, $\sigma \circ u \neq \sigma(\xi_2)$, and so we have

$$\sup_{\gamma \in L^\infty(\Omega)} J(u, \gamma) = +\infty .$$

Therefore, the sets A, B and the functions I, J satisfy the assumptions of Proposition 2.10 and hence we have

$$(2.7) \quad \begin{aligned} \sup_{L^\infty(\Omega)} \inf_X (I + J) &\leq \max \left\{ \int_{\Omega} h(x, \xi_1, 0) dx, \int_{\Omega} h(x, \xi_3, 0) dx \right\} \\ &< \int_{\Omega} h(x, \xi_2, 0) dx = \inf_X \sup_{L^\infty(\Omega)} (I + J) . \end{aligned}$$

Now, we can apply Theorem 2.1 considering X equipped with the weak topology and taking

$$\begin{aligned} Y &= L^\infty(\Omega) , \\ f &= I + J , \\ \psi &= 0 , \\ S &= \frac{1}{\lambda} T \end{aligned}$$

and

$$\varphi(u) = \omega \left(\int_{\Omega} k(x, u(x), \nabla u(x)) dx \right) .$$

Notice that, in view of (2.7), inequality (2.1) holds thanks to (2.6), and the conclusion follows. When $T = C_0^\infty(\Omega)$ the same proof as above holds in view of Proposition 2.11. \square

Remark 2.13. Notice that condition (iii) holds if and only if the function $\int_{\Omega} h(x, \cdot, 0)$ is not quasi-convex.

Remark 2.14. For $\omega = 0$, Theorem 2.12 reduces to Theorem 1.2 of [9].

We conclude presenting an application of Theorem 2.12 to the Neumann problem for a Kirchhoff-type equation.

Given $K : [0, +\infty[\rightarrow \mathbf{R}$ and a Carathéodory function $\psi : \Omega \times \mathbf{R} \rightarrow \mathbf{R}$, consider the following Neumann problem

$$\begin{cases} -K \left(\int_{\Omega} |\nabla u(x)|^p dx \right) \operatorname{div}(|\nabla u|^{p-2} \nabla u) = \psi(x, u) & \text{in } \Omega \\ \frac{\partial u}{\partial \nu} = 0 & \text{on } \partial\Omega \end{cases}$$

where ν is the outward unit normal to $\partial\Omega$.

Let us recall that a weak solution of this problem is any $u \in W^{1,p}(\Omega)$ such that, for every $v \in W^{1,p}(\Omega)$, one has $\psi(\cdot, u(\cdot))v(\cdot) \in L^1(\Omega)$ and

$$K \left(\int_{\Omega} |\nabla u(x)|^p dx \right) \int_{\Omega} |\nabla u(x)|^{p-2} \nabla u(x) \nabla v(x) dx - \int_{\Omega} \psi(x, u(x))v(x) dx = 0 .$$

Theorem 2.15. *Let $f, g : \mathbf{R} \rightarrow \mathbf{R}$ be two C^1 functions lying in \mathcal{E} and satisfying the following conditions:*

- (a₁) *the function g' has a constant sign and $\operatorname{int}((g')^{-1}(0)) = \emptyset$;*
- (a₂) *$\lim_{|\xi| \rightarrow +\infty} \frac{f(\xi)}{|g(\xi)|+1} = +\infty$;*
- (a₃) *there are $\xi_1, \xi_2, \xi_3 \in \mathbf{R}$, with $\xi_1 < \xi_2 < \xi_3$, such that*

$$\max\{f(\xi_1), f(\xi_3)\} < f(\xi_2) .$$

Then, for every $a > 0$, for every $\beta \in L^\infty(\Omega)$, with $\inf_{\Omega} \beta > 0$, for every convex set $T \subseteq L^\infty(\Omega)$ dense in $L^\infty(\Omega)$, for every C^1 , non-decreasing, bounded function $\chi : [0, +\infty[\rightarrow \mathbf{R}$, and for every λ satisfying

$$\lambda > \frac{2 \sup_{[0, +\infty[} |\chi|}{p(f(\xi_2) - \max\{f(\xi_1), f(\xi_3)\}) \int_{\Omega} \beta(x) dx}$$

there exists $\gamma \in T$ such that the problem

$$(P) \begin{cases} -(a + \chi' \left(\int_{\Omega} |\nabla u(x)|^p dx \right)) \operatorname{div}(|\nabla u|^{p-2} \nabla u) = \gamma(x)g'(u) - \lambda\beta(x)f'(u) & \text{in } \Omega \\ \frac{\partial u}{\partial \nu} = 0 & \text{on } \partial\Omega \end{cases}$$

has at least two weak solutions.

Proof. Fix a, β, T, χ and λ as in the conclusion. We are going to apply Theorem 2.12, defining h, k, σ by

$$h(x, \xi, \eta) = \frac{a}{p\lambda} |\eta|^p + \beta(x)f(\xi) ,$$

$$k(\eta) = |\eta|^p ,$$

$$\sigma(\xi) = -g(\xi)$$

for all $(x, \xi, \eta) \in \Omega \times \mathbf{R} \times \mathbf{R}^n$. It is immediate to realize that, by (a₁) – (a₃), the above h, k, σ satisfy the assumptions of Theorem 2.12. Then, applying Theorem

2.12 with $\omega = \frac{1}{p}\chi$, we get the existence of $\gamma \in T$ such that the functional

$$u \rightarrow \lambda \left(\frac{a}{p\lambda} \int_{\Omega} |\nabla u(x)|^p dx + \int_{\Omega} \beta(x)f(u(x))dx \right) - \int_{\Omega} \gamma(x)g(u(x))dx + \frac{1}{p}\chi \left(\int_{\Omega} |\nabla u(x)|^p dx \right)$$

has at least two global minima in $W^{1,p}(\Omega)$. But, by classical results (recall that $f, g \in \mathcal{E}$), such a functional is C^1 and its critical points (and so, in particular, its global minima) are weak solutions of problem (P). The proof is complete. \square

A challenging problem is as follows:

PROBLEM 1. - Does the conclusion of Theorem 2.15 hold with *three* instead of *two*?

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